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Ray-Tracing

projective
rendering

for each Δ
project onto
screen

for each pixel in Δ
render



Ray tracing

for each pixel

| build ray

| for each Δ

| intersect ray with Δ

| find closest intersection

| render

Figure 1: Reflection test: (left) with environment map. (right) with environment map and ray-traced interreflections.

[**Pixar: Ray Tracing for the Movie ‘Cars’**

<http://graphics.pixar.com/library/RayTracingCars/paper.pdf>]

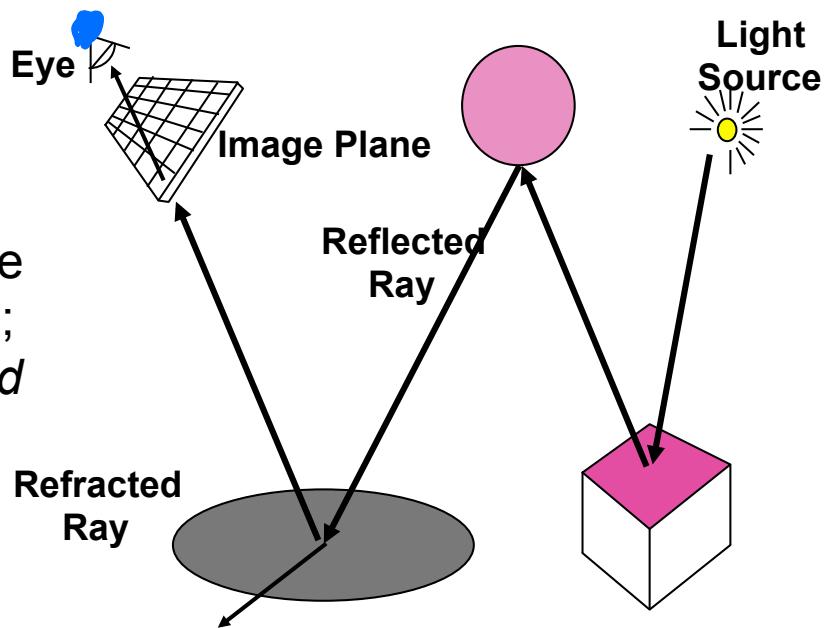


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Ray-tracing Overview

- handles multiple inter-reflections of light
- partly physics-based: geometric optics
- well suited to transparent and reflective objects

Trace light path from the eye backwards(!) into the scene;
recursively apply to reflected and refracted rays.





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Ray-Tracing

raytrace(ray) {
 find closest intersection: P
 colour_local = (0,0,0);
 if visible(P,L) // cast shadow ray
 colour_local = Phong(N,L,rayDir)
 colour_reflect = raytrace(reflected_ray) // if reflective
 colour_refract = raytrace(refracted_ray) // if refractive
 colour = k1*colour_local +
 k2*colour_reflect +
 k3*colour_refract
 return(colour)
}

Handwritten annotations in blue ink:

- A curly arrow points from the text "intersect ray with all geometry" to the opening brace of the raytrace function.
- A large blue circle highlights the term "colour_local". A handwritten label "k Local" is written below it, with a curved arrow pointing to the term.
- A large blue circle highlights the term "colour_reflect". A handwritten label "k Reflect" is written below it, with a curved arrow pointing to the term.

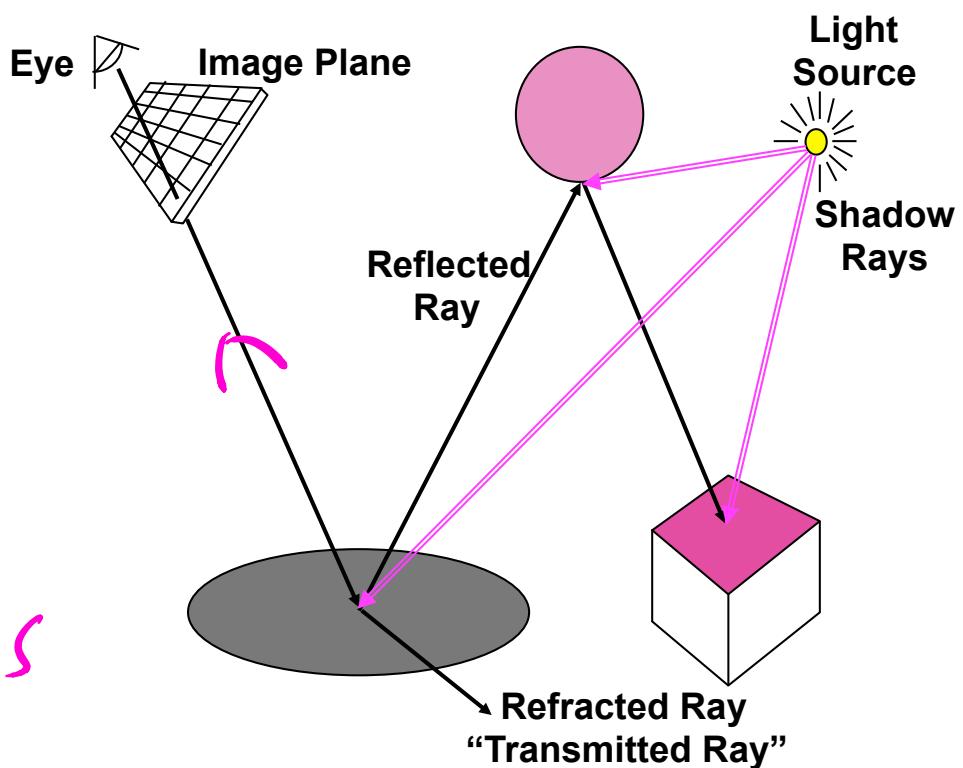
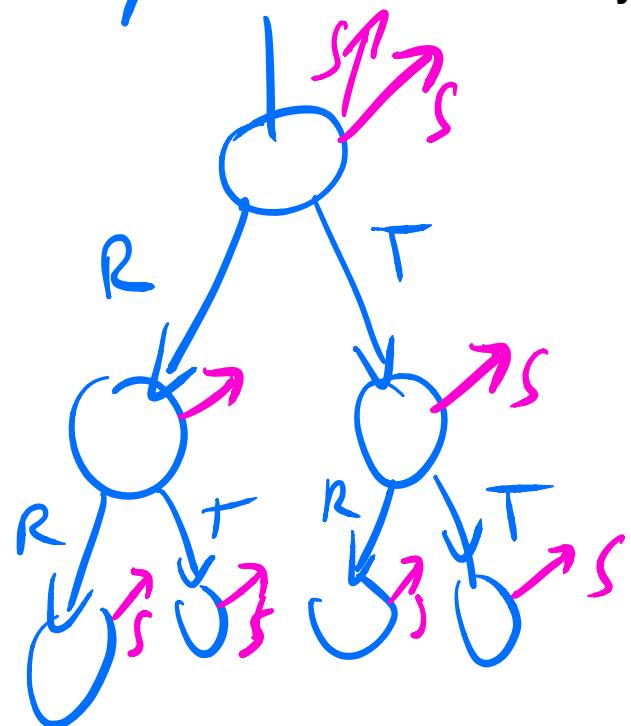
- “raycasting” : only cast first ray from eye

R = reflected ("refracted")
T = transmitted ("refracted")



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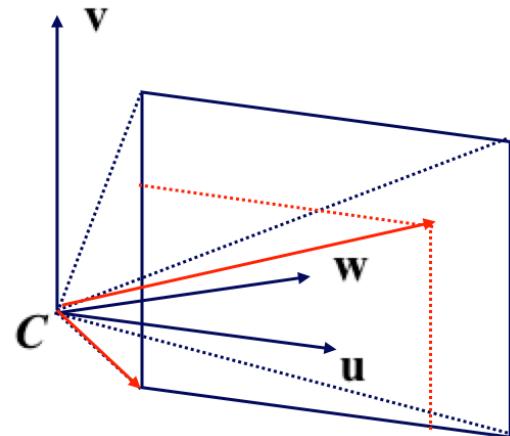
Ray Tree





Ray Generation & Termination

- distance to image plane: d
- image resolution (in pixels): N_x, N_y
- image plane dimensions:
- pixel i, j $left, right, top, bot$



$$P_{0,0} = C + d \vec{w} + left \vec{u} + bot \vec{v}$$

$$P_{i,j} = P_{0,0} + i \Delta u \vec{u} + j \Delta v \vec{v}$$

where

$$\Delta u = (right - left) / N_x$$

$$\Delta v = (top - bot) / N_y$$

Ray Termination

- ray hits a diffuse object
- ray exits the scene
- when exceeding max recursion depth
- when final contribution will be too small



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Ray-Sphere & Ray-Triangle Intersections

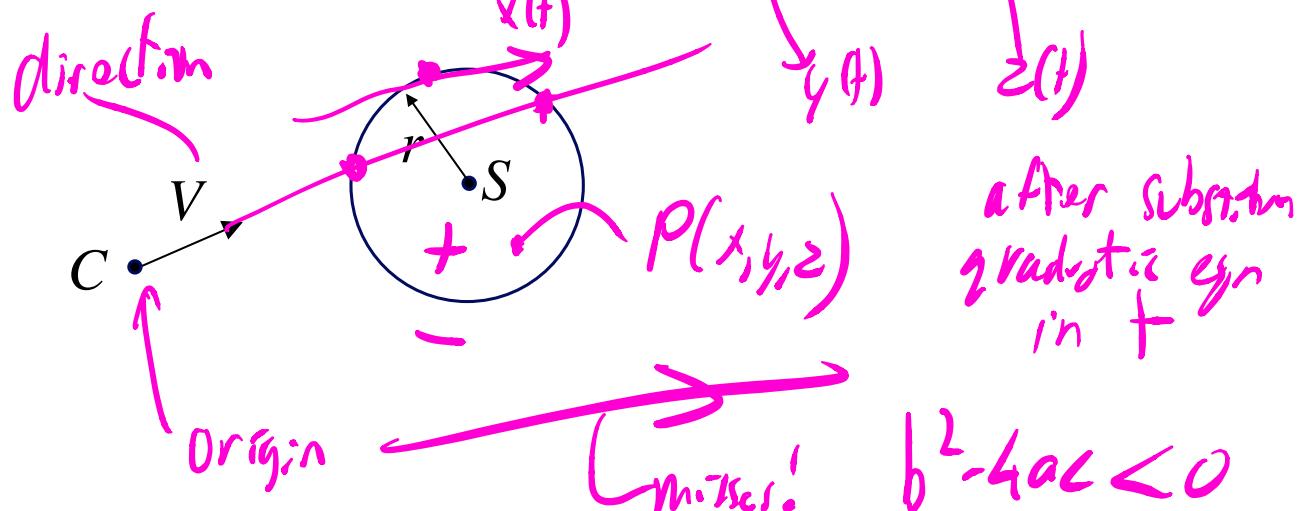
Ray

$$\mathbf{R}_{i,j}(t) = \mathbf{C} + t \cdot (\mathbf{P}_{i,j} - \mathbf{C}) \\ = \overrightarrow{\mathbf{C}} + t \cdot \overrightarrow{\mathbf{v}}_{i,j}$$

pixel(i,j)

$$x(t) = C_x + V_x t \\ y(t) = C_y + V_y t \\ z(t) = C_z + V_z t$$

Sphere $F(x, y, z) = r^2 - (x - S_x)^2 - (y - S_y)^2 - (z - S_z)^2 = 0$

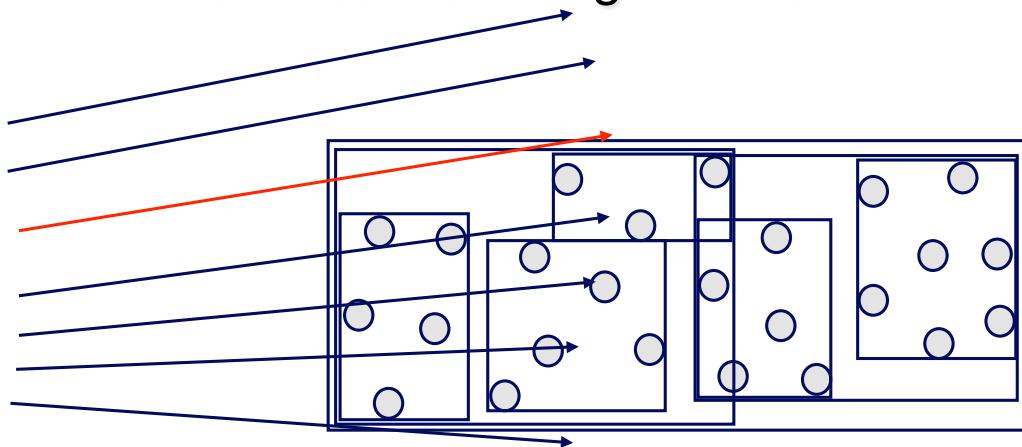




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Ray-Tracing: Optimizations

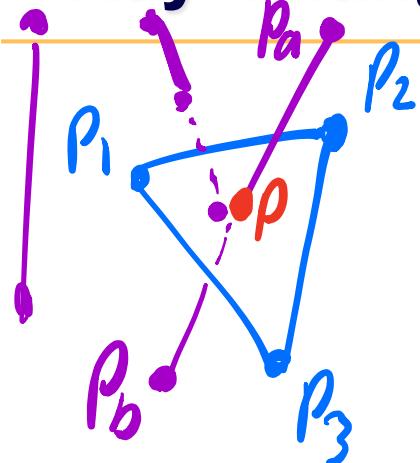
- process rays in parallel (multi-core, GPU, ⋯)
- efficient ray-object culling
 - hierarchical bounding volumes





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Ray-Triangle Intersections



$$\begin{aligned}P(\alpha, \beta) &= \alpha P_1 + \beta P_2 + (1-\alpha-\beta) P_3 \\&= P_3 + \alpha(P_1-P_3) + \beta(P_2-P_3) \\P(t) &= P_a + t(P_b-P_a)\end{aligned}$$

At intersection
 $P(\alpha, \beta) = P(t)$

$$\begin{aligned}P_1 - P_3 &\quad P_3 + \alpha(P_1 - P_3) + \beta(P_2 - P_3) = P_a + t(P_b - P_a) \\P_2 - P_3 &\quad \alpha(P_1 - P_3) + \beta(P_2 - P_3) + (P_b - P_a) = P_a - P_3 \\[0][0] &\quad [0] \quad [0] = [0] \\P_a - P_b &\quad P_a - P_3\end{aligned}$$

then test : $\begin{aligned}0 &\leq \alpha \leq 1 \\0 &\leq \beta \leq 1 \\0 &\leq 1-\alpha-\beta \leq 1 \\0 &\leq t \leq 1\end{aligned}$