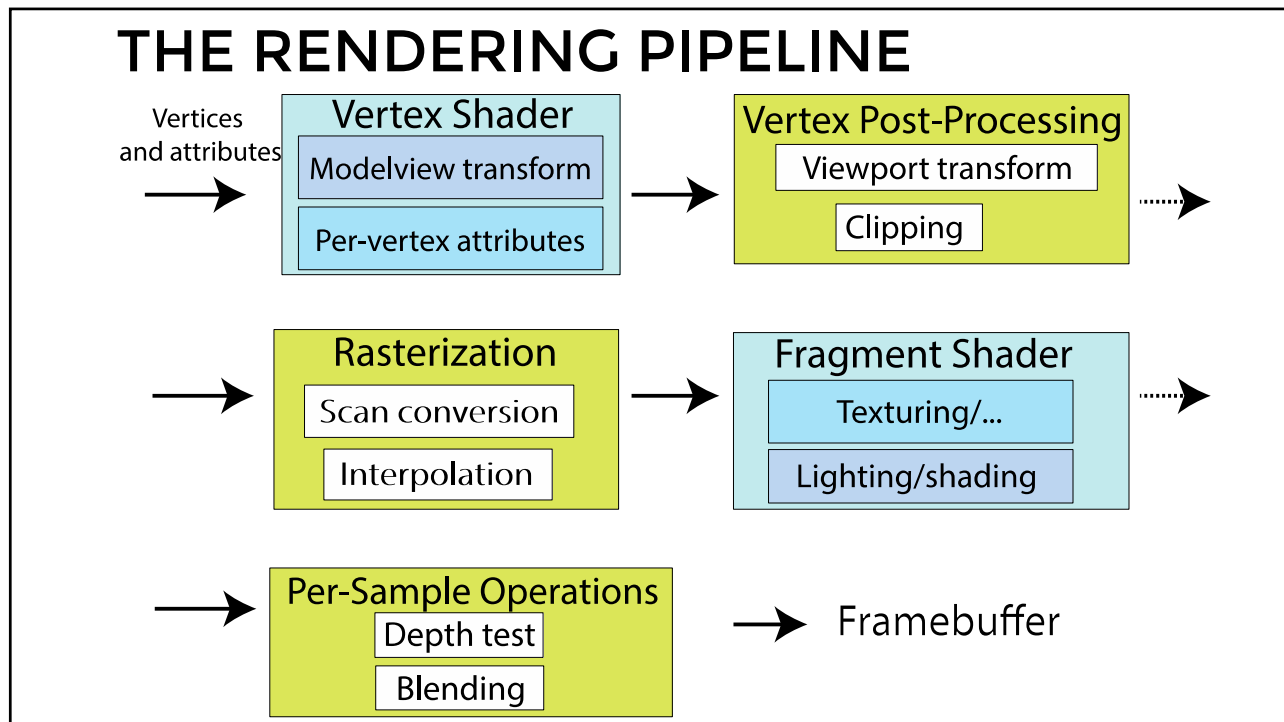


33 – BIG REVIEW

- This review is NOT everything you need to know
- This is just a list of questions you might want to answer in order to start preparation
- Now is a good time to start preparing!

RENDERING

- What is rendering?
- What is the input for the rendering process? Output?
- What are the stages of rendering?
 - Describe each one
- How do we make rendering real-time?
- How do we make rendering realistic?



HOMOGENEOUS COORDINATES

- Why do we use homogeneous coordinates?
- How to convert them from/to Euclidean coordinates?
 - Is such conversion 1-1?
- Where in the pipeline do we operate with HC/EC?
- How to tell a vector from a point in HC?

TRANSFORMATION MATRICES

- What's an affine transformation? Linear?
- Can all of them be represented as matrix operations?
- What's a structure of a transformation matrix?

AUGMENTED MATRIX

Linear Transformation

$$\begin{bmatrix} m_{11} & m_{12} & m_{13} & b_x \\ m_{21} & m_{22} & m_{23} & b_y \\ m_{31} & m_{32} & m_{33} & b_z \\ 0 & 0 & 0 & w \end{bmatrix}$$

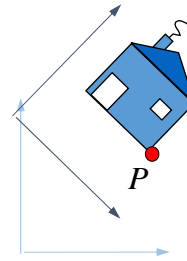
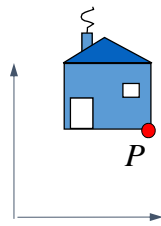
Translation



TRANSFORMING COORDINATE FRAME

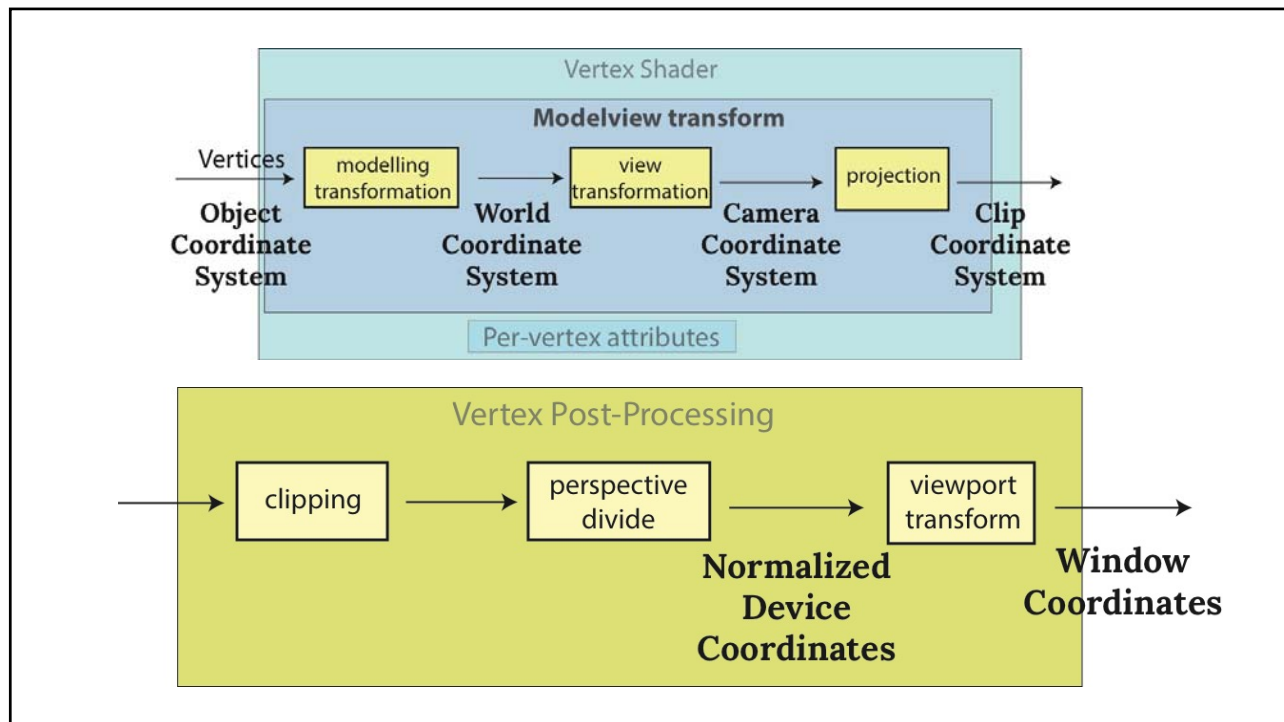
Columns are new basis vectors (and new origin)!

$$\begin{pmatrix} \cos \theta & -\sin \theta & p_x \cdot (1 - \cos \theta) + p_y \cdot \sin \theta \\ \sin \theta & \cos \theta & p_y \cdot (1 - \cos \theta) + p_x \cdot \sin \theta \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} v_x \\ v_y \\ 1 \end{pmatrix}$$



PIPELINE

- What are the transformations involved in the pipeline?
- What are the coordinate systems involved?
- Why do we do perspective divide?
- Why do we do clipping before perspective divide?
- Why do we need viewport transform?



MATH

- What are implicit, explicit, and parametric ways to define geometry?
 - What are their limitations?
- How to intersect two objects if they are
 - Both implicitly defined
 - Both explicitly defined
- How many parameters do we need to represent objects parametrically?

MATH

- How to calculate a normal to an implicit surface/curve?
- How to calculate a tangent plane?
- How to approximate surface area of some 2D shape?
- How to intersect a ray with a planar polygon in 2D? In 3D?

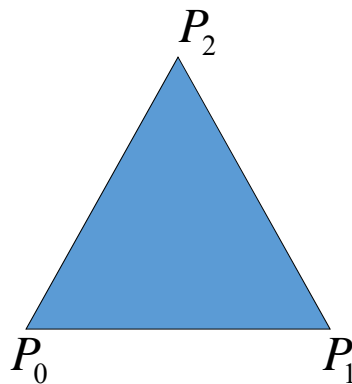
TRIANGLE

- Normal

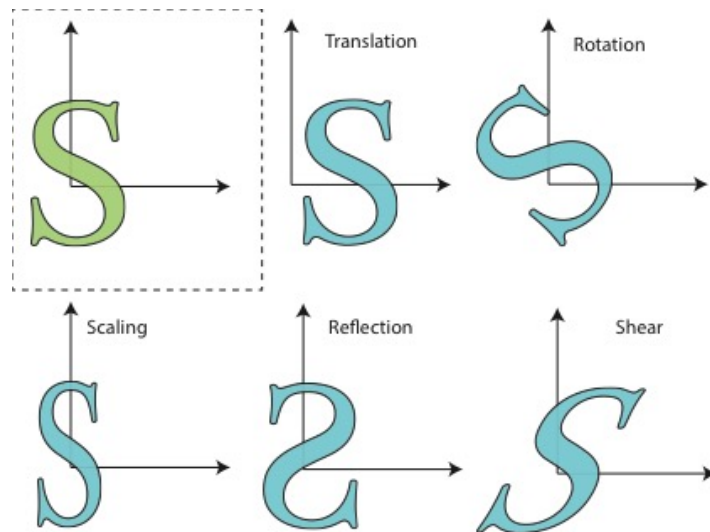
$$n = \frac{(P_1 - P_0) \times (P_2 - P_0)}{\|(P_1 - P_0) \times (P_2 - P_0)\|}$$

- Area

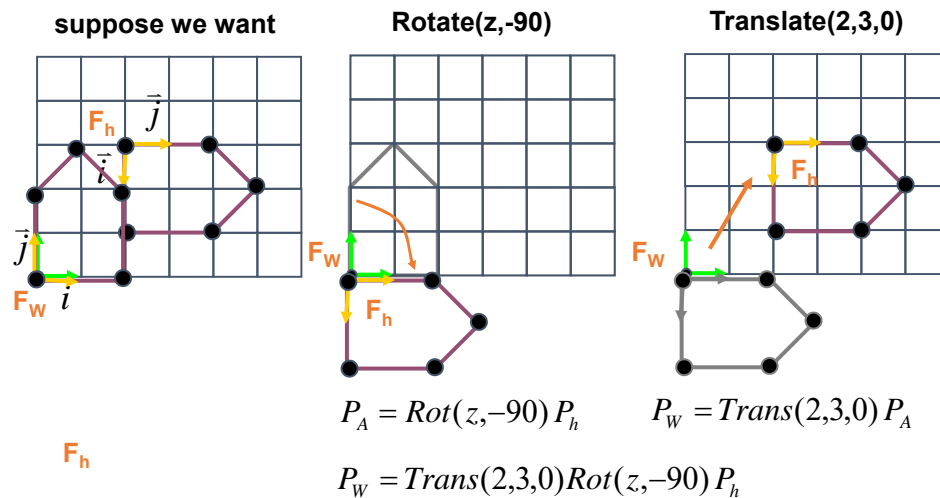
$$A = \frac{1}{2} \left\| \overrightarrow{P_0P_1} \times \overrightarrow{P_0P_2} \right\|$$



AFFINE TRANSFORMATIONS



COMPOSING TRANSFORMATIONS



COMPOSING TRANSFORMATIONS

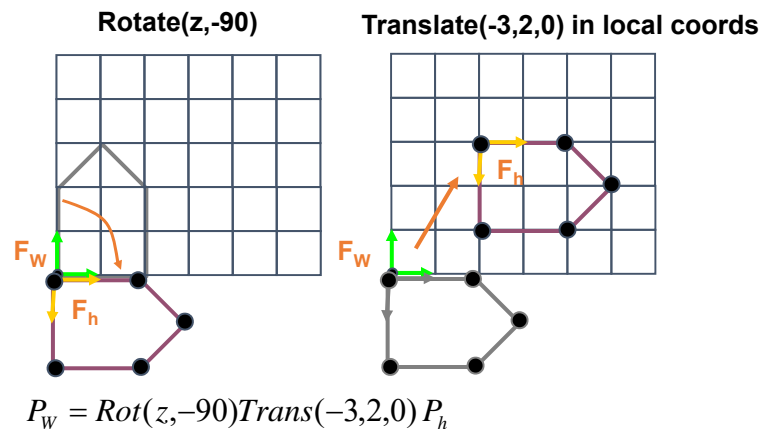
$$P_w = \text{Trans}(2,3,0)\text{Rot}(z,-90)P_h$$

- R-to-L: interpret operations wrt fixed coords
 - [moving object](#)
- L-to-R: interpret operations wrt local coords
 - [changing coordinate system](#)

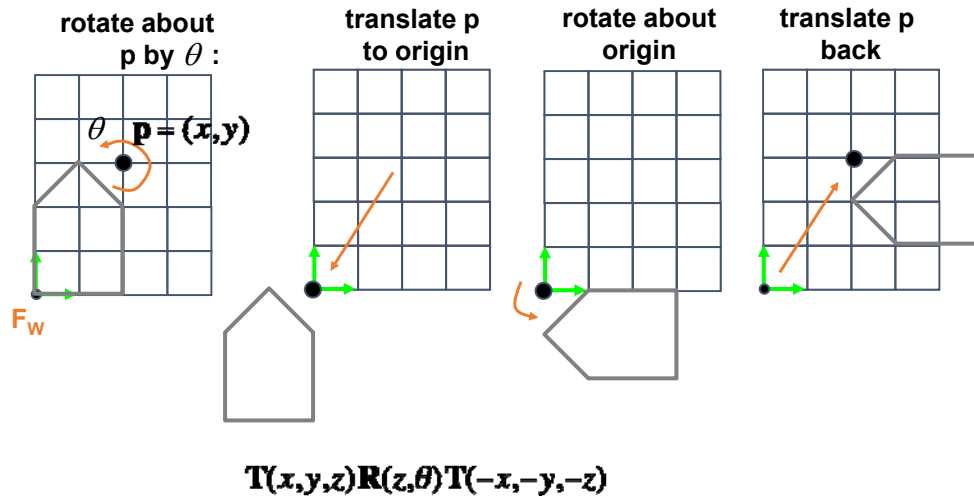
$$M_{MV} = \text{Trans}(2,3,0) \cdot M_{MV}$$

$$M_{MV} = \text{Rot}(z,-90)M_{MV}$$

COMPOSING TRANSFORMATIONS



ROTATION ABOUT A POINT: MOVING OBJECT



SIMPLE COMPOSITIONS

$$Tr(x_1, y_1, z_1) \cdot Tr(x_2, y_2, z_2) = Tr(x_1 + x_2, y_1 + y_2, z_1 + z_2)$$

$$Tr(x_2, y_2, z_2) \cdot Tr(x_1, y_1, z_1) = Tr(x_2, y_2, z_2) \cdot Tr(x_1, y_1, z_1)$$

$$Scale(a, b, c) \cdot Scale(d, e, f) = Scale(ad, be, cf)$$

$$Scale(a, b, c) \cdot Scale(d, e, f) = Scale(d, e, f) \cdot Scale(a, b, c)$$

$$Rot(\alpha, 0, 0, 1) \cdot Rot(\beta, 0, 0, 1) = Rot(\alpha + \beta, 0, 0, 1)$$

$$Rot(\alpha, 0, 0, 1) \cdot Rot(\beta, 0, 0, 1) = Rot(\beta, 0, 0, 1) \cdot Rot(\alpha, 0, 0, 1)$$

MORE COMPLICATED COMPOSITIONS

$$Tr(x, y, z) \cdot Scale(a, b, c) \neq Scale(a, b, c) \cdot Tr(x, y, z)$$

$$Tr(x, y, z) \cdot Scale(a, b, c) = Scale(a, b, c) \cdot Tr\left(\frac{x}{a}, \frac{y}{b}, \frac{z}{c}\right)$$

$$Tr(x, y, z) \cdot Rot(\alpha, 0, 0, 1) \neq Rot(\alpha, 0, 0, 1) \cdot Tr(x, y, z)$$

$$Rot(\alpha, 0, 0, 1) \cdot Rot(\beta, 0, 1, 0) \neq Rot(\beta, 0, 1, 0) \cdot Rot(\alpha, 0, 0, 1)$$

$$Scale(a, a, a) \cdot Rot(\beta, 0, 0, 1) = Rot(\beta, 0, 0, 1) \cdot Scale(a, a, a)$$

$$Scale(a, b, c) \cdot Rot(\beta, 0, 0, 1) \neq Rot(\beta, 0, 0, 1) \cdot Scale(a, b, c)$$

INVERSE TRANSFORMS

$$Tr(x, y, z)^{-1} = Tr(-x, -y, -z)$$

$$Rot(\alpha, 0, 0, 1)^{-1} = Rot(-\alpha, 0, 0, 1) = Rot(\alpha, 0, 0, 1)^T \text{ (orthogonal!)}$$

$$Scale(a, b, c)^{-1} = Scale\left(\frac{1}{a}, \frac{1}{b}, \frac{1}{c}\right)$$

ROTATION AFTER NON-UNIFORM SCALE

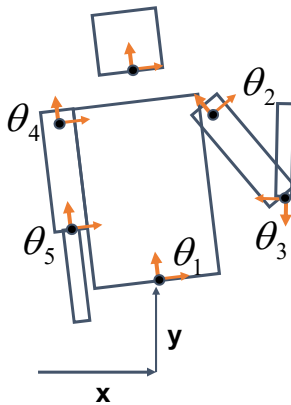
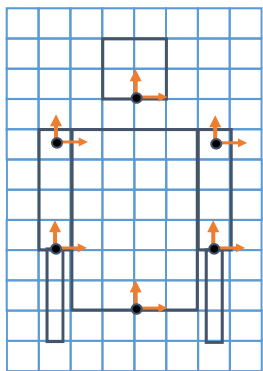
- Not what you'd expect!
- $M = \text{Scale}(a, b, c) \cdot \text{Rot}(\beta, 0, 0, 1) =$

$$\begin{pmatrix} a \cdot \cos(\beta) & -a \cdot \sin(\beta) & 0 & 0 \\ b \cdot \sin(\beta) & b \cdot \cos(\beta) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

- Basis vector not orthogonal

TRANSFORMATION HIERARCHIES

- Example



$$M_1 = \text{Tr}_{(x,y)} \cdot \text{Rot} \theta_1$$

$$M_2 = M_1 \cdot \text{Tr}_{(2.5,5.5)} \cdot \text{Rot} \theta_2$$

$$M_3 = M_2 \cdot \text{Tr}_{(0,-3.5)} \cdot \text{Rot} \theta_3$$

PROJECTIONS

- What is the purpose of projections?
- What's the difference between ortho- and perspective projections?
- Who chooses which projection to use?
- Can we get a nearly orthographic projection while using a perspective projection matrix?
- What happens to z in perspective projection?
- What happens to the view volumes?

CLIPPING

- What happens to points during clipping? Triangles?
- What are the equations of the frustum planes?
- How can we test if a triangle should be clipped?

RASTERIZATION

- What's rasterization?
- How do we rasterize a polygon?
- Why do we interpolate?
- What are the values we typically interpolate?
- How?
- How is it done in ray/path tracing?

LIGHTING & SHADING

- What's a Gouraud shading?
- What are Lambert/Phong materials?
- If the scene is lit with only ambient light, what will we see?
 - Only diffuse/specular?
- How can we control size of the specular highlight?
- How do we shade in ray tracing? in path tracing?
- In path tracing, how can we simulate more complex materials?

TEXTURING

- How can we tile a wall with bricks?
 - If a texture contains a single brick, what should be texture coordinates for wall's corners?
- Why do we use mipmaps?
- How much storage do we need for them?
- How do we generate mipmaps?
- Where do we get texture coordinates?
- How do we interpolate them?

BUMP AND NORMAL MAPPING

- Why?
- Which mapping would you use to add scales to a fish?
- Bullets on the walls?
- Fur on an animal?
- How do we apply bump mapping?

ENVIRONMENT MAPS

- Why do we need them?
- What are the types?
- How do we generate them?
- How do we apply them?
- When do we re-generate them?

SHADOW MAPS

- Why do we need them?
- How does it fit into pipeline?
- What's the algorithm?

ILLUMINATION MODELS/ALGORITHMS

Local illumination - Fast
 Ignore real physics, approximate the look
 Interaction of each object with light

- Compute on surface (light to viewer)



Global illumination - Slow
 Physically based
 Interactions between objects



BASIC RAY-TRACING ALGORITHM

```

RayTrace(r,scene)
obj = FirstIntersection(r,scene)

if (no obj) return BackgroundColor;
else {
  if (Reflect(obj))
    reflect_color = RayTrace(ReflectRay(r,obj));
  else
    reflect_color = Black;

  if (Transparent(obj))
    refract_color = RayTrace(RefractRay(r,obj));
  else
    refract_color = Black;

  return Shade(reflect_color, refract_color, obj);
}
  
```


WHEN TO STOP?

- Algorithm above does not terminate
- Termination Criteria
 - No intersection
 - Contribution of secondary ray attenuated below threshold – each reflection/refraction attenuates ray
 - Maximal depth is reached

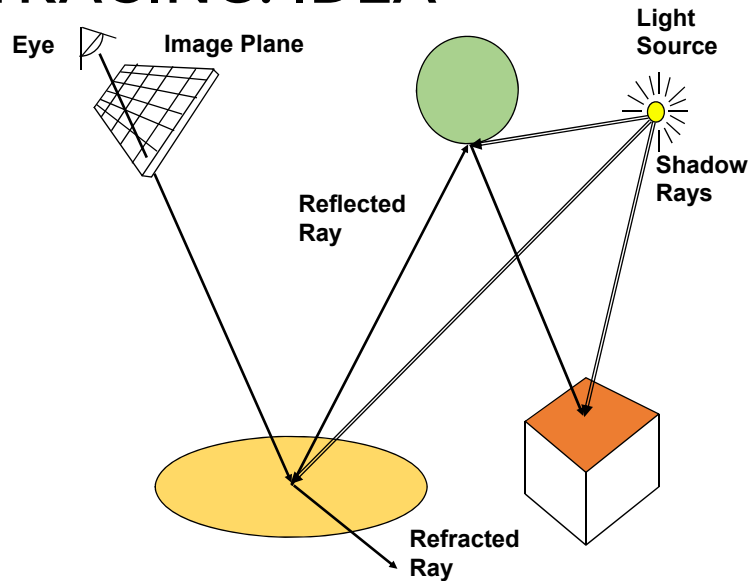
SIMULATING SHADOWS

- Trace ray from each ray-object intersection point to light sources
 - If the ray intersects an object in between \Rightarrow point is shadowed from the light source

```
shadow = RayTrace(LightRay(obj,r,light));
```

```
return Shade(shadow,reflect_color,refract_color,obj);
```

RAY TRACING: IDEA



RAY-OBJECT INTERSECTIONS

- Core of ray-tracing \Rightarrow must be extremely efficient
- Usually involves solving a set of equations
 - Using implicit formulas for primitives

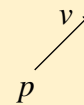
Example: Ray-Sphere intersection

ray: $x(t) = p_x + v_x t$, $y(t) = p_y + v_y t$, $z(t) = p_z + v_z t$

(unit) sphere: $x^2 + y^2 + z^2 = 1$

quadratic equation in t :

$$\begin{aligned}
 0 &= (p_x + v_x t)^2 + (p_y + v_y t)^2 + (p_z + v_z t)^2 - 1 \\
 &= t^2 (v_x^2 + v_y^2 + v_z^2) + 2t(p_x v_x + p_y v_y + p_z v_z) \\
 &\quad + (p_x^2 + p_y^2 + p_z^2) - 1
 \end{aligned}$$



RAY-TRACING: DIRECT ILLUMINATION

- Local surface information (normal...)

- For implicit surfaces $F(x,y,z)=0$:
normal $\mathbf{n}(x,y,z)$ is gradient of F:

$$\mathbf{n}(x, y, z) = \nabla F(x, y, z) = \begin{pmatrix} \partial F(x, y, z)/\partial x \\ \partial F(x, y, z)/\partial y \\ \partial F(x, y, z)/\partial z \end{pmatrix}$$

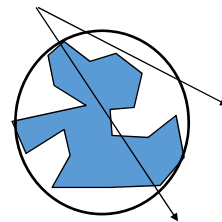
- Example:

$$F(x, y, z) = x^2 + y^2 + z^2 - r^2$$

$$\mathbf{n}(x, y, z) = \begin{pmatrix} 2x \\ 2y \\ 2z \end{pmatrix} \quad \text{Needs to be normalized!}$$

OPTIMIZED RAY-TRACING

- Basic algorithm is simple but VERY expensive
- Optimize...
 - Reduce number of rays traced
 - Reduce number of ray-object intersection calculations
- Parallelize
 - Cluster
 - GPU
- Methods
 - Bounding Boxes
 - Spatial Subdivision
 - Visibility, Intersection/Collision
 - Tree Pruning



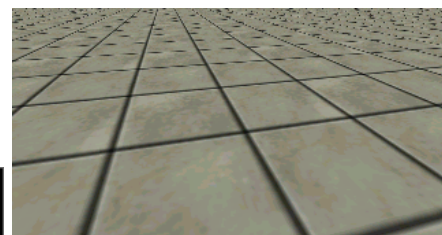
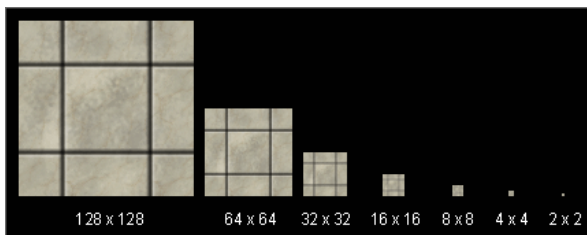
ALIASING & ANTI-ALIASING



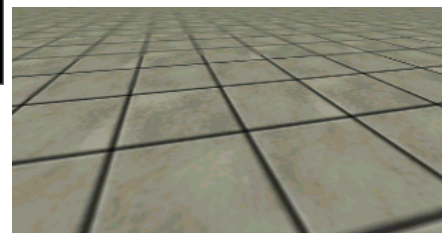
© Adobe, inc., <https://helpx.adobe.com/photoshop/key-concepts/aliasing-anti-aliasing.html>

MIPMAPPING

use “image pyramid” to precompute averaged versions of the texture



Without MIP-mapping



With MIP-mapping

THANK YOU AND GOOD BYE!

FIN