Transformations as a change of basis

$$
\begin{aligned}
& P_{1}=(3,-1) P_{2}=(-1.5,-) \text { goal: } P_{2}=M P_{1} \\
& P=O+x \vec{i}+y \vec{j} \\
& {\left[\begin{array}{l}
x_{1} \\
y_{1}
\end{array}\right]_{1}=\left[\begin{array}{l}
0 \\
0
\end{array}\right]_{1}+x_{1}\left[\begin{array}{l}
1 \\
0
\end{array}\right]_{1}+y_{1}\left[\begin{array}{l}
0 \\
1
\end{array}\right]_{1}} \\
& {\left[\begin{array}{l}
x_{2} \\
y_{2}
\end{array}\right]_{2}=\left[\begin{array}{l}
0 \\
0 \\
3
\end{array}\right]+x_{1}\left(\left[\begin{array}{c}
0.5 \\
0
\end{array}\right]_{2}+y_{1}\left[\begin{array}{l}
0 \\
0
\end{array}\right)\right]_{2}} \\
& {\left[\begin{array}{c}
\text { check: } \\
-(5.5 \\
2 \\
1
\end{array}\right]=\left[\begin{array}{ccc}
-0.5 & 0 & 0 \\
0 & 1 & 3 \\
0 & 0 & 1
\end{array}\right]\left[\begin{array}{c}
3 \\
-1 \\
1
\end{array}\right]\left[\begin{array}{c}
-x_{2} \\
y_{2} \\
1
\end{array}\right]=\left[\begin{array}{ccc}
-0.5 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
y_{1} \\
1
\end{array}\right]}
\end{aligned}
$$

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