

# Ray-Tracing





Figure 1: Reflection test: (left) with environment map. (right) with environment map and ray-traced interreflections.

[Pixar: Ray Tracing for the Movie 'Cars'

http://graphics.pixar.com/library/RayTracingCars/paper.pdf]

# Ray-tracing Overview



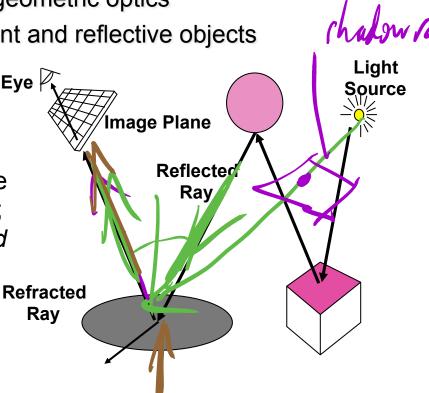
handles multiple inter-reflections of light

partly physics-based: geometric optics

well suited to transparent and reflective objects

Eye |

Trace light path from the eye backwards(!) into the scene; recursively apply to reflected and refracted rays.



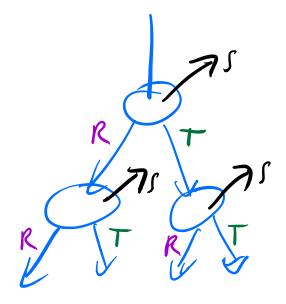


## Ray-Tracing

```
raytrace( ray ) {
  find closest intersection: P
  colour_local = (0,0,0);
  if visible(P,L)
                                 // cast shadow ray
      colour_local = Phong(N,L,rayDir)
  colour_reflect = raytrace(`reflected_ray ) // if reflective
  colour_refract = raytrace( refracted_ray ) // if refractive
  colour = k1*colour_local +
           k2*colour_reflect +
           k3*colour_refract
  return(colour)
```

"raycasting": only cast first ray from eye

# Ray Tree



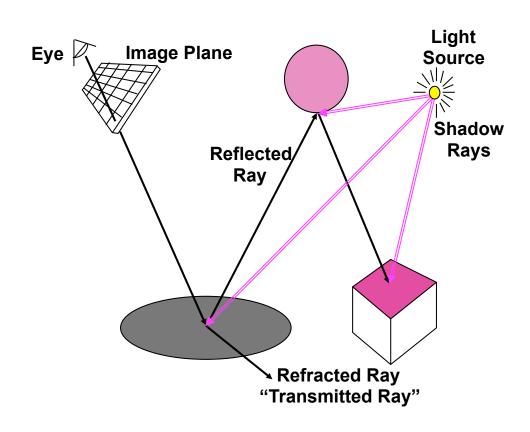
S = shadow ray

R = reflected ray

T = transmitted ray

Crefracted







# Ray termination

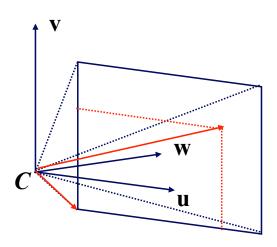
- ray hits a diffuse object
- ray exits the scene
- when exceeding max recursion depth
- when final contribution will be too small

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# **Generation of Rays**

- distance to image plane: d
- image resolution (in pixels):  $N_x, N_y$
- image plane dimensions: *left*, *right*, *top*, *bot*
- pixel *i*, *j*

$$\begin{split} P_{0,0} &= C + d\,\vec{w} + left\,\vec{u} + bot\,\vec{v} \\ P_{i,j} &= P_{0,0} + i\Delta u\,\vec{u} + j\Delta v\,\vec{v} \\ \text{where} \\ \Delta u &= (right - left) / N_x \\ \Delta v &= (top - bot) / N_v \end{split}$$





### **Ray-Sphere Intersections**

Ray 
$$R_{i,j}(t) = C + t \cdot (P_{i,j} - C)$$
  $x(t) = C_x + V_x t$ 

$$= C + t \cdot \mathbf{v}_{i,j}$$
  $y(t) = C_y + V_y t$ 

$$z(t) = C_z + V_z t$$
Sphere  $F(x, y, z) = r^2 - (x - S_x)^2 - (y - S_y)^2 - (z - S_z)^2$ 

$$\Rightarrow q \text{ vadratic eq vation in } t$$

$$two \text{ solutions}$$

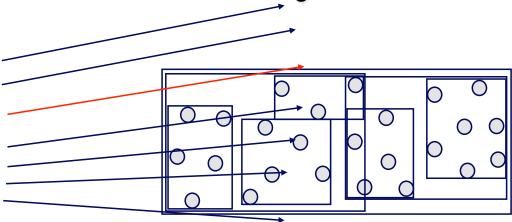
$$- vne \text{ solutions}$$

$$2 \text{ evo solutions}$$



## **Ray-Tracing: Optimizations**

- process rays in parallel (multi-core, GPU, ···)
- efficient ray-object culling
  - hierarchical bounding volumes





### **Ray-Triangle Intersections**

(covered as Q4 of 14)