



Chapter 8

Scan Conversion (part 2)– Drawing Polygons on Raster Display



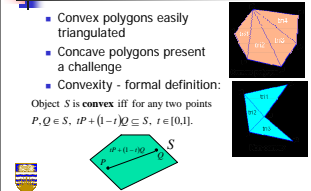

Rasterizing Polygons/Triangles

- Basic surface representation in rendering
- Why?
 - Lowest common denominator
 - Can approximate any surface with arbitrary accuracy
 - All polygons can be broken up into triangles
 - Guaranteed to be:
 - Planar
 - Triangles - Convex
- Simple to render
 - Can implement in hardware



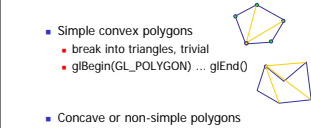

Triangulation

- Convex polygons easily triangulated
- Concave polygons present a challenge
- Convexity - formal definition:
 - Object S is convex iff for any two points $P, Q \in S$, $tP + (1-t)Q \subseteq S, t \in [0,1]$.



OpenGL Triangulation

- Simple convex polygons
 - break into triangles, trivial
 - `glBegin(GL_POLYGON) ... glEnd()`
- Concave or non-simple polygons
 - break into triangles, more effort
 - `gluNewTess()`, `gluTessCallback()`, ...

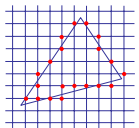

Polygon Rasterization

- Assumptions – well behaved
 - simple - no self intersections
 - simply connected (no holes)
- Solutions
 - Flood fill
 - Scan line
 - Implicit test

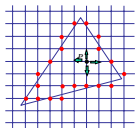

Formulation

- Input
 - polygon P with rasterized edges
- Problem: Fill its interior with specified color on graphics display

Flood Fill Algorithm


- Input
 - polygon P with rasterized edges
 - $P = (x,y) \in P$ point inside P

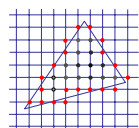
Flood Fill

```


FloodFill (Polygon P, int x, int y, Color C)
if not (OnBoundary (x,y,P) or Colored (x,y,C))
begin
  PlotPixel (x,y,C);
  FloodFill (P,x+1,y,C);
  FloodFill (P,x,y+1,C);
  FloodFill (P,x,y-1,C);
  FloodFill (P,x-1,y,C);
end ;
  
```



Flood Fill




- Drawbacks?



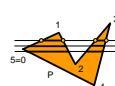

Flood Fill - Drawbacks

- How do we find a point inside?
- Pixels visited up to 4 times to check if already set
- Need per-pixel flag indicating if set already
 - clear for every polygon!



Scanline Algorithm

- Observation: Each intersection of straight line with boundary moves it from/into polygon
- Detect (& set) pixels inside polygon boundary (simple closed curve) with set of horizontal lines (pixel apart)





Scanline

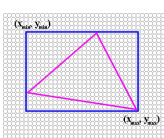

```

ScanConvert (Polygon P, Color C)
For y:= 0 to ScreenYMax do
  I ← Points of intersections of edges of P with line Y = y;
  Sort I in increasing X order and
  Fill with color C alternating segments;
end;
  
```

- Limit to bounding box to speed up
- Other enhancements...



Bounding Box

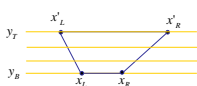




Edge Walking

- Scanline is more efficient for specific polygons – trapezoids (triangles)

```

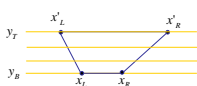

scanTrapezoid(xL, xR, yB, yT, x'L, x'R)
  
```

Edge Walking

```

for (y=yB; y<=yT; y++) {
  x1 = intersect (Y=y, (xL,x'L));
  x2 = intersect (Y=y, (xR,x'R));
  for (x=x1; x<=x2; x++)
    setPixel (x,y);
}
  
```

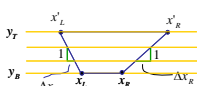




Edge Walking

- Exploit continuous L and R edges

```

scanTrapezoid(xL, xR, yB, yT, ΔxL, ΔxR)
  
```

Edge Walking

```

for (y=yB; y<=yT; y++) {
  for (x=xL; x<=xR; x++)
    setPixel(x,y);
  xL += DxL;
  xR += DxR;
}
    
```

Edge Walking Triangles

- Split triangles into two regions with continuous left and right edges

```

scanTrapezoid(x1,x2,y1,y2,1/m12,1/m23)
scanTrapezoid(x1,x2,y2,y3,1/m12,1/m23)
    
```

Edge Walking Triangles

- Issues
 - Many small triangles
 - setup cost is non-trivial
 - Clipping triangles produces non-triangles

Modern Rasterization

- Define a triangle from implicit edge equations:

Computing Edge Equations

- Computing A,B,C from (x1, y1), (x2, y2)

$$Ax_1 + By_1 + C = 0$$

$$Ax_2 + By_2 + C = 0$$

- Two equations, three unknowns
- Express A, B in terms of C

Computing Edge Equations

$$\begin{bmatrix} x_1 & y_1 \\ x_2 & y_2 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = -C \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$A = \frac{-C - By_1}{x_1}$$

$$B(x_2 - x_1) = C(x_1 - x_2)$$

(special case if x1 = 0)

- Choose C = x2y1 - x1y2 for convenience
- Then A = y2 - y1 and B = x1 - x2
- Our original implicit formula
- Note - in literature you can find same equation multiplied by -1
- Changes sides

Edge Equations

- Given P0, P1, P2, what are our three edges?
 - Half-spaces defined by the edge equations must share the same sign on the interior of the triangle
 - Consistency (Ex: [P0,P1], [P1,P2], [P2,P0])
 - How do we make sure that sign is positive?
 - Test & flip if needed (A = -A, B = -B, C = -C)

Edge Equations: Code

- Basic structure of code:
 - Setup: compute edge equations, bounding box
 - (Outer loop) For each scanline in bounding box...
 - (Inner loop) ...check each pixel on scanline:
 - evaluate edge equations
 - draw pixel if all three are positive

Edge Equations: Code

```

findBoundingBox(xmin, xmax, ymin, ymax);
setupEdges (a0,a1,b0,b1,c0,c1,a2,a3,b2,b3,c2,c3);
for (int y = ymin; y <= ymax; y++) {
  for (int x = xmin; x <= xmax; x++) {
    float a0 = a0*x + b0*y + c0;
    float a1 = a1*x + b1*y + c1;
    float a2 = a2*x + b2*y + c2;
    if (a0 > 0 && a1 > 0 && a2 > 0)
      Image[x][y] = TriangleColor;
  }
}
    
```

Edge Equations: Code

```

// more efficient inner loop
for (int y = ymin; y <= ymax; y++) {
  float a0 = a0*min + b0*y + c0;
  float a1 = a1*min + b1*y + c1;
  float a2 = a2*min + b2*y + c2;
  for (int x = min; x <= max; x++) {
    if (a0 > 0 && a1 > 0 && a2 > 0)
      Image[x][y] = TriangleColor;
    a0 += a0; a1 += a1; a2 += a2;
  }
}
    
```

Triangle Rasterization Issues

- Exactly which pixels should be lit?
 - Pixels inside triangle edges
 - What about pixels exactly on the edge?
 - Draw - BUT order of triangles matters (it shouldn't)
 - Don't draw - BUT gaps possible between triangles
- Need consistent (if arbitrary) rule
- Example: draw pixels on left or top edge, but not on right or bottom edge

Triangle Rasterization Issues

- Sliver

Triangle Rasterization Issues

- Moving Slivers

Triangle Rasterization Issues

- Shared Edge Ordering

Interpolation - access triangle interior

- Interpolate between vertices:
 - z
 - r,g,b - colour components
 - u,v - texture coordinates
 - N1, N2, N3 - surface normals
- Equivalent
 - Bilinear interpolation
 - Barycentric coordinates

Barycentric Coordinates

- Area

$$A = \frac{1}{2} \left\| \overrightarrow{P_1P_2} \times \overrightarrow{P_1P_3} \right\|$$
- Barycentric coordinates
 - a1 = AP2P3 / A, a2 = AP3P1 / A, a3 = AP1P2 / A
 - a1 + a2 + a3 = 1
 - P = a1P1 + a2P2 + a3P3

Barycentric Coordinates

- weighted combination of vertices

$$P = a_1 \cdot P_1 + a_2 \cdot P_2 + a_3 \cdot P_3$$

$$a_1 + a_2 + a_3 = 1$$

$$0 \leq a_1, a_2, a_3 \leq 1$$

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Barycentric Coords: Alternative formula

- For point P on scanline:

$$P_x = P_2 + \frac{d_1}{d_1 + d_2} (P_1 - P_2)$$

$$= (1 - \frac{d_1}{d_1 + d_2}) P_2 + \frac{d_1}{d_1 + d_2} P_1 = \frac{d_2}{d_1 + d_2} P_2 + \frac{d_1}{d_1 + d_2} P_1$$

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Computing Barycentric Coords

- similarly:

$$P_y = P_2 + \frac{b_1}{b_1 + b_2} (P_1 - P_2)$$

$$= (1 - \frac{b_1}{b_1 + b_2}) P_2 + \frac{b_1}{b_1 + b_2} P_1 = \frac{b_2}{b_1 + b_2} P_2 + \frac{b_1}{b_1 + b_2} P_1$$

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Computing Barycentric Coords

- combining

$$P = \frac{c_2}{c_1 + c_2} P_2 + \frac{c_1}{c_1 + c_2} P_1$$

$$P_x = \frac{d_1}{d_1 + d_2} P_2 + \frac{d_2}{d_1 + d_2} P_1$$

$$P_y = \frac{b_1}{b_1 + b_2} P_2 + \frac{b_2}{b_1 + b_2} P_1$$
- gives

$$P = \frac{c_2}{c_1 + c_2} \left(\frac{d_2}{d_1 + d_2} P_2 + \frac{d_1}{d_1 + d_2} P_1 \right) + \frac{c_1}{c_1 + c_2} \left(\frac{b_2}{b_1 + b_2} P_2 + \frac{b_1}{b_1 + b_2} P_1 \right)$$

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Computing Barycentric Coords

- thus

$$P = a_1 \cdot P_1 + a_2 \cdot P_2 + a_3 \cdot P_3$$
- with

$$a_1 = \frac{c_1}{c_1 + c_2} \frac{b_2}{b_1 + b_2}$$

$$a_2 = \frac{c_2}{c_1 + c_2} \frac{d_2}{d_1 + d_2} + \frac{c_1}{c_1 + c_2} \frac{b_1}{b_1 + b_2}$$

$$a_3 = \frac{c_2}{c_1 + c_2} \frac{d_1}{d_1 + d_2}$$

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Computing Barycentric Coords

- Can verify barycentric properties

$$a_1 + a_2 + a_3 = 1$$

$$0 \leq a_1, a_2, a_3 \leq 1$$

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Bilinear Interpolation

- Interpolate quantity along L and R edges, as a function of y
 - then interpolate quantity as a function of x

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