

Chapter 7

Clipping

Clipping - 1

Explicit Solution: Line Segments

- Intersection of convex regions is convex
 - Why?
- L & D are convex - intersection is convex
 - single connected segment of L
- Clipping uses intersections of L with four boundary segments of window D

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Rendering Pipeline

Discard geometry outside viewport window

Basic Method

```

Clip( $P_0, P_1, x_{min}, x_{max}, y_{min}, y_{max}$ )
if ( $(P_0$  and  $P_1$  inside window) then draw ( $P_0, P_1$ );
test if segment ( $P_0, P_1$ ) intersects any of the edges
if not, return;
else let  $P_2$  be the first intersection found
  Clip( $P_0, P_2, x_{min}, x_{max}, y_{min}, y_{max}$ );
  Clip( $P_2, P_1, x_{min}, x_{max}, y_{min}, y_{max}$ );
end
    
```

- Works, but inefficient for lines OUTSIDE D
 - Four intersection tests
- Note: need special care for vertices ON window edges

Line/Polygon Clipping (2D)

Problem:
Given a 2D line/polygon and a window, clip the line/polygon to their regions that are inside the window.

- Objectives
 - Efficiency
 - (Parallelization)
- Two approaches
 - Explicit (continuous setting)
 - Implicit (discrete setting) – part of scan conversion

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Segment-Segment Intersection

$$G_1 = \begin{cases} x^1(t) = x_0 + (x_1 - x_0)t \\ y^1(t) = y_0 + (y_1 - y_0)t \end{cases} \quad t \in [0,1] \quad G_2 = \begin{cases} x^2(r) = x_2 + (x_3 - x_2)r \\ y^2(r) = y_2 + (y_3 - y_2)r \end{cases} \quad r \in [0,1]$$

Intersection: x & y values equal in both representations - two linear equations in two unknowns (r, t)
test if resulting r & t are inside the $[0,1]$ range

$$\begin{aligned} x_0 + (x_1 - x_0)t &= x_2 + (x_3 - x_2)r \\ y_0 + (y_1 - y_0)t &= y_2 + (y_3 - y_2)r \end{aligned}$$

Intersection with axis-aligned lines

$$G_1 = \begin{cases} x^1(t) = x_0^1 + (x_1^1 - x_0^1)t \\ y^1(t) = y_0^1 + (y_1^1 - y_0^1)t \end{cases} t \in [0,1], G_2 = \begin{cases} x^2(r) = x_0^2 \\ y^2(r) = y_0^2 + (y_1^2 - y_0^2)r \end{cases} r \in [0,1]$$

Intersection: x & y values equal in both representations - two linear equations in two unknowns (r, t)

$$x_0^1 + (x_1^1 - x_0^1)t = x_0^2$$

$$t = \frac{x_0^2 - x_0^1}{x_1^1 - x_0^1}, \text{ if } t < 0 \text{ or } t > 1 \text{ no intersection}$$

$$y_0^1 + (y_1^1 - y_0^1)t = y_0^2 + (y_1^2 - y_0^2)r, \text{ (relevant only for segments)}$$

Line Clipping

Line Clipping

Cohen-Sutherland Algorithm (cont'd)

Given L from (x_0, y_0) to (x_1, y_1) & rectangle D .

If bitwise **and** of the codes of (x_0, y_0) and (x_1, y_1) is not zero, or the bitwise **or** is zero, then L can be trivially handled (it is either totally outside or totally inside D).

Why?

Cohen-Sutherland Algorithm

Purpose:
Fast treatment of line segments that are trivially inside/outside window.

$P = (x, y)$ - point to be classified against window D

Idea: Assign to P a binary code consisting of a bit for each edge of D , using lookup table:

bit	1	0
1	$y < y_{min}$	$y \geq y_{min}$
2	$y > y_{max}$	$y \leq y_{max}$
3	$x > x_{max}$	$x \leq x_{max}$
4	$x < x_{min}$	$x \geq x_{min}$

Cohen-Sutherland Algorithm (cont'd)

C-S-Clip ($P_0 = (x_0, y_0), P_1 = (x_1, y_1), x_{min}, x_{max}, y_{min}, y_{max}$) (assumes $x_0 < x_1$)

$C_0 \Leftarrow \text{code}(P_0); C_1 \Leftarrow \text{code}(P_1);$
 if $((C_0 \text{ and } C_1) \neq 0)$ then return;
 if $((C_0 \text{ or } C_1) = 0)$ then draw(P_0, P_1);
 else if (OutsideWindow(P_0)) then begin
 Edge \Leftarrow Window boundary of leftmost non-zero bit of C_0 ;
 $P_2 \Leftarrow \overline{P_0}, P_1 \cap \text{Edge};$
 C-S-Clip($P_2, P_1, x_{min}, x_{max}, y_{min}, y_{max}$);
 end
 else
 Edge \Leftarrow Window boundary of leftmost non-zero bit of C_1 ;
 $P_2 \Leftarrow \overline{P_1}, P_0 \cap \text{Edge};$
 C-S-Clip($P_0, P_2, x_{min}, x_{max}, y_{min}, y_{max}$);
 end

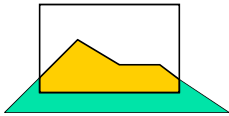
bit	1	0
1	$y < y_{min}$	$y \geq y_{min}$
2	$y > y_{max}$	$y \leq y_{max}$
3	$x > x_{max}$	$x \leq x_{max}$
4	$x < x_{min}$	$x \geq x_{min}$

3D clipping

- Determine portion of line inside axis-aligned parallelepiped (viewing frustum in NDC)
- Simple extension to 2D algorithms
- After perspective transform
 - means that clipping volume always the same
 - xmin=ymin= -1, xmax=ymax= 1 in OpenGL
 - boundary lines become boundary planes
 - but bit-codes still work the same way
 - additional front and back clipping plane
 - zmin = -1, zmax = 1 in OpenGL

Other Geometric Problems

- Questions: How can these ideas be used to design an algorithm for checking if:
 - a point is inside a (convex) polygon?
 - E.g. For collision detection
 - A (convex) polygon is inside/intersects/outside a (convex) polygon?



Triangle Clipping

- How does intersection of rectangle & triangle looks like?
 - How many sides?
- How to expand clipping to triangles?
 - Hint: it is convex
 - Will develop on the board...

Cohen-Sutherland Algorithm for convex polygons

```

C - S - Clip( poly = P0, ..., Pn, xmin, xmax, ymin, ymax )
for i = 1 to n Ci ← code( Pi );
if ( ( C0 and Ci and ... and Cn ) != 0 ) then return;
if ( ( C0 or Ci or ... or Cn ) = 0 ) then draw( poly );
else
for i = 1 to n if ( OutsideWindow( Pi ) ) then
begin
Edge ← Window boundary of leftmost non - zero bit of Ci;
Pi-1,j ← Pi-1}, Pi ∩ Edge;
Pi,j+1 ← Pi}, Pi-1 ∩ Edge;
C - S - Clip( P0, ..., Pi-1,j}, Pi,j+1}, Pi+1}, ..., Pn, xmin, xmax, ymin, ymax );
end
    
```

	0101	0100	0110
	0001	0000	0010
	1001	1000	1010

bit	1	0
1	y < y _{min}	y ≥ y _{min}
2	y > y _{max}	y ≤ y _{max}
3	x > x _{max}	x ≤ x _{max}
4	x < x _{min}	x ≥ x _{min}