




## Chapter 2

### Basics of Computer Graphics: Rendering Pipeline/OpenGL




## Todo's reminder

- Discussion Group: register
- Assignment 1
  - Test programming environment on lab computers/Set up programming environment on your laptop (optional)
  - Start assignment (have most background after class today)
- Reading (in Shirley: Introduction to CG)
  - Math refresher: Chapters 2, 4
    - Lots of math coming soon– be ready !!!
  - Background on graphics: Chapter 1



## Rendering



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Goal:


- Transform (3D) computer models into images
- Photo-realistic (or not)

Interactive rendering:


- Fast, but until recently low quality
- Roughly follows a fixed patterns of operations
  - **Rendering Pipeline**

Offline rendering:

- Ray-tracing
- Global illumination

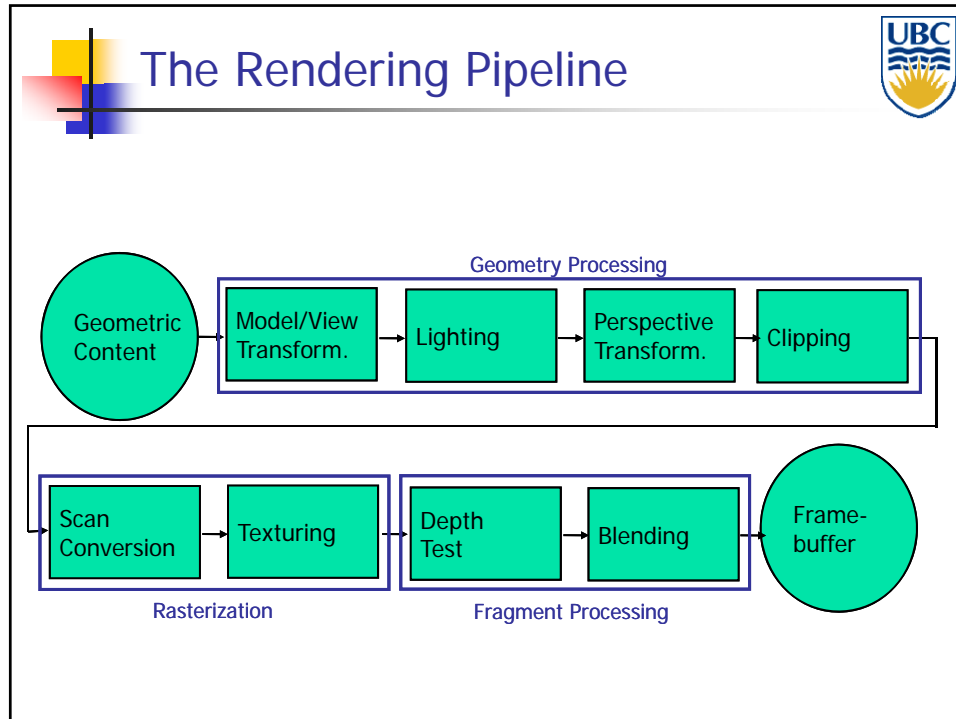


## Rendering Tasks (no particular order)




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- Project 3D geometry onto image plane
  - Geometric transformations
- Determine which primitives/parts of primitives are visible
  - Hidden surface removal
- Determine which pixels geometric primitive covers
  - Scan conversion
- Compute color of every visible surface point
  - Lighting, shading, texture mapping




- 
- Abstract model of
    - sequence of operations to transform geometric model into digital image
    - graphics hardware workflow
  - Underlying API (application programming interface) model for programming graphics hardware
    - OpenGL
    - Direct 3D
  - **Actual implementations vary**




## Discussion




- Advantages of pipeline structure
  - Logical separation of different components, modularity
  - Easy to parallelize:
    - Earlier stages can already work on new data while later stages still work with previous data
    - Similar to pipelining in modern CPUs
    - But much more aggressive parallelization possible (special purpose hardware!)
    - Important for hardware implementations!
  - Only local knowledge of the scene is necessary




## Discussion




- Disadvantages:
  - Limited flexibility
  - Some algorithms would require different ordering of pipeline stages
    - Hard to achieve while still preserving compatibility
  - Only local knowledge of scene is available – doesn't support:
    - Shadows
    - Global illumination




## (Tentative) Lecture Syllabus




- Introduction + Rendering Pipeline (week 1/2)
- Transformations (week 2/3)
- Scan Conversion (week 4/5)
- Clipping (week 5)
- Hidden Surface Removal (week 6/7)
- Review & Midterm (week 7)
  - Midterm: Oct 20
- Lighting Models (week 8)
- Texture mapping (week 9/10)
- Review & Midterm (week 10)
  - Midterm: Nov 10
- Ray Tracing (week 11)
- Shadows (week 11/12)
- Modeling (content creation) (week 12/13)
- Review (last lecture)




## Rendering Pipeline Implementation: OpenGL/Glut







## OpenGL




- API for graphics hardware
- Started in 1989 by Kurt Akeley
- Designed to exploit GPU
- Implemented on many different platforms
- Low level, powerful flexible
- Pipeline processing
  - Communication via state setting
  - Event driven



## Graphics State (global variables)



- Set state once, remains until overwritten
  - `glColor3f(1.0, 1.0, 0.0)` → set color to yellow
  - `glClearColor(0.0, 0.0, 0.2)` → dark blue bg
  - `glEnable(LIGHT0)` → turn on light
  - `glEnable(GL_DEPTH_TEST)` → hidden surf.




## GLUT: OpenGL Utility Toolkit




- **Event driven !!!**

```
int main(int argc, char **argv)
{
    glutInit( &argc, argv );
    glutInitDisplayMode( GLUT_RGB |
                        GLUT_DOUBLE | GLUT_DEPTH);
    glutInitWindowSize( 640, 480 );
    glutCreateWindow( "openGLDemo" );
    glutDisplayFunc( DrawWorld );
    glutIdleFunc(Idle);
    glClearColor( 1,1,1 );
    glutMainLoop();


    return 0;        // never reached
}
```




## Event-Driven Programming




- Main loop not under your control
  - vs. procedural
- Control flow through event **callbacks**
  - redraw the window now
  - key was pressed
  - mouse moved
- Callback functions called from main loop **when events occur**
  - mouse/keyboard, redrawing...




## OpenGL/GLUT Example



```
void DrawWorld() {  
    glMatrixMode( GL_PROJECTION );  
    glLoadIdentity();  
    glMatrixMode( GL_MODELVIEW );  
    glLoadIdentity();  
    glClear( GL_COLOR_BUFFER_BIT );  
    angle += 0.05;  
    glRotatef( angle, 0, 0, 1 );  
    ... // draw triangle  
    glutSwapBuffers();  
}
```




## GLUT Example




```
void Idle() {  
    angle += 0.05;  
    glutPostRedisplay();  
}
```






## GLUT Input Events




```
// you supply these kind of functions
void reshape(int w, int h);
void keyboard(unsigned char key, int x, int y);
void mouse(int but, int state, int x, int y);

// register them with glut
glutReshapeFunc(reshape);
glutKeyboardFunc(keyboard);
glutMouseFunc(mouse);
```




## GLUT and GLU primitives




```
gluSphere(...)
gluCylinder(...)
glutSolidSphere(GLdouble radius, GLint slices, GLint stacks)
glutWireSphere(...)
glutSolidCube(GLdouble size)
glutWireCube(...)
glutSolidTorus(...)
glutWireTorus(...)
glutSolidTeapot(...)
glutWireTeapot(...)
```

- Note:
  - Have limited set of parameters
  - Control via global transformations (see a1 template)
  - **Need to save/restore setting**




## GLUT and GLU primitives




- Example (from a1): draw ball at random positions

```
// Setup transformation matrix for this ball.  
  
glPushMatrix(); → Save previous state  
  
glTranslatef(x_, y_, 0);  
// Now have coordinate system with 0,0,0 at ball centre  
// DRAW IT!  
glutSolidSphere(radius_, 12, 4);  
// Restore the transformation matrix.  
  
glPopMatrix(); → Restore previous state
```




## GLUT and GLU primitives




- Basic Transformations:

```
// Different basic transformations  
glTranslatef(...);  
glRotatef(...);  
glScalef(...);
```



## Depth buffer




- For visibility (hidden surface removal)
  - stores a z-value for every pixel
  - smaller z means “closer”


```
// allocate depth buffer
glutInitDisplayMode( GLUT_RGB | GLUT_DOUBLE | GLUT_DEPTH );

// enabling the depth test
glEnable( GL_DEPTH_TEST );


// clearing the depth buffer for each frame
glClear( GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT );
```




## Geometry Pipeline

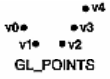


- How to interpret geometry
  - glBegin(<mode of geometric primitives>)
  - mode = GL\_TRIANGLE, GL\_POLYGON, etc.
- Feed vertices
  - glVertex3f(-1.0, 0.0, -1.0)
  - glVertex3f(1.0, 0.0, -1.0)
  - glVertex3f(0.0, 1.0, -1.0)
- Done
  - glEnd()

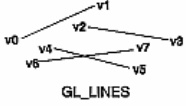


## Open GL: (Some) Primitives

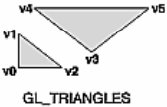




GL\_POINTS




GL\_LINES




GL\_TRIANGLES

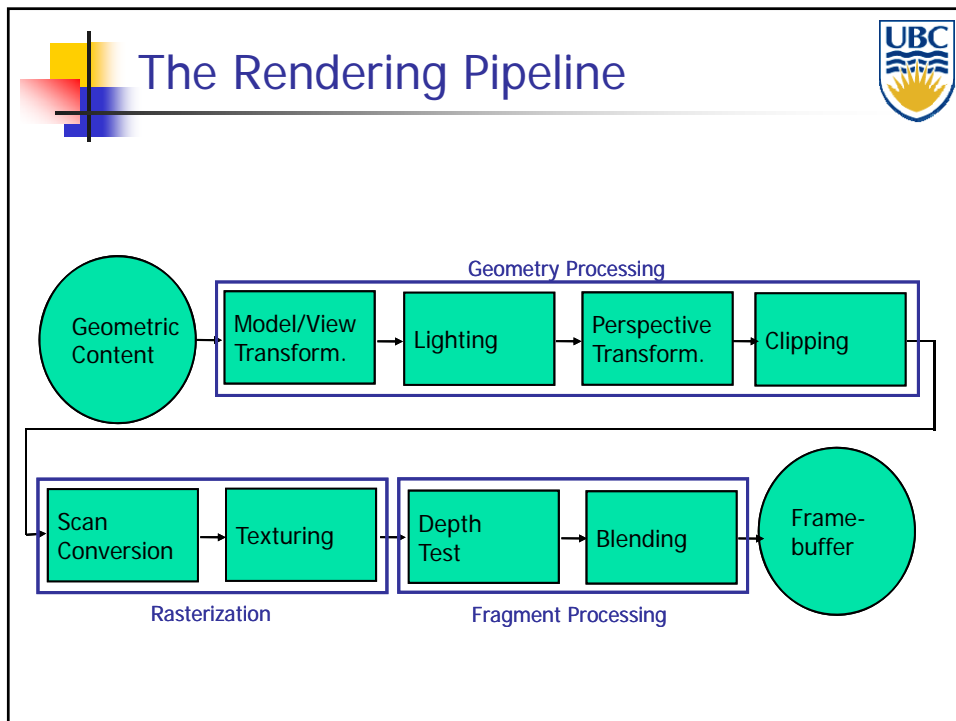
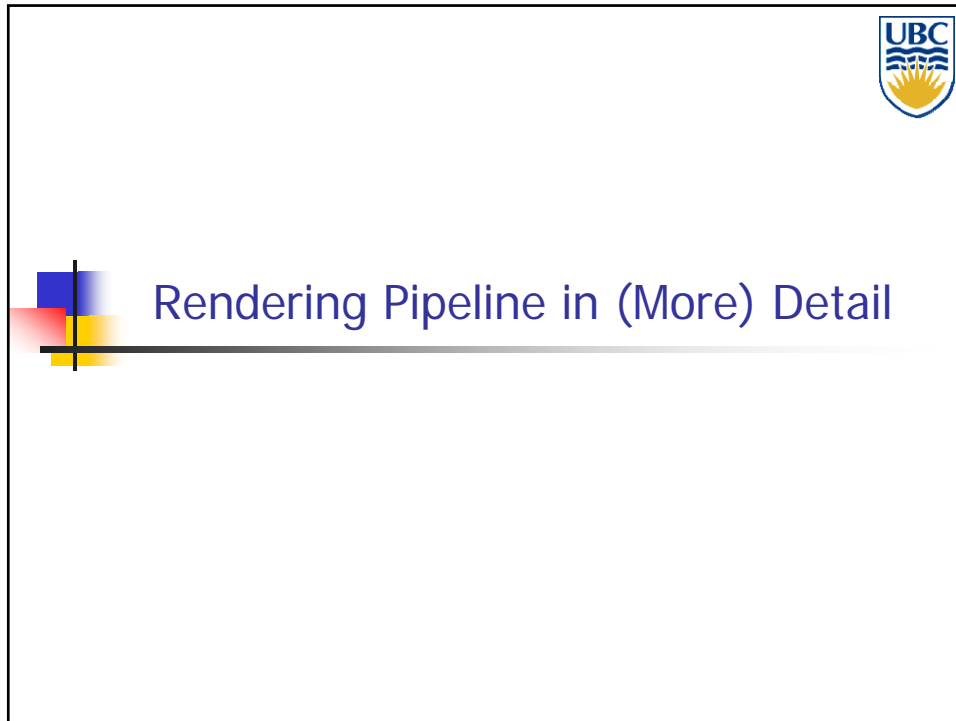
```
glPointSize( float size);  
glLineWidth( float width);  
glColor3f( float r, float g, float b);  
....  
  
■ TRIANGLE...  
  
glColor3f(0,1,0);  
glBegin( GL_TRIANGLES );  
  
    glVertex3f( 0.0f, 0.5f, 0.0f );  
    glVertex3f( -0.5f, -0.5f, 0.0f );  
    glVertex3f( 0.5f, -0.5f, 0.0f );  
  
glEnd();
```




## Assignment 1




- Experience OpenGL & GLUT
  
- Have FUN
  
- Description:  
<http://www.ugrad.cs.ubc.ca/~cs314/Vsep2011/a1/a1.pdf>
  
- Deadline: Sep 23







## (Not only) Geometric Content




- Needs to represent models for
  - Geometric primitives
  - Relations between different primitives (transformations)
  - Object materials
  - Light sources
  - Camera




## Geometric Primitives




- Different philosophies:
  - Collections of complex shapes
    - Spheres, cones, cylinders, tori, ...
  - One simple type of geometric primitive
    - Triangles or triangle meshes
  - Small set of complex primitives with adjustable parameters
    - E.g. "all polynomials of degree 2"
    - Splines, NURBS (details in CPSC 424)
    - Implicits




## Geometric Primitives




- Mathematical representations:
  - Explicit functions
  - Parametric functions
  - Implicit functions




## Explicit Functions




- Curves:
  - $y$  is a function of  $x$ :  $y := \sin(x)$
  - Only works in 2D
- Surfaces:
  - $z$  is a function of  $x$  and  $y$ :  $z := \sin(x) + \cos(y)$
  - Cannot define arbitrary shapes in 3D




## Parametric Functions



- Curves:
  - 2D: x and y are functions of a parameter value t
  - 3D: x, y, and z are functions of a parameter value t

$$C(t) := \begin{pmatrix} \cos(t) \\ \sin(t) \\ t \end{pmatrix}$$



## Parametric Functions




- Surfaces:
  - Surface S is defined as a function of parameter values s, t
  - Names of parameters can be different to match intuition:

$$S(\phi, \theta) := \begin{pmatrix} \cos(\phi) \cos(\theta) \\ \sin(\phi) \cos(\theta) \\ \sin(\theta) \end{pmatrix}$$






## Geometric Content




- Implicit Surfaces:
  - Surface defined by zero set (roots) of function
  - E.g:

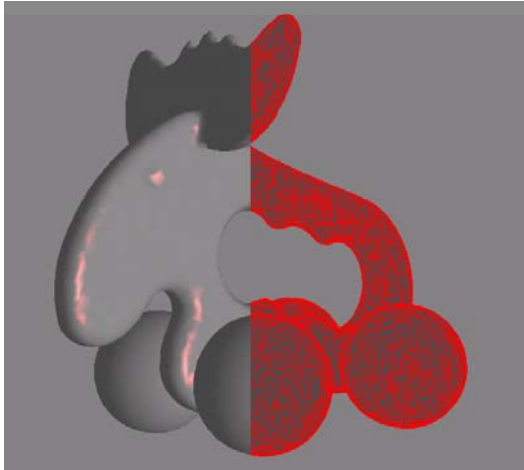
$$S(x, y, z) : x^2 + y^2 + z^2 - 1 = 0$$

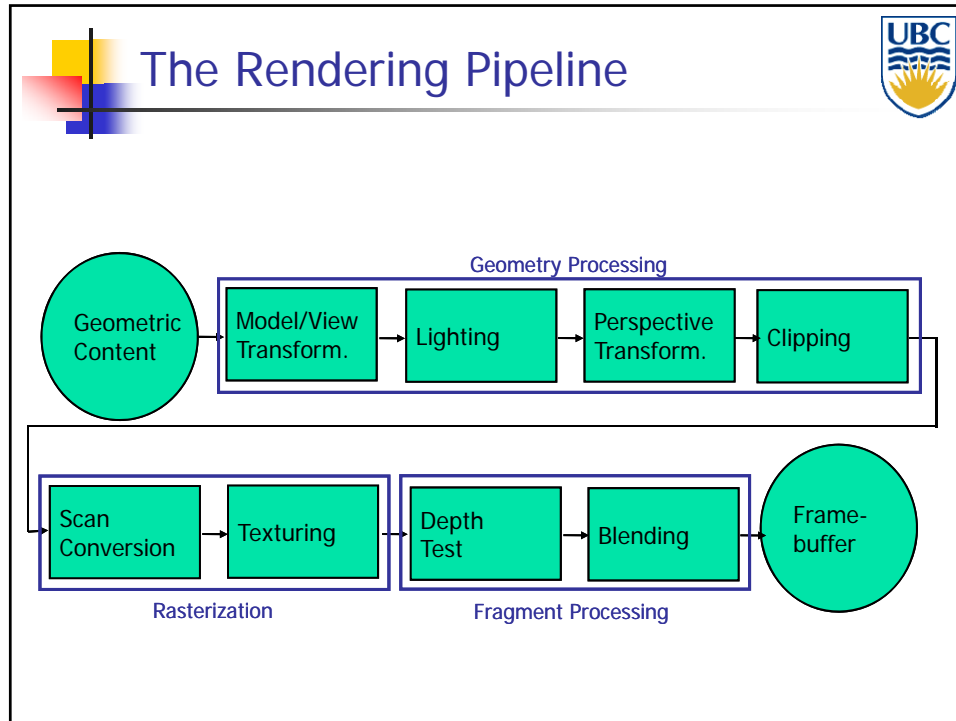


## Geometric Content

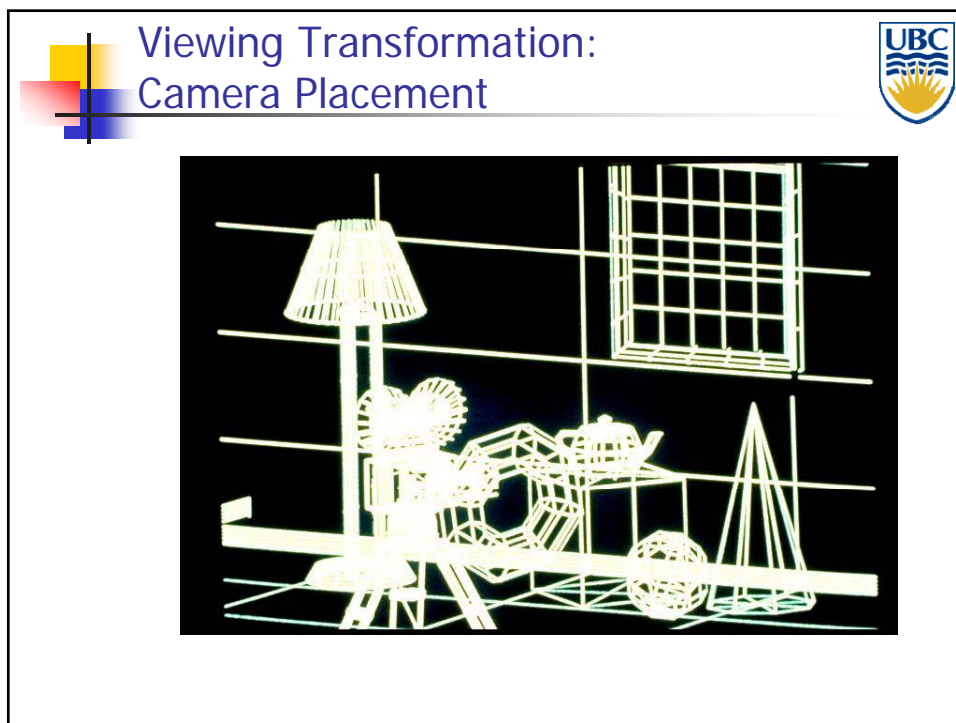
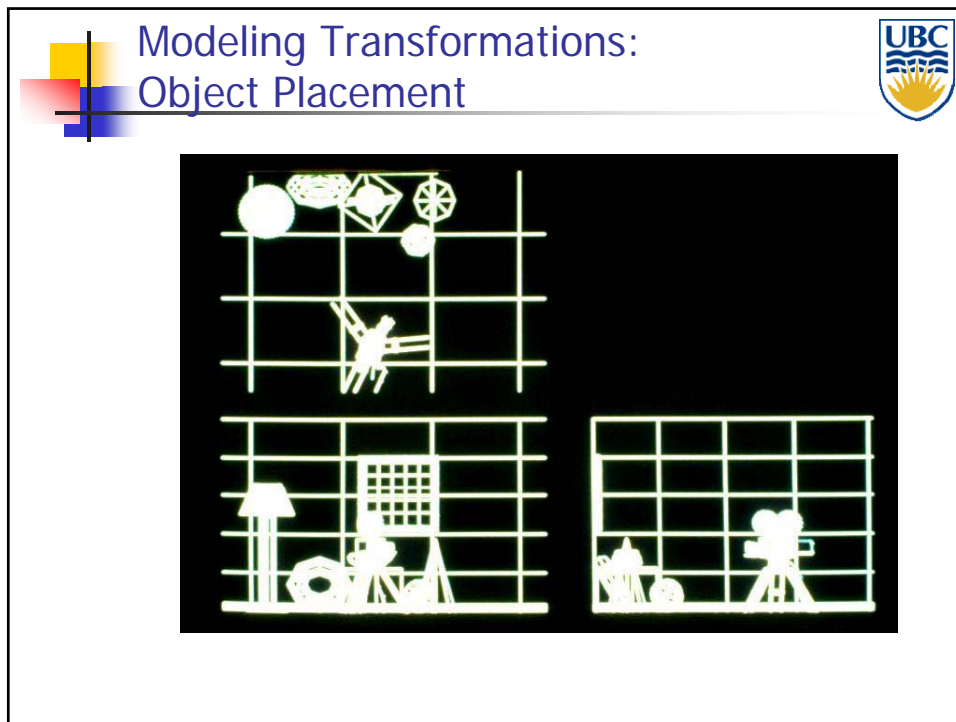




- Triangles and Triangle Meshes:



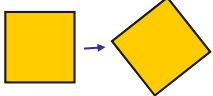
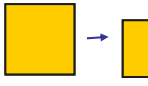
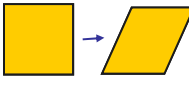


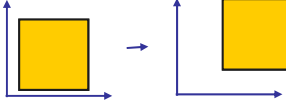

- 
- The slide is titled 'Modeling and Viewing Transformations'. It contains two main bullet points, each with a sub-bullet point. The UBC logo is in the top right corner.
- Placing objects - Modeling transformations
    - Map points from object coordinate system to world coordinate system
  - Placing camera - Viewing transformation
    - Map points from world coordinate system to camera (or eye) coordinate system





 Modeling & Viewing Transformations 

- Types of transformations:
  - Rotations, scaling, shearing


  

- Translations 
- Other transformations (not handled by rendering pipeline):
  - Freeform deformation 


 Modeling & Viewing Transformation 

- Linear transformations
  - Rotations, scaling, shearing
  - Can be expressed as 3x3 matrix
  - E.g. rotation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$



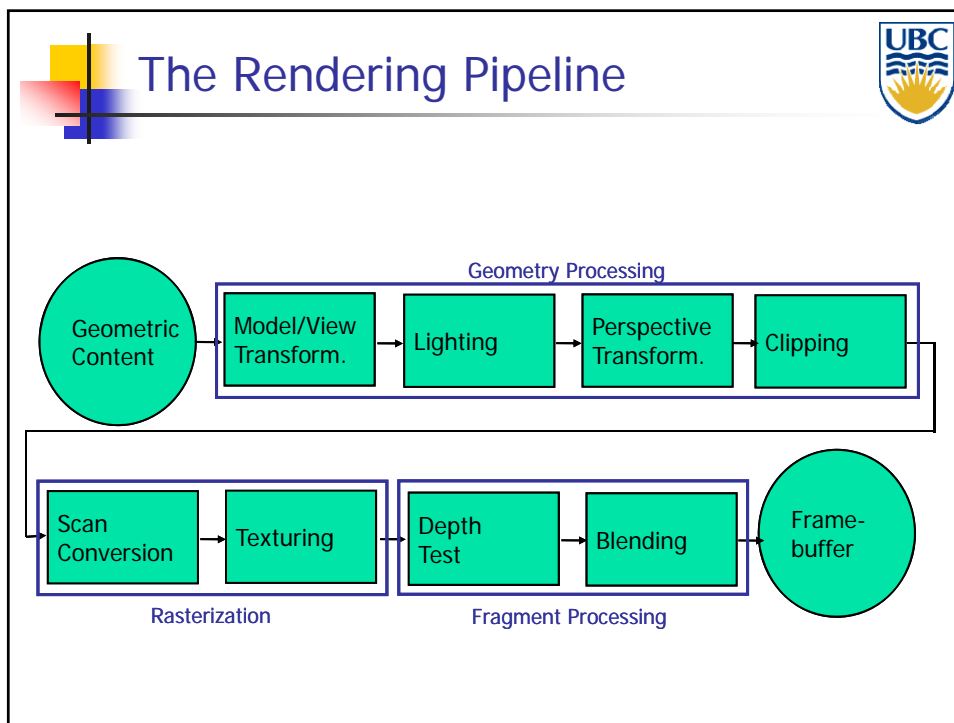
## Modeling & Viewing Transformation

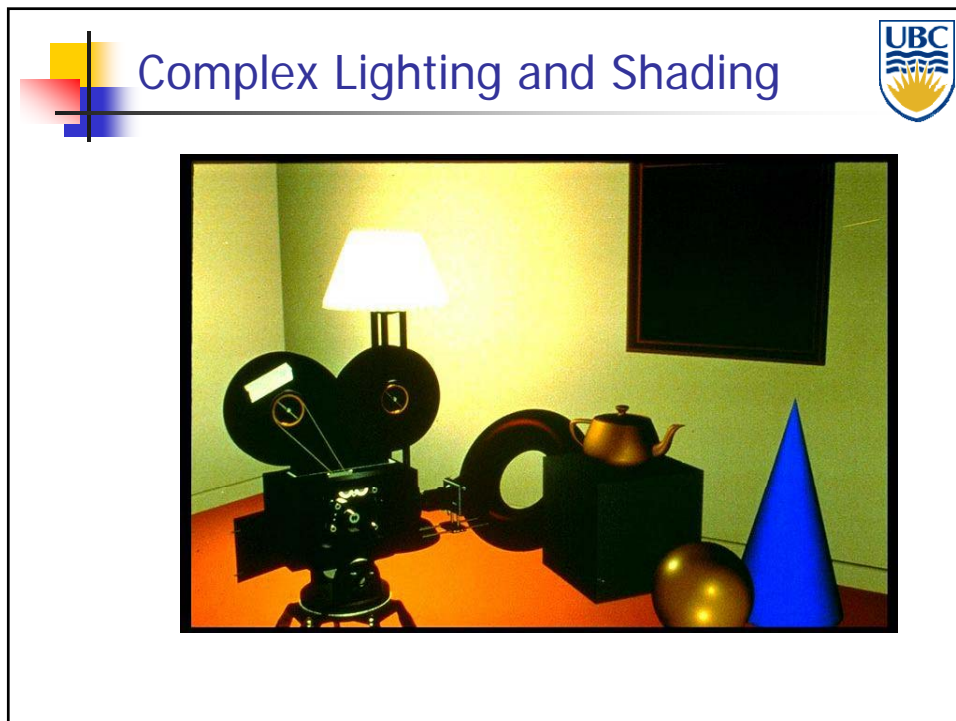
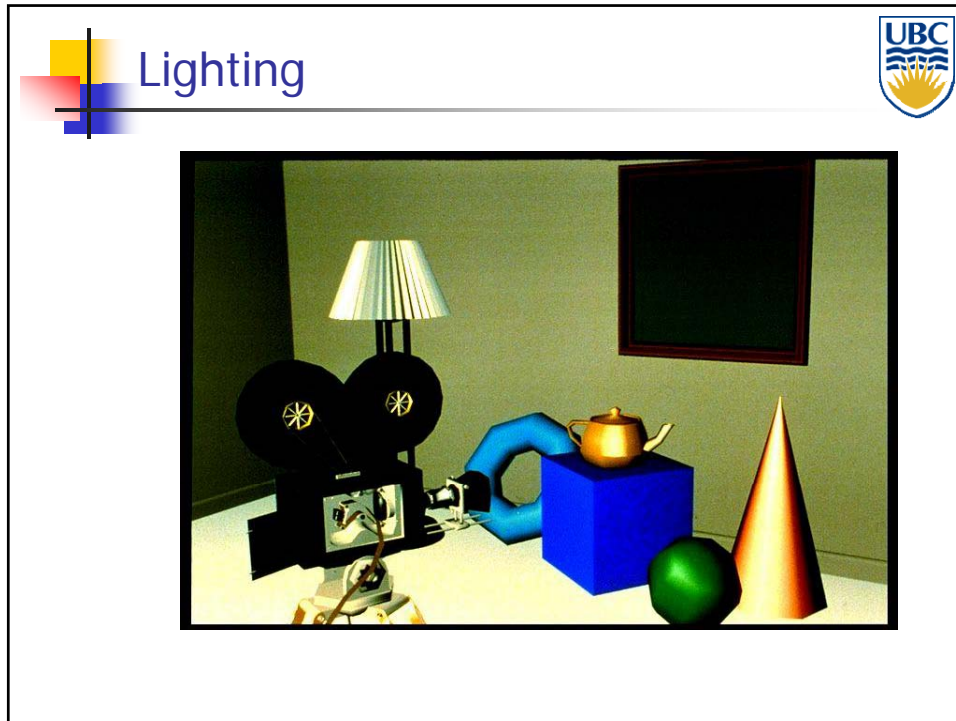


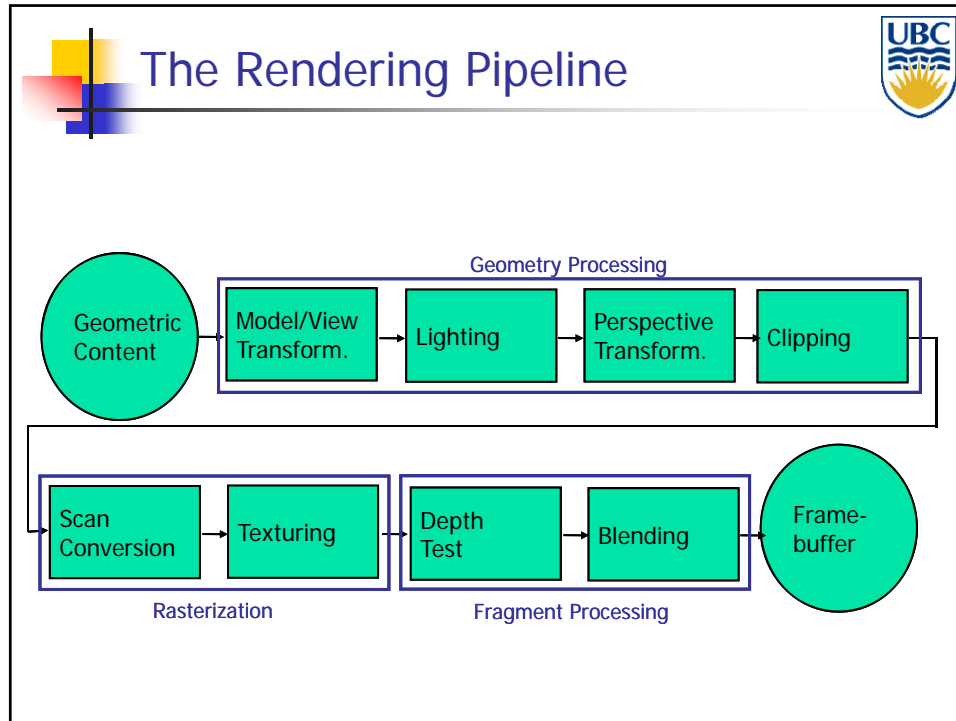
- Affine transformations
  - Linear transformations + translations
  - Can be expressed as 3x3 matrix + 3 vector
  - E.g. rotation + translation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \\ t_z \end{pmatrix}$$

- Another representation: 4x4 homogeneous matrix



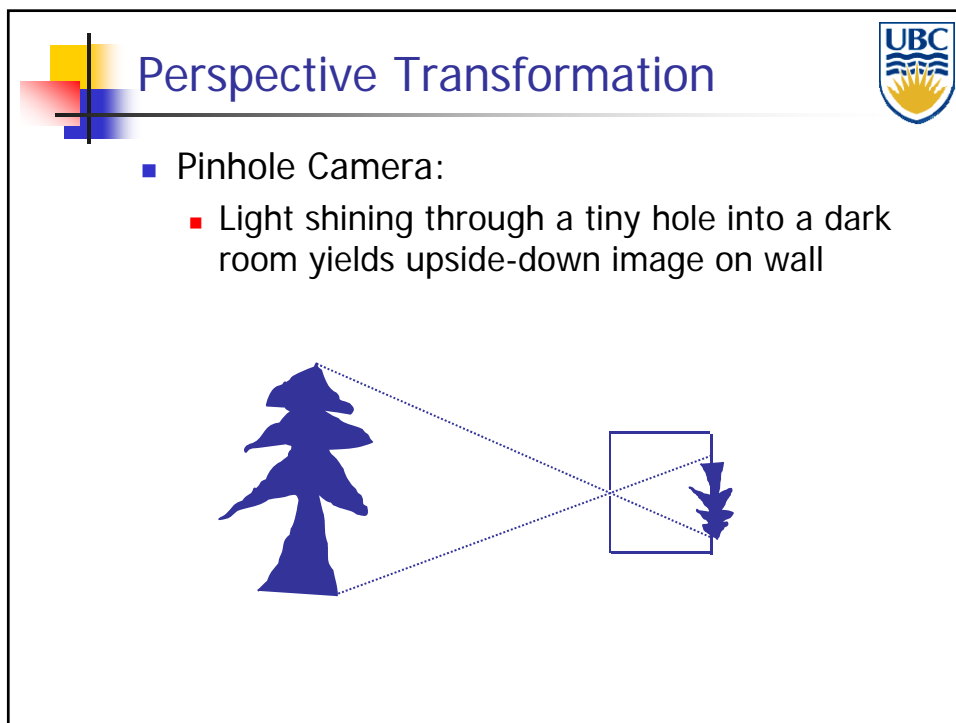
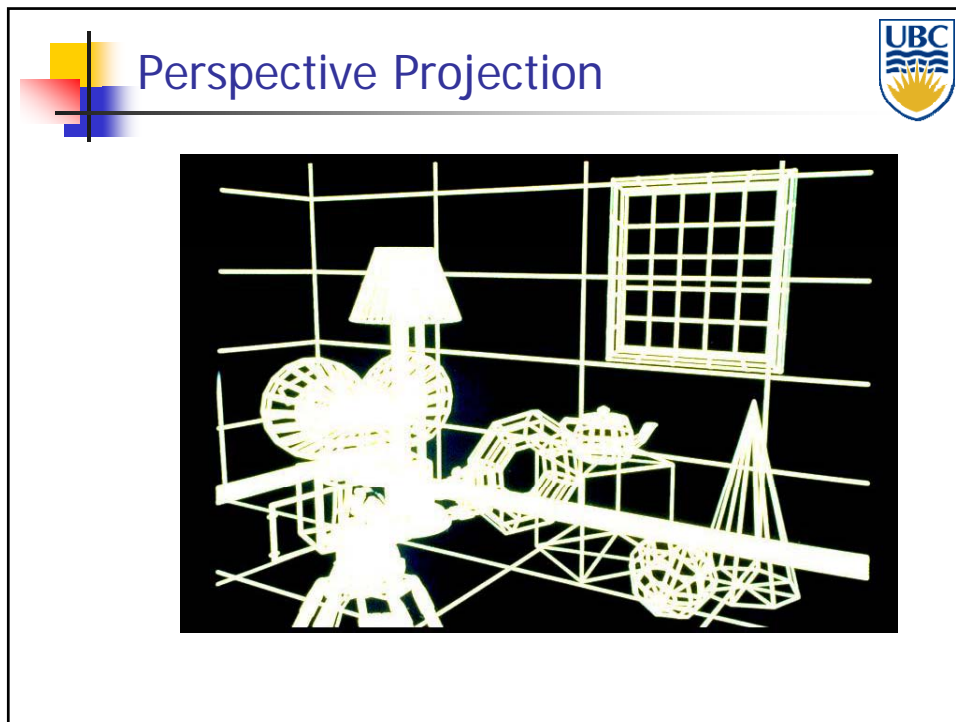




## Perspective Transformation

- Purpose:
  - Project 3D geometry to 2D image plane
  - Simulates a camera
- Camera model:
  - Pinhole camera (single view point)
  - Other, more complex camera models also exist in computer graphics, but are less common
    - Thin lens cameras
    - Full simulation of lens geometry

The UBC logo is in the top right corner.





 Perspective Transformation 

- Pinhole Camera

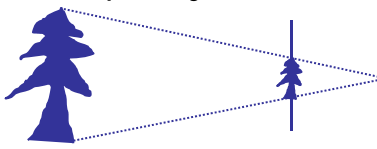


 Pinhole Camera - Camera Obscura 

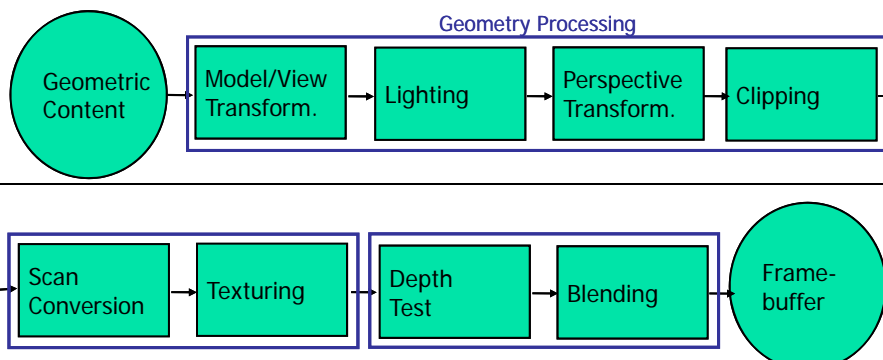


## Perspective Transformation

- In computer graphics:
  - Image plane conceptually in front of center of projection
  - Perspective transformations – subset of projective transformations
  - Linear & affine transformations also belong to this class
  - All projective transformations can be expressed as 4x4 matrix operations



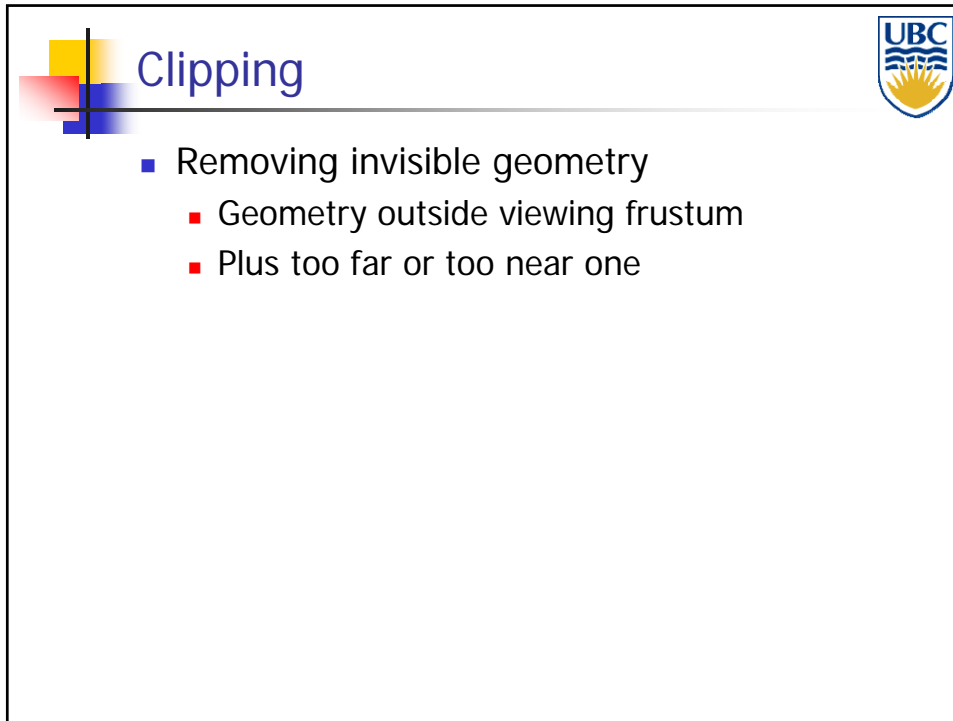
## The Rendering Pipeline



```
graph LR; GC((Geometric Content)) --> G1[Model/View Transform.]; G1 --> G2[Lighting]; G2 --> G3[Perspective Transform.]; G3 --> G4[Clipping]; G4 --> R1[Scan Conversion]; R1 --> R2[Texturing]; R2 --> F1[Depth Test]; F1 --> F2[Blending]; F2 --> FB((Frame-buffer));
```

The rendering pipeline consists of the following stages:

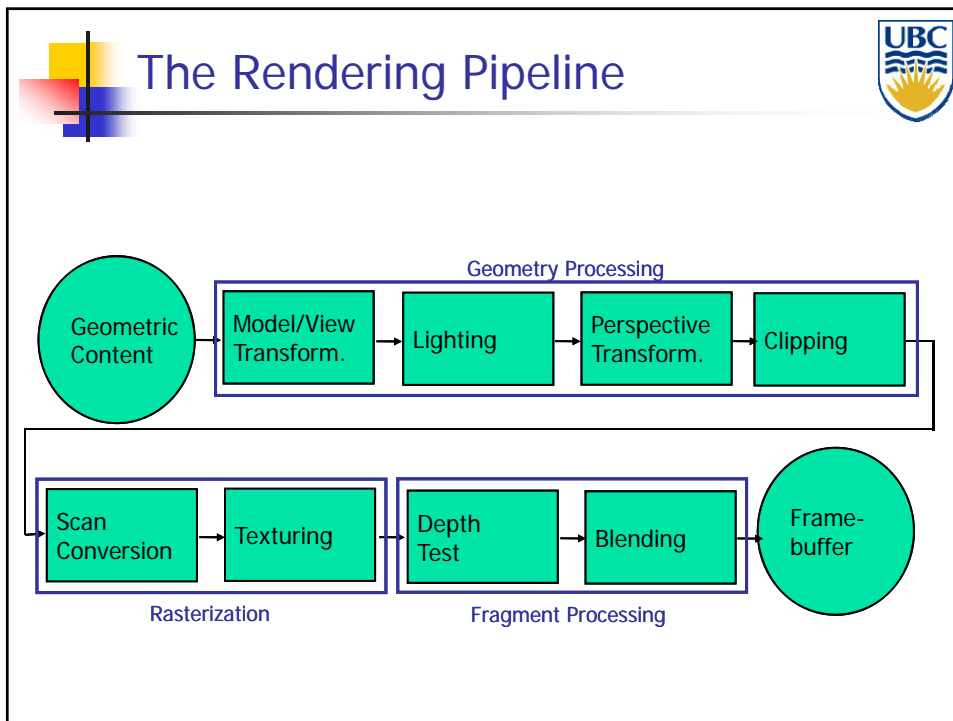
- Geometric Content** (Input)
- Geometry Processing**: Model/View Transform., Lighting, Perspective Transform., Clipping
- Rasterization**: Scan Conversion, Texturing
- Fragment Processing**: Depth Test, Blending
- Frame-buffer** (Output)




**Clipping**


- Removing invisible geometry
  - Geometry outside viewing frustum
  - Plus too far or too near one

UBC logo







## Scan Conversion/Rasterization

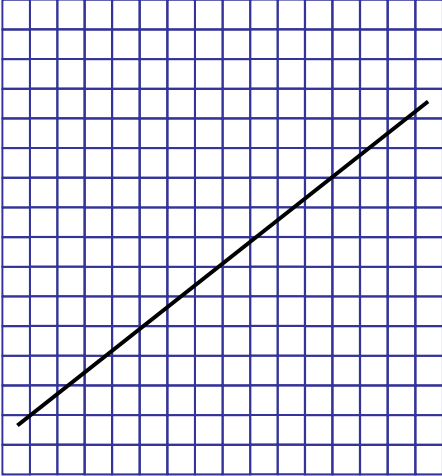



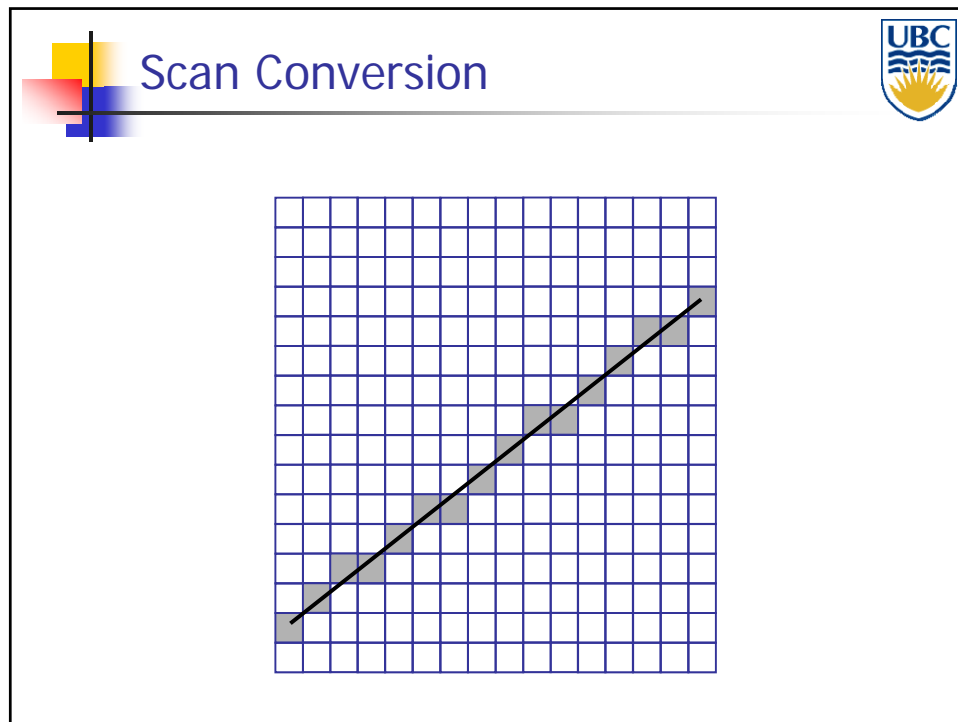
- Convert continuous 2D geometry to discrete
- Raster display – discrete grid of elements
- Terminology
  - **Pixel:** basic element on device
  - **Resolution:** number of rows & columns in device
    - Measured in
      - Absolute values (1K x 1K)
      - Density values (300 dots per inch)
  - **Screen Space:** Discrete 2D Cartesian coordinate system of the screen pixels





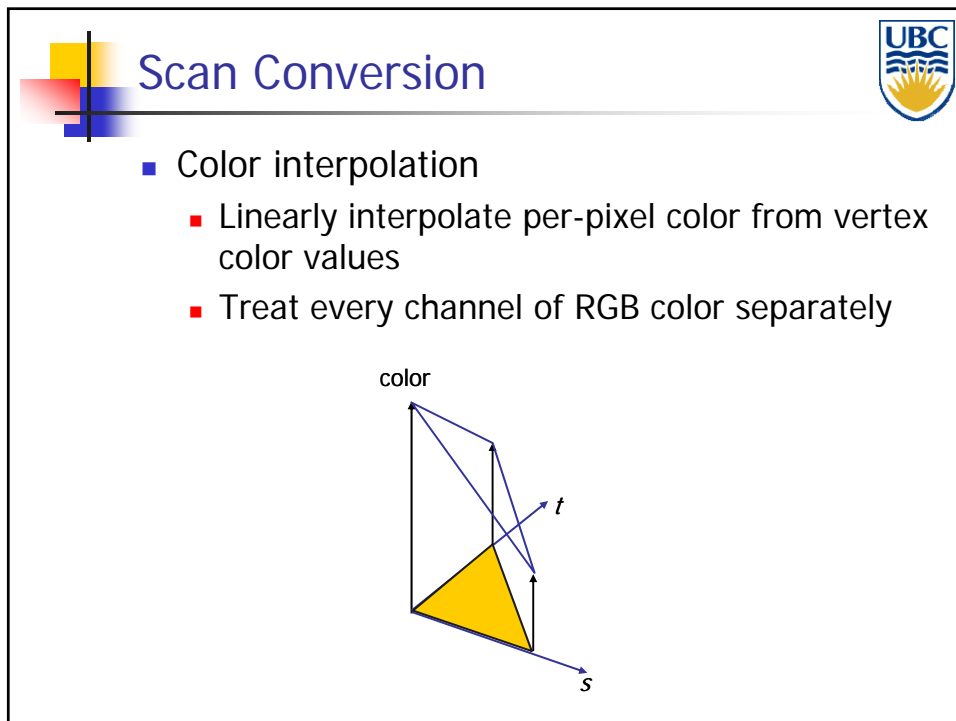
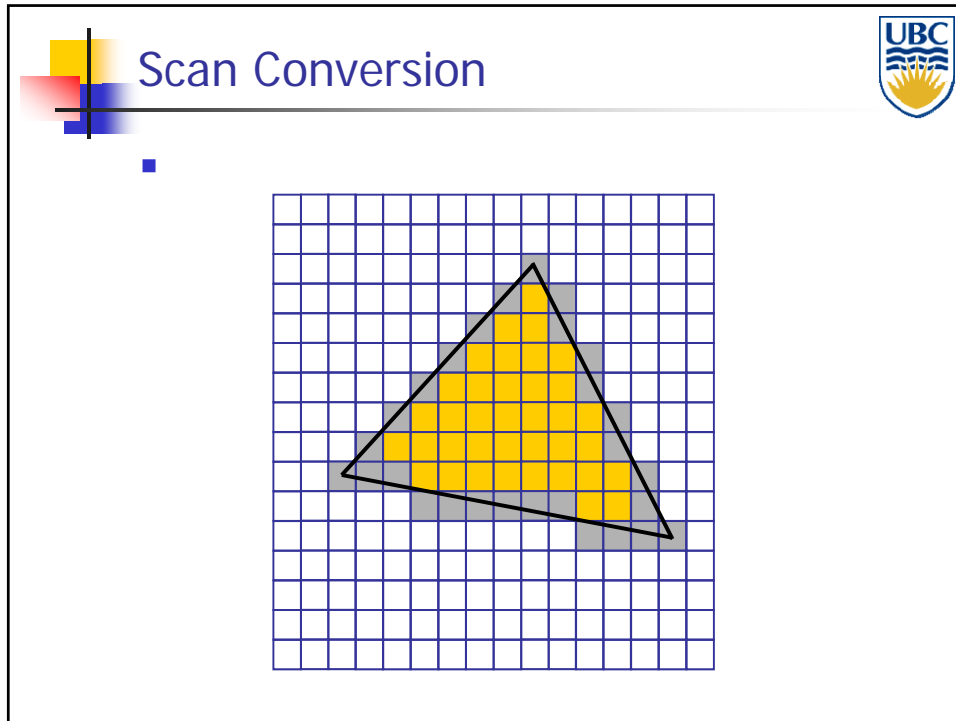
## Scan Conversion





The slide is titled "Scan Conversion" and features the UBC logo in the top right corner. It contains a bulleted list of problems:

- Problem:
  - Line is infinitely thin, but image has finite resolution
  - Results in steps rather than a smooth line
    - Jaggies
    - Aliasing
  - One of the fundamental problems in computer graphics



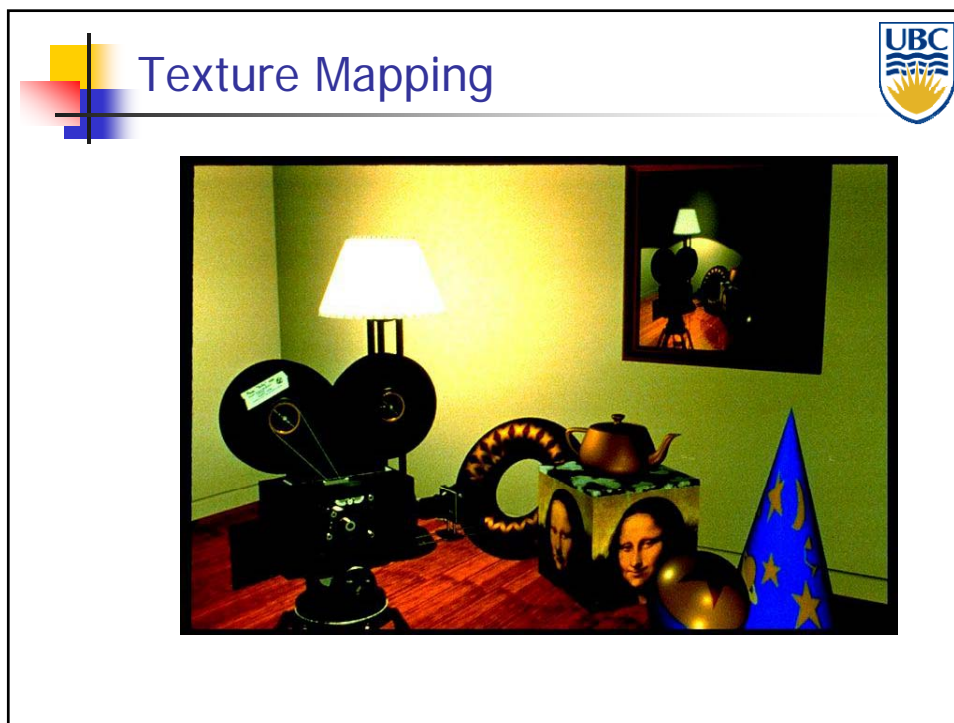
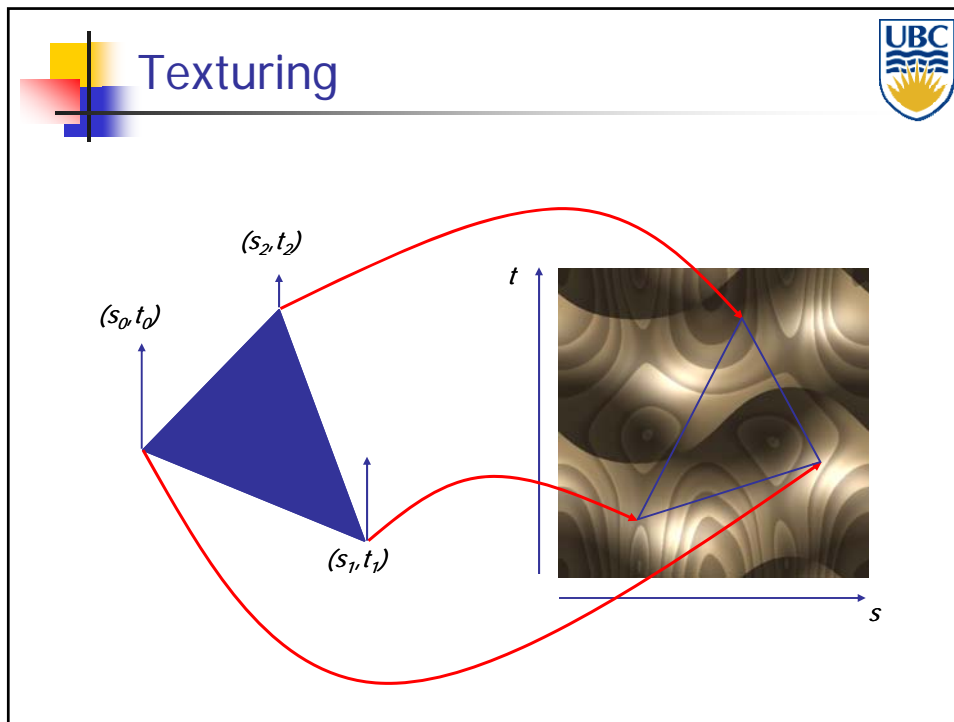
## Scan Conversion

- Color interpolation
- Example:

red      green      blue

## The Rendering Pipeline

```
graph LR; GC((Geometric Content)) --> GP[Geometry Processing]; subgraph GP; MVT[Model/View Transform.]; L[Lighting]; PT[Perspective Transform.]; C[Clipping]; end; GP --> R[Rasterization]; subgraph R; SC[Scan Conversion]; T[Texturing]; end; R --> FP[Fragment Processing]; subgraph FP; DT[Depth Test]; B[Blending]; end; FP --> FB((Frame-buffer));
```

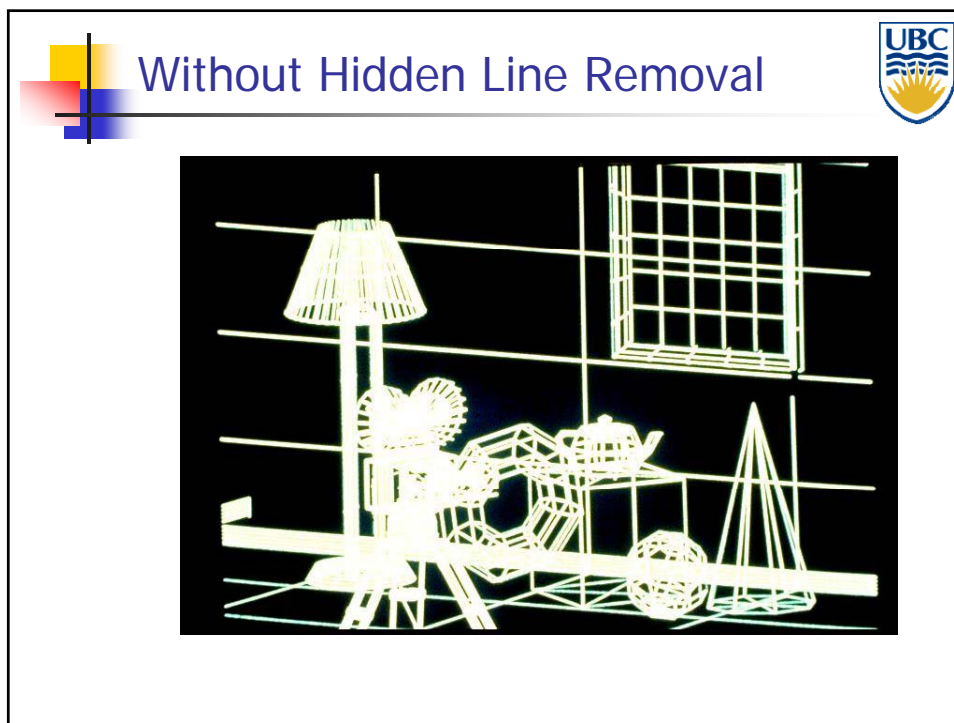
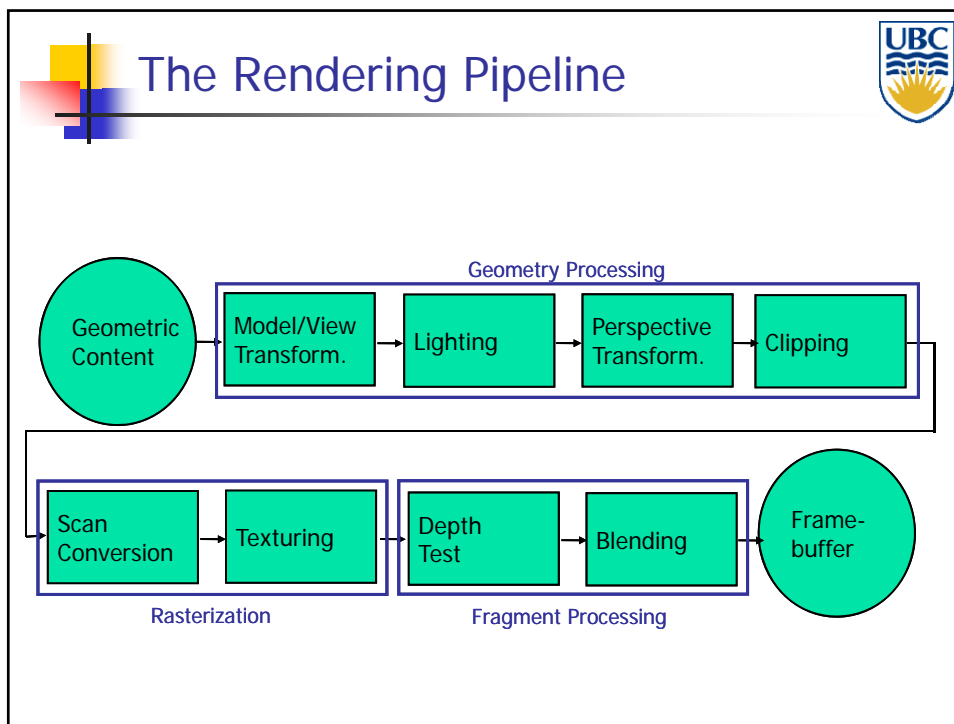







## Texturing


- Issues:
  - How to map pixel from texture (texels) to screen pixels
    - Texture can appear widely distorted in rendering
    - Magnification / minification of textures
  - Filtering of textures
  - Preventing aliasing (anti-aliasing)








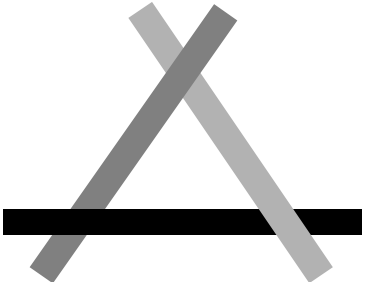

## Depth Test /Hidden Surface Removal

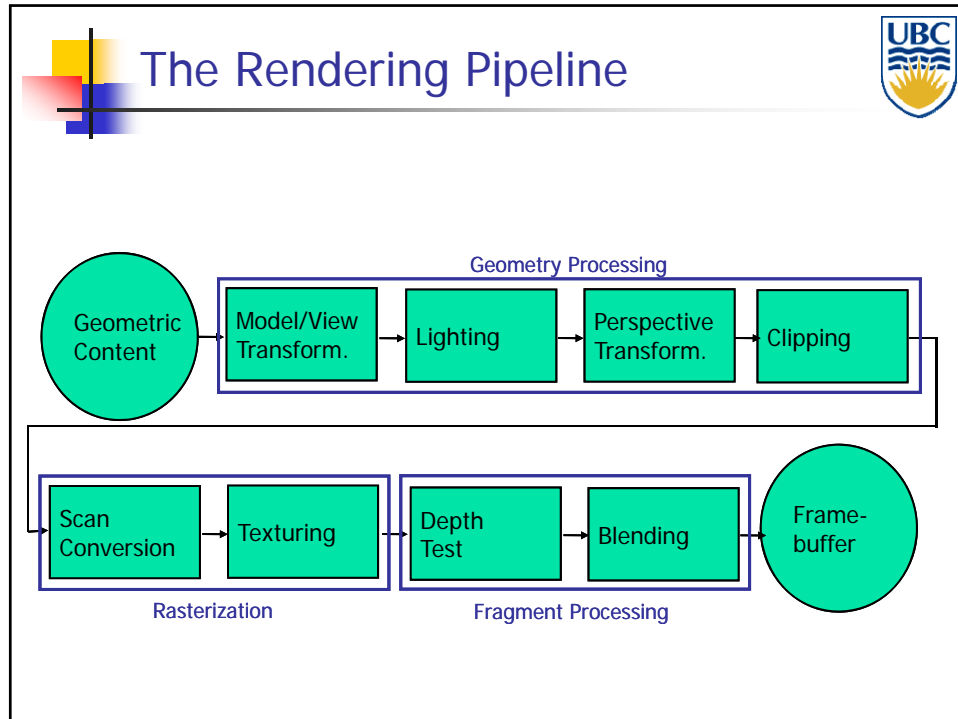


- Remove invisible geometry
  - Parts that are hidden behind other geometry
- Possible Implementations:
  - Per-fragment decision
    - Depth buffer
  - Object space decision
    - Clipping polygons against each other
    - Sorting polygons by distance from camera



## Depth Test /Hidden Surface Removal





## Blending

- Blending:
  - Final image: write fragments to pixels
  - Draw from farthest to nearest
  - No blending – replace previous color
  - Blending: combine new & old values with some arithmetic operations
- Frame Buffer : video memory on graphics board that holds resulting image & used to display it

The UBC logo is in the top right corner.

