


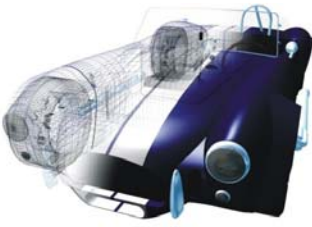


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## Chapter 14




### Geometric Modeling - Basics

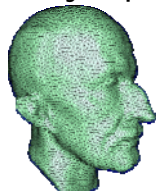


## Geometry

- Mathematical models of real world shapes
  - Most common: Boundary representations

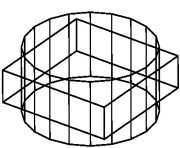


Freeform –  
smooth surface

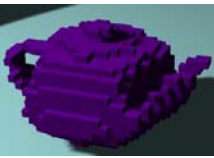


Mesh – polygonal  
surface


- Alternative: Volumetric representations




Primitive based



Voxel based

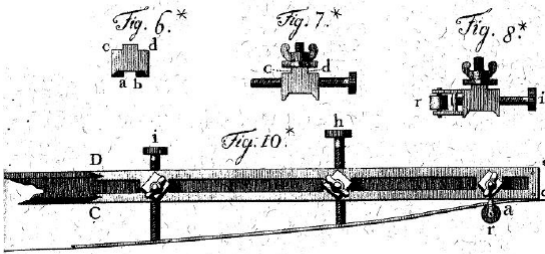


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## Splines – Free Form Curves


- Geometric meaning of coefficients (base)
  - Approximate/interpolate set of positions, derivatives, etc..



- Will see one example



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## Splines – Free Form Curves


- Usually parametric
  - $C(t)=[x(t),y(t)]$  or  $C(t)=[x(t),y(t),z(t)]$
- Description = basis functions + coefficients

$$C(t) = \sum_{i=0}^n P_i B_i(t) = (x(t), y(t))$$


$$x(t) = \sum_{i=0}^n P_i^x B_i(t)$$

$$y(t) = \sum_{i=0}^n P_i^y B_i(t)$$

- Same basis functions for all coordinates




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## Hermite Cubic Basis

- Geometrically-oriented coefficients
  - 2 positions + 2 tangents
- Require  $C(0)=P_0$ ,  $C(1) = P_1$ ,  $C'(0)=T_0$ ,  $C'(1)=T_1$
- Define basis function per requirement

$$C(t) = P_0h_{00}(t) + P_1h_{01}(t) + T_0h_{10}(t) + T_1h_{11}(t)$$


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## Hermite Basis Functions

$$C(t) = P_0h_{00}(t) + P_1h_{01}(t) + T_0h_{10}(t) + T_1h_{11}(t)$$


- To enforce  $C(0)=P_0$ ,  $C(1) = P_1$ ,  $C'(0)=T_0$ ,  $C'(1)=T_1$  basis should satisfy

$$h_{ij}(t); i, j = 0,1, t \in [0,1]$$

curve	$C(0)$	$C(1)$	$C'(0)$	$C'(1)$
$h_{00}(t)$	1	0	0	0
$h_{01}(t)$	0	1	0	0
$h_{10}(t)$	0	0	1	0
$h_{11}(t)$	0	0	0	1



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## Hermite Cubic Basis


- Can satisfy with cubic polynomials as basis

$$h_{ij}(t) = a_3t^3 + a_2t^2 + a_1t + a_0$$


- Obtain - solve 4 linear equations in 4 unknowns for each basis function

$$h_{ij}(t); i, j = 0,1, t \in [0,1]$$

curve	$C(0)$	$C(1)$	$C'(0)$	$C'(1)$
$h_{00}(t)$	1	0	0	0
$h_{01}(t)$	0	1	0	0
$h_{10}(t)$	0	0	1	0
$h_{11}(t)$	0	0	0	1



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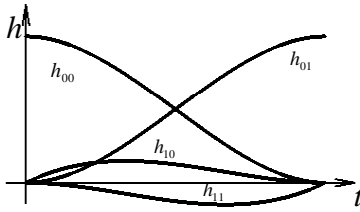



## Hermite Cubic Basis

- Four polynomials that satisfy the conditions


$h_{00}(t) = t^2(2t-3)+1$ 
 $h_{01}(t) = -t^2(2t-3)$

$h_{10}(t) = t(t-1)^2$ 
 $h_{11}(t) = t^2(t-1)$



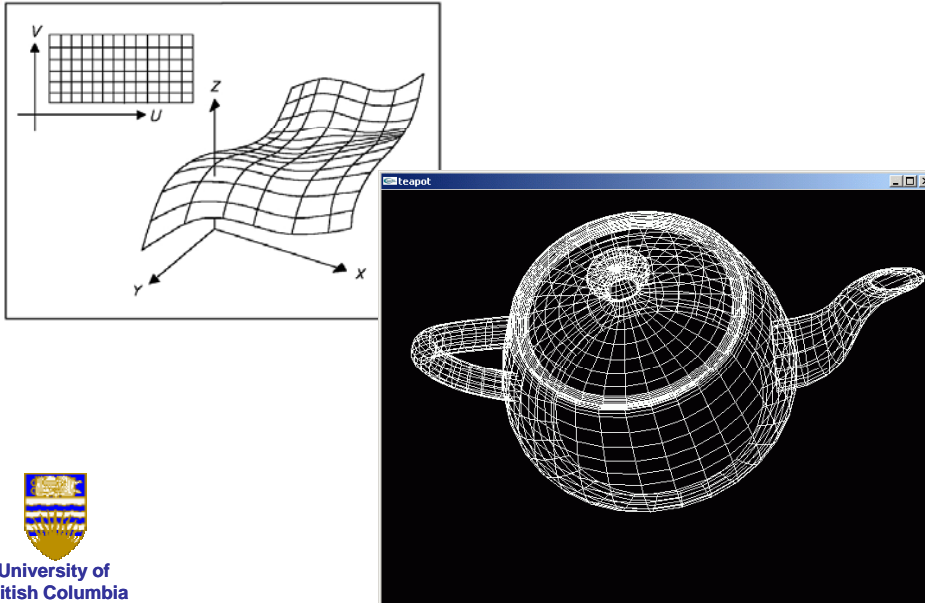


hermite



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## Tensor Spline Surfaces




The diagram illustrates the concept of tensor spline surfaces. On the left, a 2D grid in the UV plane is shown, with axes labeled U and V. This grid is mapped to a 3D coordinate system with axes X, Y, and Z, where the grid is deformed into a smooth, wavy surface. On the right, a 3D wireframe model of a teapot is shown, demonstrating the application of tensor spline surfaces to create a smooth, curved object. The teapot is rendered in a wireframe style, showing the underlying grid structure.

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## From Curves to Surfaces – Tensor Splines

- Curve is expressed as inner product of  $P_i$  coefficients and basis functions
 
$$C(u) = \sum_{i=0}^n P_i B_i(u)$$
- To extend curves to surfaces - treat surface as a curve of curves
- Assume  $P_i$  is not constant, but a function of second parameter  $v$ :  $P_i(v) = \sum_{j=0}^m Q_{ij} B_j(v)$

$$C(u,v) = \sum_{i=0}^n \sum_{j=0}^m Q_{ij} B_j(v) B_i(u)$$


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## Bilinear Patches

- Bilinear interpolation of 4 3D points

$$P_{00}, P_{01}, P_{10}, P_{11}$$

- surface analog of line segment curve

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## Bilinear Patches

- Given  $P_{00}, P_{01}, P_{10}, P_{11}$  associated parametric bilinear surface for  $u, v \in [0,1]$  is:



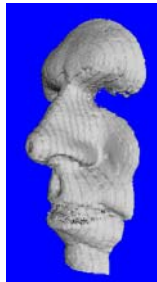
$$P(u, v) = (1-u)(1-v)P_{00} + (1-u)vP_{01} + u(1-v)P_{10} + uvP_{11}$$

- Questions:
  - What does an isoparametric curve of a bilinear patch look like ?
  - When is a bilinear patch planar?

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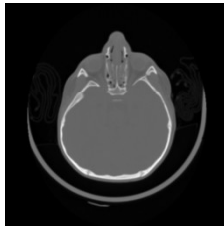

## Geometry Creation (Meshes)

- Reconstruction: Capture real life shapes & convert to mesh
  - Inputs:
    - Points (laser scanner)
    - 3D images
- Modeling (user driven)
- Will see two examples
  - Marching Cubes – reconstruction from images
  - Subdivision – generating smooth meshes from coarse user-given “cages”



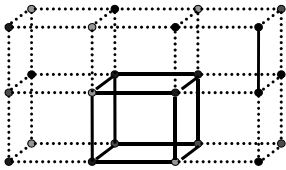

## Reconstruction from Volume Data

- Volume data – view as voxel grid with values at vertices
  - Defines implicit function in 3D
    - interpolate grid values
- Shape defined by isosurface
  - isosurface = set of points with constant isovalue  $\alpha$
  - separates values above  $\alpha$  from values below
- Reconstruction – Extract triangulation approximating isosurface



## Voxels

- Voxel – cube with values at eight corners
  - Each value is above or below isovalue  $\alpha$
- $2^8=256$  possible configurations (per voxel)
  - reduced to 15 (symmetry and rotations)
- Each voxel is either:
  - Entirely inside isosurface
  - Entirely outside isosurface
  - Intersected by isosurface
- MC main observation: Can extract triangulation independently per voxel

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## Basic MC Algorithm

- For each voxel produce set of triangles
  - Based on above/below corner configuration
  - Empty for non-intersecting voxels
  - Approximate surface inside voxel

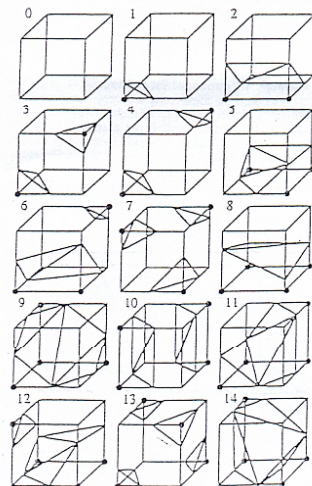



Figure 2. Configurations.



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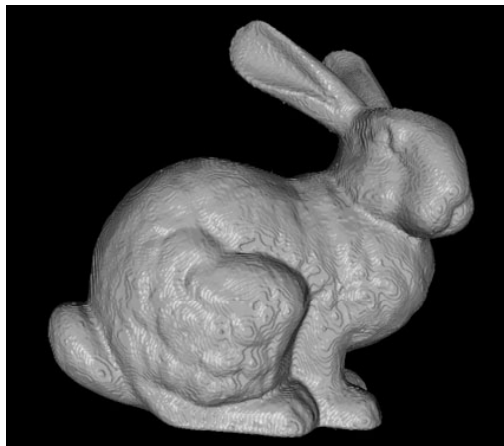


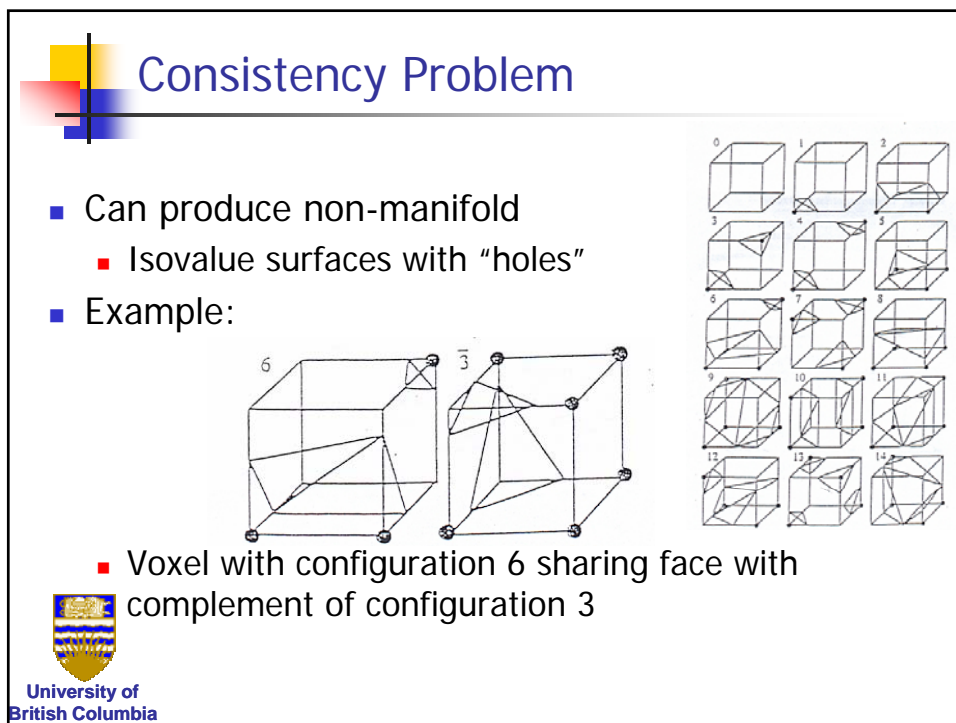
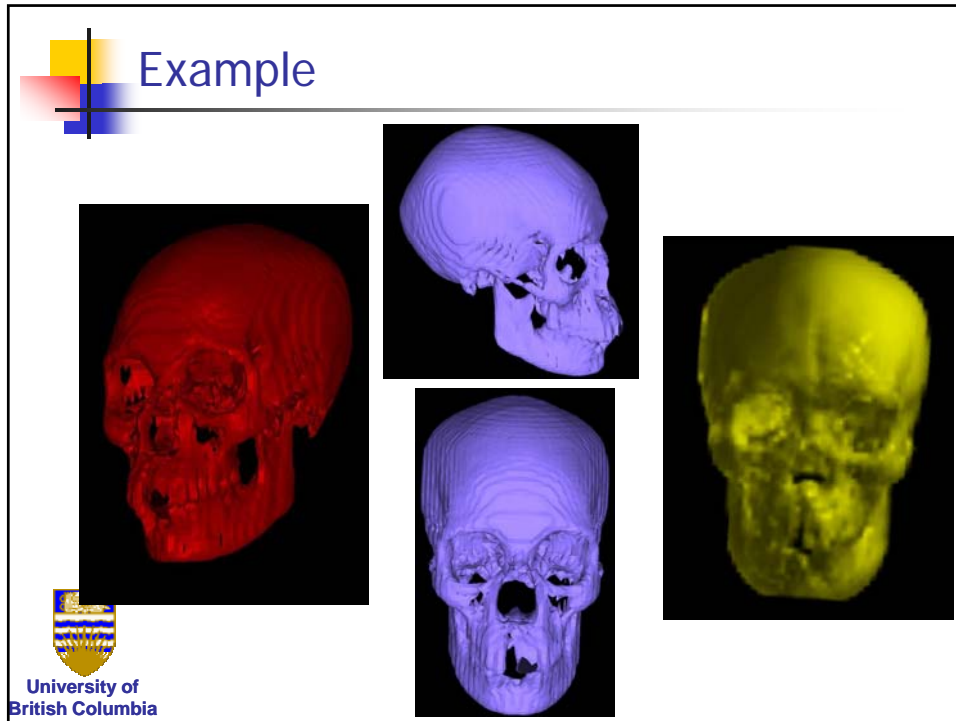
## Configurations

- For each configuration add 1-4 triangles to isosurface
- Isosurface vertices computed by:
  - Interpolation along edges (according to grid values)
    - better shading, smoother surfaces
  - Default – mid-edges



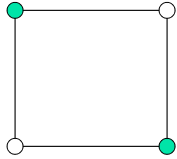
## Example



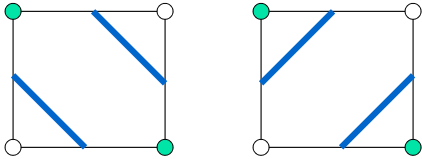


## Ambiguous Faces


- Face containing two diagonally opposite marked grid points and two unmarked ones



- Two locally valid interpretations




- Source of MC consistency problem



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## Consistency

- Problem:
  - Connection of isosurface points on shared face done one way on one face & another way on the other
- Need consistency → use different triangulations
- If choices are consistent get topologically correct surface



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## Solution

- For each problematic configuration have more than one triangulation
- Distinguish different cases by choosing pairwise connections of four vertices on common face
  - Example:

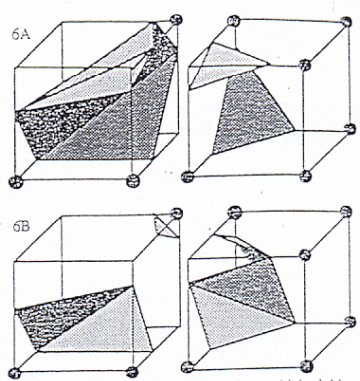



Figure 4. Two possible triangulations which yield a topologically correct isovalue surface.

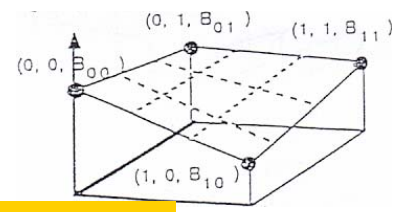
2.0 Asymptotic Decider



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## Asymptotic Decider


- "Guess" value at quad center
- Use bilinear interpolation to obtain



$$B(s, t) = (1-s \quad s) \begin{pmatrix} B_{00} & B_{01} \\ B_{10} & B_{11} \end{pmatrix} \begin{pmatrix} 1-t \\ t \end{pmatrix}$$

$$\{(s, t): 0 \leq s \leq 1, \quad 0 \leq t \leq 1\}$$

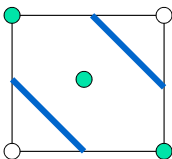
- $B_{ij}$  - isovalues at face corners




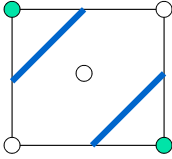
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## Ambiguous Faces

- If center value closer to "green" choose



- Else



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## Various Cases

- Some configurations have no ambiguous faces → no modifications
- Other configurations need modifications according to number of ambiguous faces
  - Apply decoder to each face to decide on triangulation template

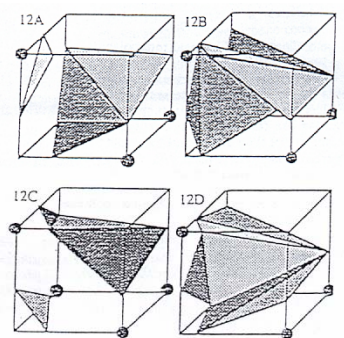



Figure 11.



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