

Shadow Algorithms

CPSC 314

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Last Lecture: Modern GPU Architectures

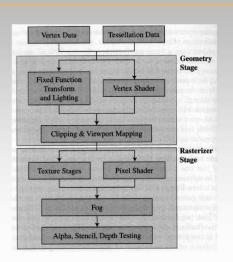


Vertex shader

- Replaces model/view, lighting, and perspective
- Have to implement these yourself
- But can also implement much more

Fragment/pixel shader

- Replaces texture mapping
- Fragment shader must do texturing
- But can do other things





Vertex Program Properties

Run for every vertex, independently

- Access to all per-vertex properties
 - Position, color, normal, texture coords, other custom properties
- Access to read/write registers for temporary results
 - Value is reset for every vertex
 - I.e. cannot pass information from one vertex to the next
- Access to read-only registers
 - Global variables, like ligt position, transformation matrices
- Write output to a specific register for the resulting color

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Vertex Shaders/Programs

Concept:

- Programmable pipeline stage
 - Floating-point operations on 4 vectors
 - Points, vectors, and colors!
- Replace all of
 - Model/View Transformation
 - Lighting
 - Perspective projection

Vertex Programs – Instruction Set



Arithmetic Operations on 4-vectors:

ADD, MUL, MAD, MIN, MAX, DP3, DP4

Operations on Scalars

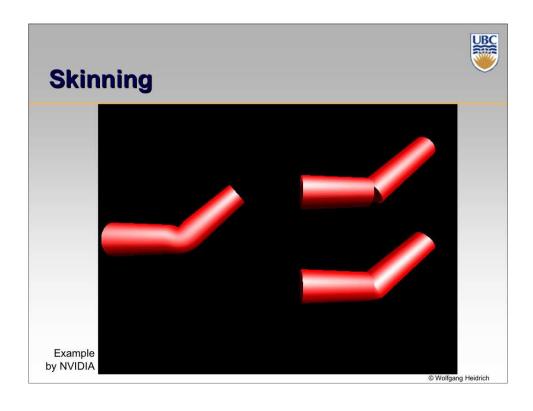
RCP (1/x), RSQ (1/√x), EXP, LOG

Specialty Instructions

- DST (distance: computes length of vector)
- LIT (quadratic falloff term for lighting)

Very latest generation:

Loops and conditional jumps





Fragment Shaders

- Fragment shaders operate on fragments in place of the texturing hardware
 - After rasterization, before any fragment tests or blending
- Input: The fragment, with screen position, depth, color, and a set of texture coordinates
- · Access to textures and some constant data and registers
- · Compute RGBA values for the fragment, and depth
 - Can also "kill "a fragment, that is throw it away
- Two types of fragment shaders: register combiners (GeForce4) and fully programmable (GeForceFX, Radeon 9700)

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High Level Shading Languages e.g. Cg



Cg is a high-level language developed by NVIDIA

- It looks like C or C++
- Actually a language and a runtime environment
 - Can compile ahead of time, or compile on the fly
 - Why compile on the fly?
- What it can do is tightly tied to the hardware
 - How does it know which hardware, and how to use it?



Vertex Program Example

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Pixel Program Example



```
void C5E3f_basicLight(float4 position : TEXCOORDO,
                          float3 normal : TEXCOORD1,
                     out float4 color
                uniform float3 globalAmbient.
                uniform float3 lightColor,
                 uniform float3 lightPosition,
                                                                 // Compute the diffuse term
float3 L = normalize(lightPosition - P);
                uniform float3 eyePosition,
                 uniform float3 Ke,
                                                                  float diffuseLight = max(dot(N, L), 0);
float3 diffuse = Kd * lightColor * diffuseLight;
                 uniform float3 Ka,
                 uniform float3 Kd,
                uniform float3 Ks.
                                                                  // Compute the specular term
                uniform float shininess)
                                                                  float3 V = normalize(eyePosition - P);
float3 H = normalize(L + V);
  float3 P = position.xyz;
float3 N = normalize(normal);
                                                                  float specularLight = pow(max(dot(N, H), 0),
                                                                                               shininess);
                                                                  if (diffuseLight <= 0) specularLight = 0;
float3 specular = Ks * lightColor * specularLight;</pre>
  // Compute the emissive term
  float3 emissive = Ke;
                                                                   color.xyz = emissive + ambient + diffuse + specular;
  // Compute the ambient term
  float3 ambient = Ka * globalAmbient;
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```

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Shadows



Types of light sources

- Point, directional
- Area lights and generally shaped lights
 - Not considered here
 - Later: ray-tracing for such light sources

Problem statement

- A shadow algorithm for point and directional lights determines which scene points are
 - Visible from the light source (I.e. illuminated)
 - Invisible from the light source (I.e. in shadow)
- Thus: shadow casting is a visibility problem!



Types of Shadow Algorithms

Object Space

- Like object space visibility algorithms, the method computes in object space which polygon parts that are illuminated and which are in shadow
 - Individuyal parts are then drawn with different intensity
- Typically slow, O(n^2), not for dynamic scenes

Image Space

- Determine visibility per pixel in the final image
 - Sort of like depth buffer
 - Shadow maps
 - Shadow volumes

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Credits

 The following shadow mapping slides are taken from Mark Kilgard's OpenGL course at Siggraph 2002.

Shadow Mapping Concept (1)



Depth testing from the light's point-of-view

- Two pass algorithm
- First, render depth buffer from the light's point-of-view
 - The result is a "depth map" or "shadow map"
 - Essentially a 2D function indicating the depth of the closest pixels to the light
- This depth map is used in the second pass

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Shadow Mapping Concept (2)



Shadow determination with the depth map

- Second, render scene from the eye's point-ofview
- For each rasterized fragment
 - Determine fragment's XYZ position relative to the light
 - This light position should be setup to match the frustum used to create the depth map
 - Compare the depth value at light position XY in the depth map to fragment's light position Z

The Shadow Mapping Concept (3)

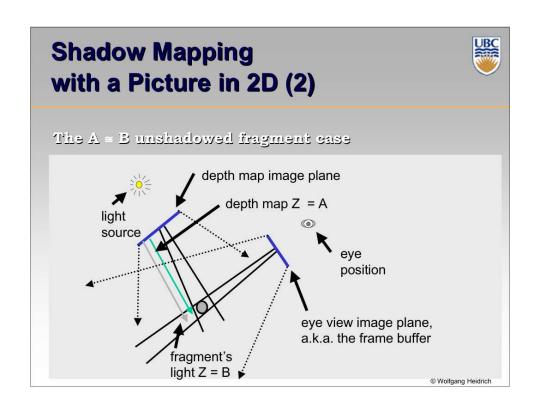


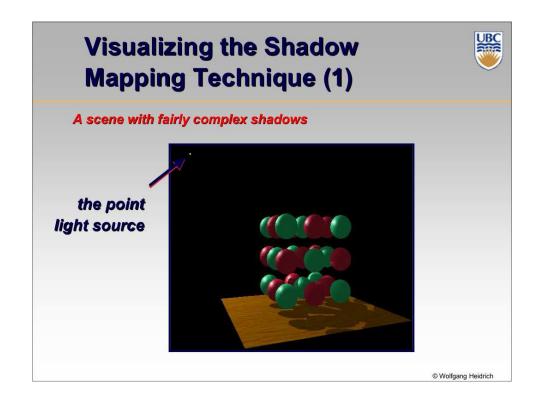
The Shadow Map Comparison

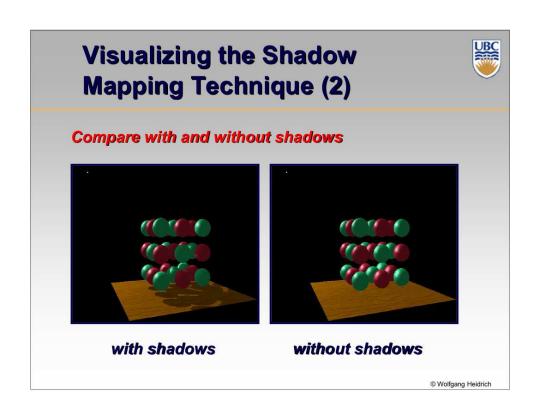
- Two values
 - A = Z value from depth map at fragment's light XY position
 - B = Z value of fragment's XYZ light position
- If B is greater than A, then there must be something closer to the light than the fragment
 - Then the fragment is shadowed
- If A and B are approximately equal, the fragment is lit

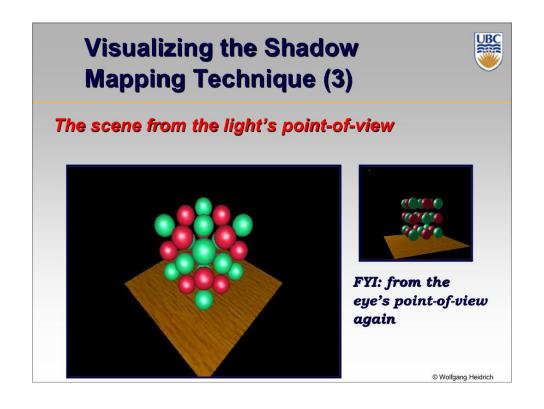
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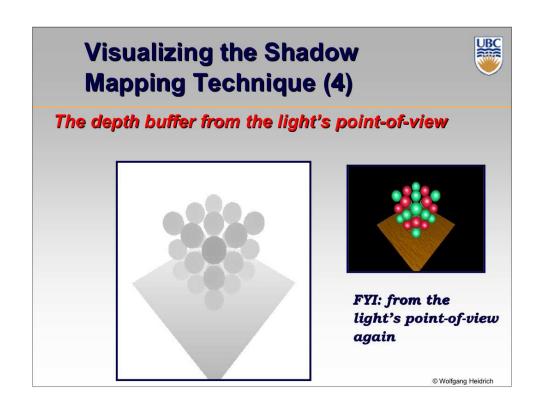
Shadow Mapping with a Picture in 2D (1) The A < B shadowed fragment case depth map image plane depth map Z = A light source eye position eye view image plane, a.k.a. the frame buffer fragment's light Z = B

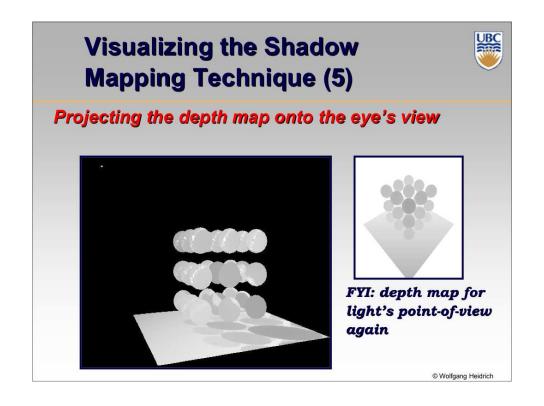


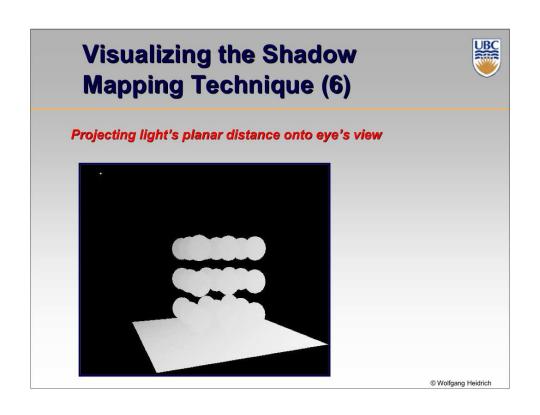


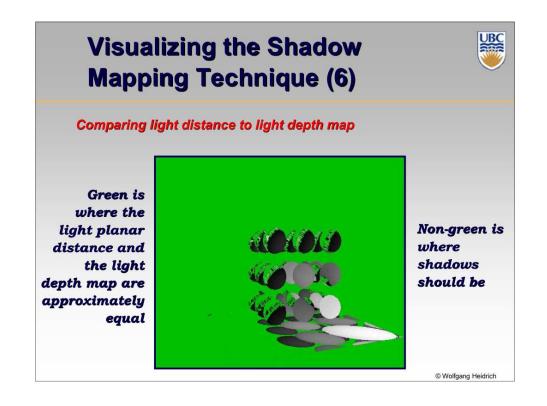


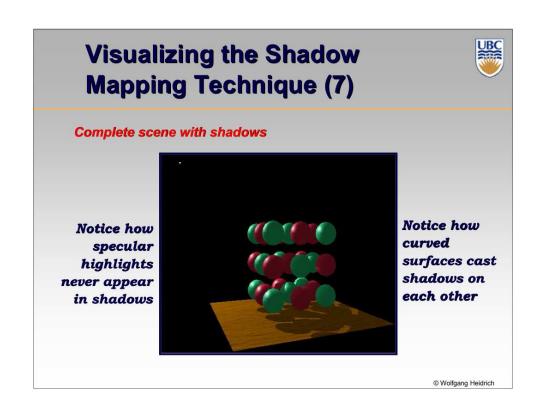


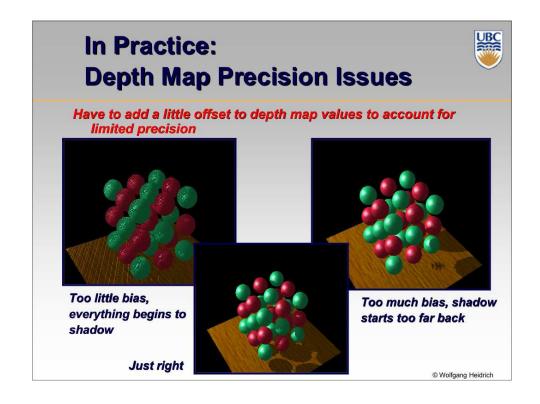












What is **Projective Texturing?**



An intuition for projective texturing

The slide projector analogy





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About Projective Texturing (1)



First, what is perspective-correct texturing?

- Normal 2D texture mapping uses (s, t) coordinates
- 2D perspective-correct texture mapping
 - Means (s, t) should be interpolated linearly in eye-space
 - So compute per-vertex s/w, t/w, and 1/w
 - Linearly interpolated these three parameters over polygon
 - Per-fragment compute s' = (s/w) / (1/w) and t' = (t/w) / (1/w)
 - Results in per-fragment perspective correct (s', t')

About Projective Texturing (2)



So what is projective texturing?

- Now consider homogeneous texture coordinates
 - (s, t, r, q) --> (s/q, t/q, r/q)
 - Similar to homogeneous clip coordinates where (x, y, z, w) = (x/w, y/w, z/w)
- Idea is to have (s/q, t/q, r/q) be projected per-fragment

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Back to the Shadow Mapping Discussion...



Assign light-space texture coordinates to polygon vertices

- Transform eye-space (x, y, z, w) coordinates to the light's view frustum (match how the light's depth map is generated)
- Further transform these coordinates to map directly into the light view's depth map
 - –Expressible as a projective transform
- (s/q, t/q) will map to light's depth map texture



Shadow Map Operation

Next Step:

- Compare depth map value to distance of fragment from light source
- Different GPU generations support different means of implementing this
 - Today's GPUs: pixel shader!
 - Earlier: special hardware for implmenting this feature (e.g. SGI), or just using alpha blending [Heidrich'99]

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Issues with Shadow Mapping (1)



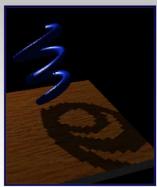
Not without its problems

- Prone to aliasing artifacts
 - "percentage closer" filtering helps this
 - normal color filtering does not work well
- Depth bias is not completely foolproof
- Requires extra shadow map rendering pass and texture loading
- Higher resolution shadow map reduces blockiness
 - but also increase texture copying expense

Hardware Shadow Map Filtering Example



GL_NEAREST: blocky GL_LINEAR: antialiased edges





Low shadow map resolution used to heightens filtering artifacts

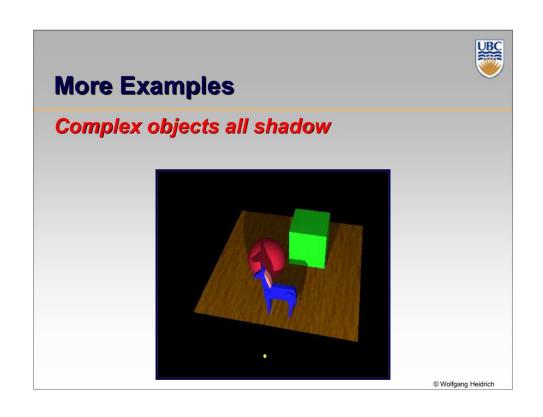
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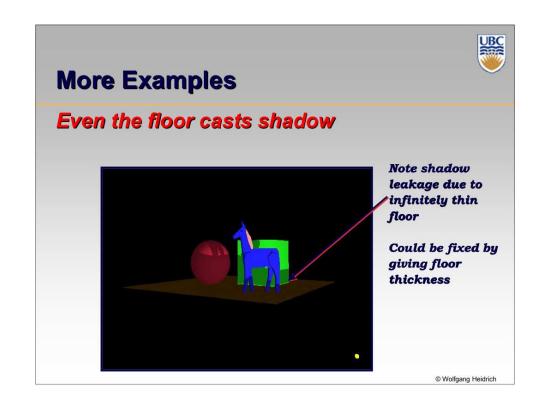
Issues with Shadow Mapping (2)



Not without its problems

- Shadows are limited to view frustums
 - could use six view frustums for omni-directional light
- Objects outside or crossing the near and far clip planes are not properly accounted for by shadowing
 - move near plane in as close as possible
 - but too close throws away valuable depth map precision when using a projective frustum

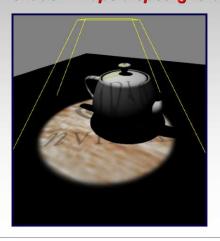




Combining Projective Texturing for Spotlights



Use a spotlight-style projected texture to give shadow maps a spotlight falloff



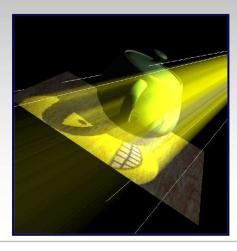


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Combining Shadows with Atmospherics



Shadows in a dusty room



Simulate atmospheric effects such as suspended dust

- 1) Construct shadow map
- 2) Draw scene with shadow map
- Modulate projected texture image with projected shadow map
- Blend back-to-front shadowed slicing planes also modulated by projected texture image

Credit: Cass Everitt



Shadow Maps

Approach for shadows from point light sources

- Surface point is in shadow if it is not visible from the light source
- Use depth buffer to test visibility:
 - Render scene from the point light source
 - Store resulting depth buffer as texture map
 - For every fragment generated while rendering from the camera position, project the fragment into the depth texture taken from the camera, and check if it passes the depth test.

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Shadow Volumes

Use new buffer: stencil buffer

- Just another channel of the framebuffer
- Can count how often a pixel is drawn

Algorithm (1):

- Generate silhouette polygons for all objects
 - Polygons starting at silhouette edges of object
 - Extending away from light source towards infinity
 - These can be computed in vertex programs



Shadow Volumes

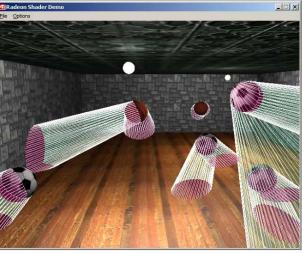


Image by ATI

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Shadow Volumes

Algorithm (2):

- Render all original geometry into the depth buffer
 - I.e. do not draw any colors (or only draw ambient illumination term)
- Render <u>front-facing</u> silhouette polygons while <u>incrementing</u> the stencil buffer for every rendered fragment
- Render <u>back-facing</u> silhouette polygons while <u>decrementing</u> the stencil buffer for every rendered fragment
- Draw illuminated geometry where the stencil buffer is 0, shadow elsewhere



Shadow Volumes



Discussion:

- Object space method therefore no precision issues
- Lots of large polygons: can be slow
 - High geometry count
 - Large number of pixels rendered

