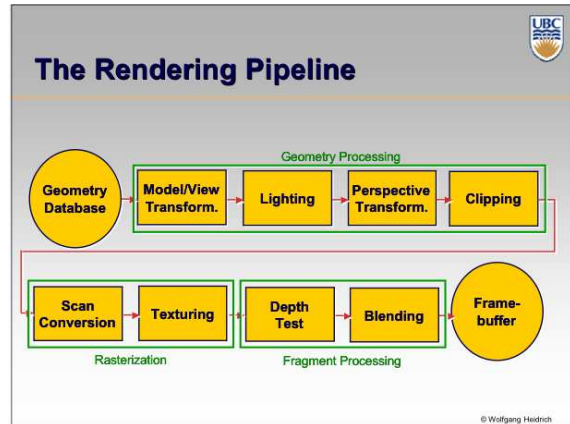



## The Rendering Pipeline – A Second Look

**Part 1: Geometry Processing**

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## Geometry Database

**Needs to represent models for**

- Geometric primitives
- Relations between different primitives (transformations)
- Object materials
- Light sources
- Camera

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## Geometric Primitives

**Different philosophies:**

- Collections of complex shapes
  - Spheres, cones, cylinders, tori, ...
- One simple type of geometric primitive
  - Triangles or triangle meshes
- Small set of complex primitives with adjustable parameters
  - E.g. "all polynomials of degree 2"
  - Splines, NURBS (details in CPSC 424)
  - Fractals

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## Geometric Primitives

**Mathematical representations:**

- Explicit functions
- Parametric functions
- Implicit functions

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## Explicit Functions

**Curves:**

- $y$  is a function of  $x$ :  $y := \sin(x)$
- Only works in 2D

**Surfaces:**

- $z$  is a function of  $x$  and  $y$ :  $z := \sin(x) + \cos(y)$
- Cannot define arbitrary shapes in 3D

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**Parametric Functions**

**Curves:**

- 2D: x and y are functions of a parameter value t
- 3D: x, y, and z are functions of a parameter value t

$$C(t) := \begin{pmatrix} \cos(t) \\ \sin(t) \\ t \end{pmatrix}$$

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**Parametric Functions**

**Surfaces:**

- Surface S is defined as a function of parameter values s, t
- Names of parameters can be different to match intuition:

$$S(\phi, \theta) := \begin{pmatrix} \cos(\phi) \cos(\theta) \\ \sin(\phi) \cos(\theta) \\ \sin(\theta) \end{pmatrix}$$

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**Geometry Database**

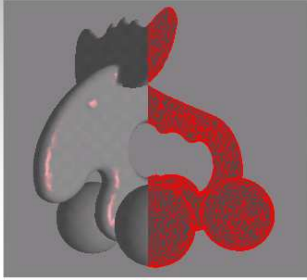
**Implicit Surfaces:**

- Surface is defined implicitly via the roots of a function
- E.g:  $S(x, y, z) : x^2 + y^2 + z^2 - 1 = 0$

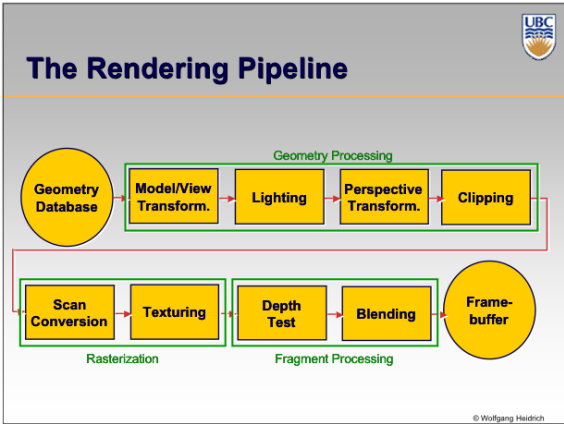
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**Geometry Database**

**Triangles and Triangle Meshes:**



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**Modeling and Viewing Transformation**

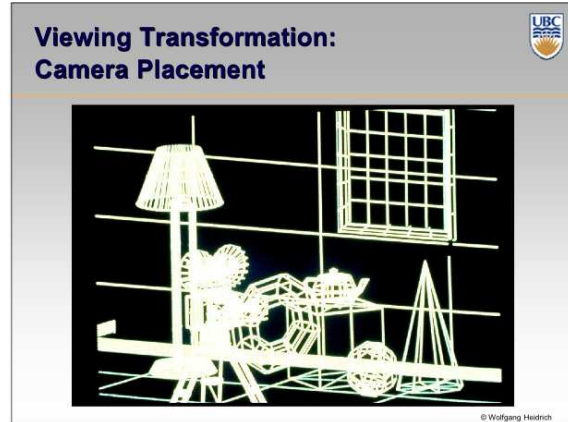
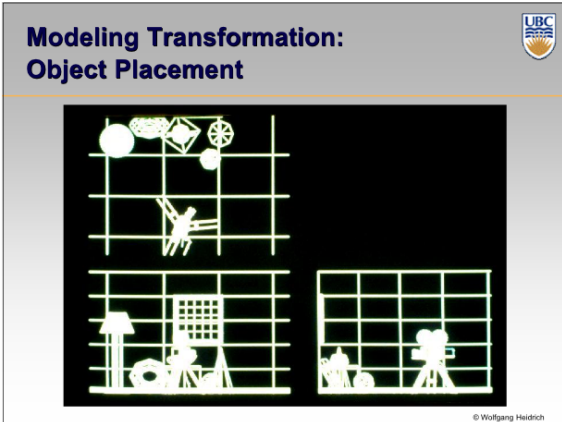
**Modeling transformation:**

- Map points from object coordinate system to world coordinate system
- Same as placing objects

**Viewing transformation:**

- Map points from world coordinate system to camera (or eye) coordinate system
- Same as placing camera

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### Modeling and Viewing Transformation

**Types of transformations:**

- Rotations, scaling, shearing

- Translations

- Other transformations (not handled by rendering pipeline):
  - Freeform deformation

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### Modeling and Viewing Transformation

**Linear transformations**

- Rotations, scaling, shearing
- Can be expressed as a 3x3 matrix
- E.g. rotation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

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### Modeling and Viewing Transformation

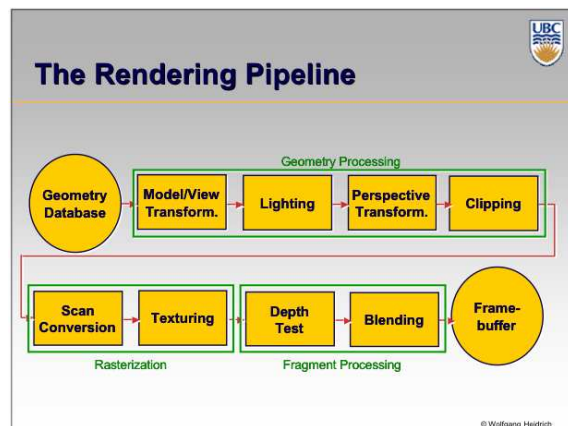
**Affine transformations**

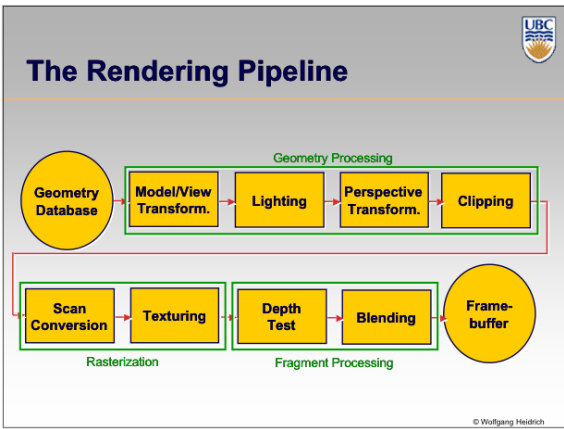
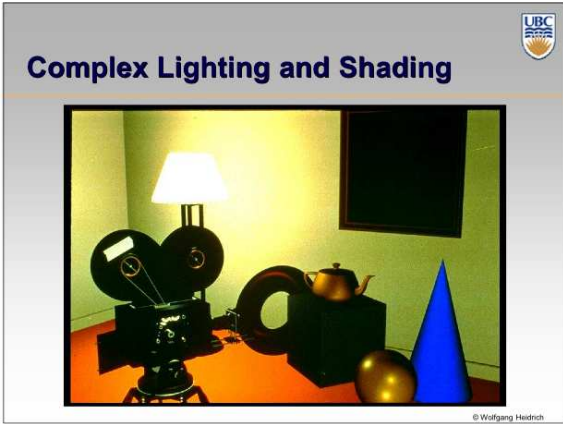
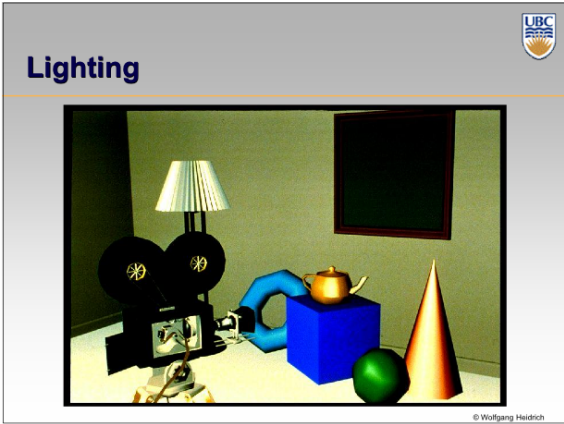
- Linear transformations + translations
- Can be expressed as a 3x3 matrix + 3 vector
- E.g. rotation + translation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \\ t_z \end{pmatrix}$$

- Another representation: 4x4 homogeneous matrix

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## Perspective Transformation

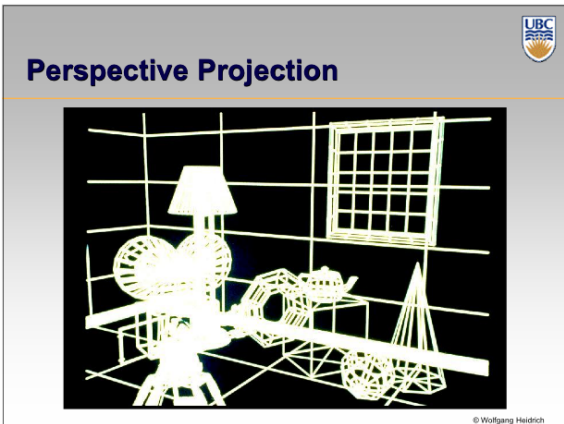
**Purpose:**

- Project 3D geometry onto a 2D image plane
- Simulates a camera

**Camera model:**

- Pinhole camera
- Other, more complex camera models also exist in computer graphics, but are less common
  - Thin lens cameras
  - Full simulation of lens geometry

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**Perspective Transformation**

*Pinhole Camera*



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**Pinhole Camera - Camera Obscura**




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**Perspective Transformation**

*In computer graphics:*

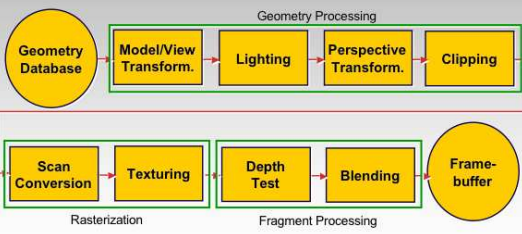
- Image plane is conceptually *in front of* the center of projection



- Perspective transformations belong to a class of operations that are called *projective transformations*
- Linear and affine transformations also belong to this class
- All projective transformations can be expressed as  $4 \times 4$  matrix operations

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**The Rendering Pipeline**



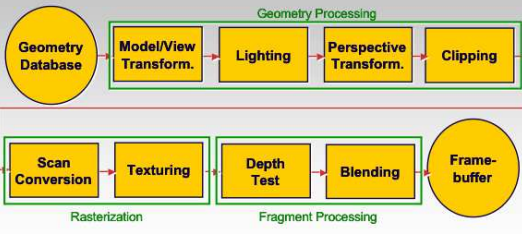
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**The Rendering Pipeline – A Second Look**

*Part 2: Rasterization & Fragment Processing*

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**The Rendering Pipeline**



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### Scan Conversion

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### Scan Conversion

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### Scan Conversion

**Problem:**

- Line is infinitely thin, but image has finite resolution
- Results in steps rather than a smooth line
  - Jaggies
  - Aliasing
- One of the fundamental problems in computer graphics

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### Scan Conversion

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### Scan Conversion

**Color interpolation**

- Linearly interpolate per-pixel color from vertex color values
- Treat every channel of RGB color separately

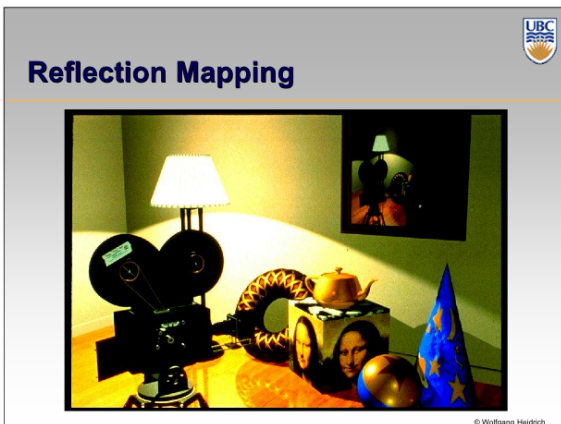
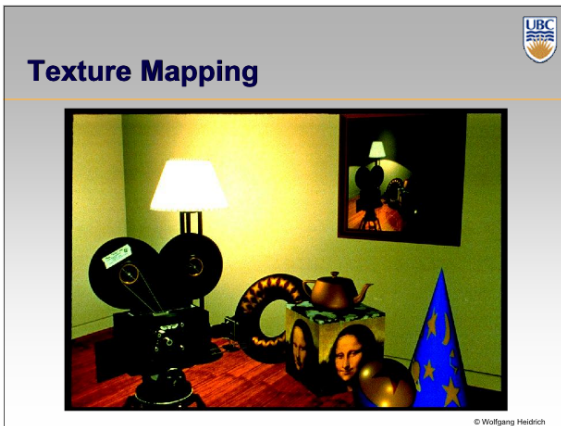
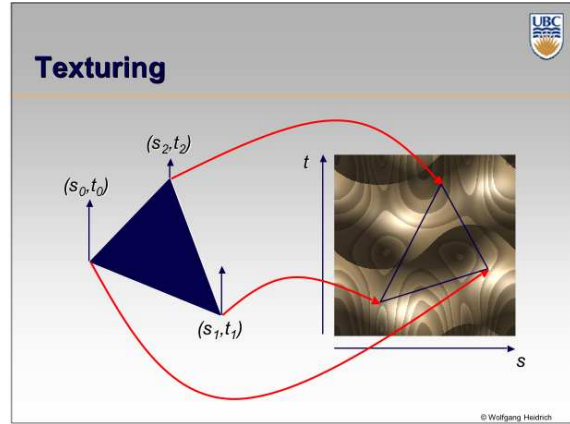
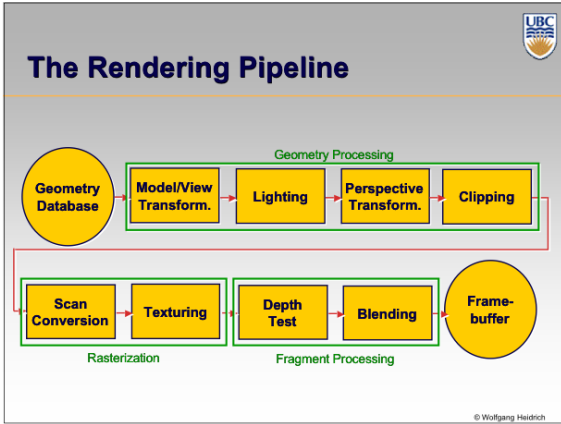
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### Scan Conversion

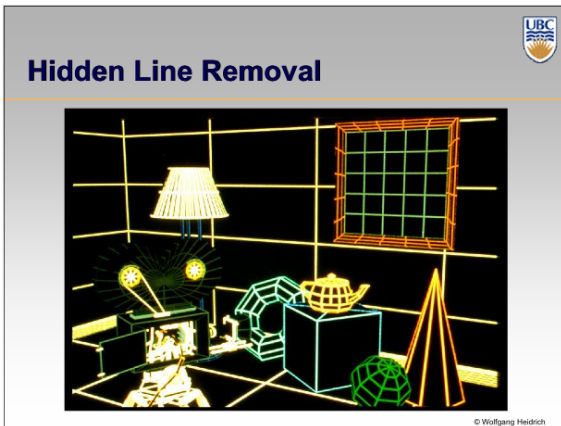
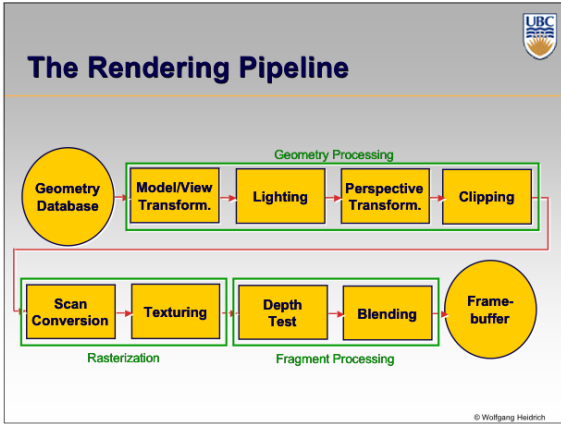
**Color interpolation**

- Example:

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- ## Texturing
- Issues:**
- How to map pixel from texture (*texels*) to screen pixels
    - Texture can appear widely distorted in rendering
    - Magnification / minification of textures
  - Filtering of textures
  - Preventing aliasing (anti-aliasing)
- © Wolfgang Heidrich



### Depth Test / Hidden Surface Removal

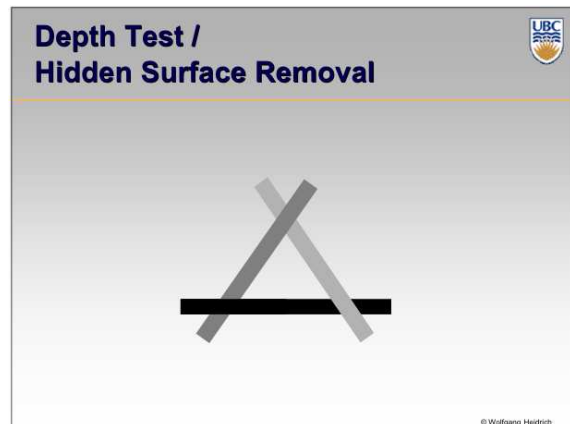
**Remove invisible geometry**

- Parts that are hidden behind other geometry

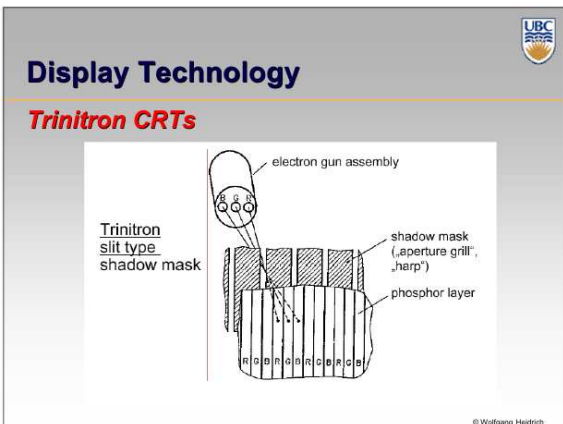
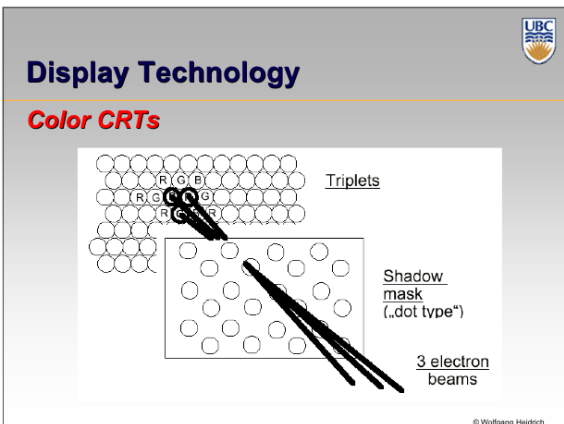
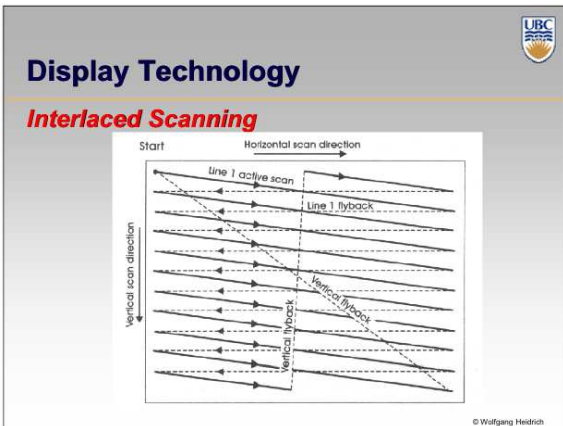
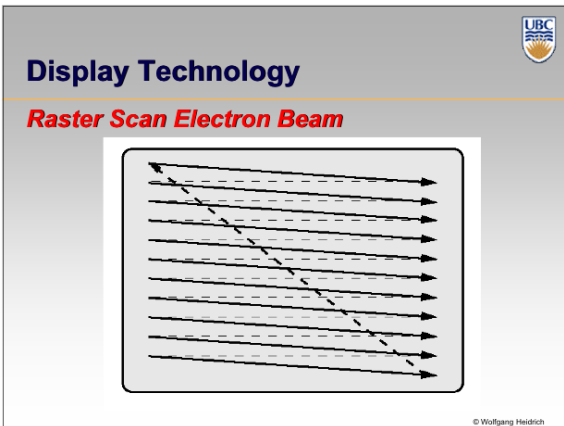
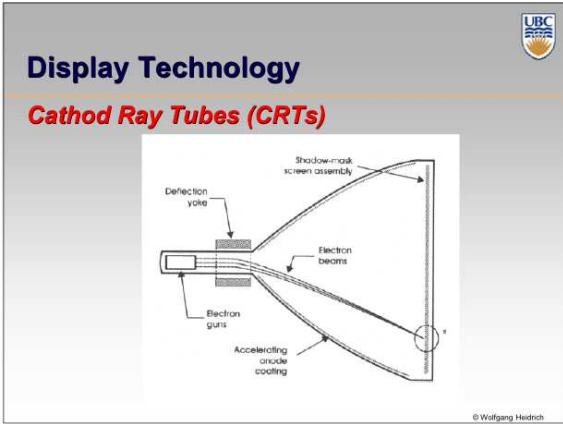
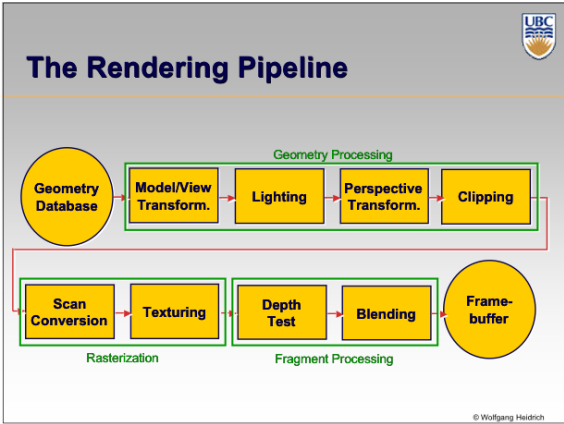
**Possible Implementations:**

- Per-fragment decision
  - Depth buffer
- Object space decision
  - Clipping polygons against each other
  - Sorting polygons by distance from camera

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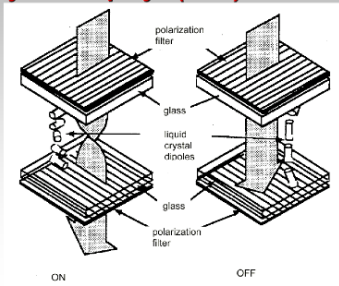




## Display Technology



### Liquid Crystal Displays (LCD)



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## Coming Up...



### Thursday, Sep 13:

- Geometric Transformations (Affine)

### Tuesday, Sep 18:

- Geometric Transformations (Perspective)

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