

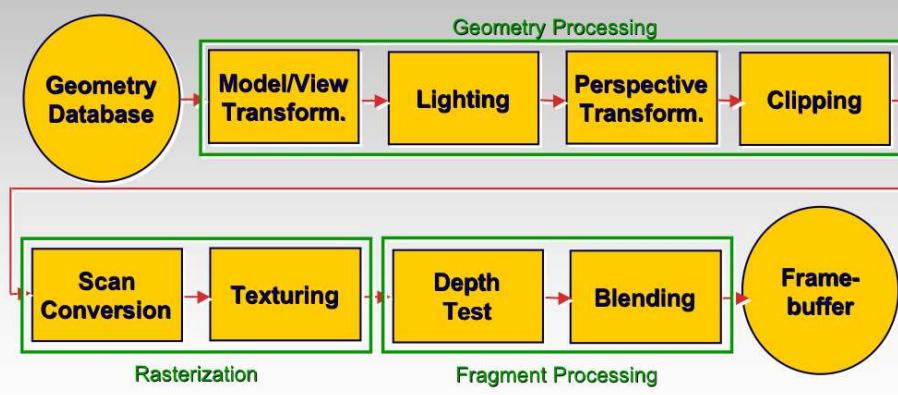


The Rendering Pipeline – A Second Look

Part 1: Geometry Processing

© Wolfgang Heidrich

The Rendering Pipeline



© Wolfgang Heidrich



Geometry Database

Needs to represent models for

- Geometric primitives
- Relations between different primitives (transformations)
- Object materials
- Light sources
- Camera

© Wolfgang Heidrich



Geometric Primitives

Different philosophies:

- Collections of complex shapes
 - *Spheres, cones, cylinders, tori, ...*
- One simple type of geometric primitive
 - *Triangles or triangle meshes*
- Small set of complex primitives with adjustable parameters
 - *E.g. “all polynomials of degree 2”*
 - *Splines, NURBS (details in CPSC 424)*
 - *Fractals*

© Wolfgang Heidrich



Geometric Primitives

Mathematical representations:

- Explicit functions
- Parametric functions
- Implicit functions

© Wolfgang Heidrich



Explicit Functions

Curves:

- y is a function of x : $y := \sin(x)$
- Only works in 2D

Surfaces:

- z is a function of x and y : $z := \sin(x) + \cos(y)$
- Cannot define arbitrary shapes in 3D

© Wolfgang Heidrich



Parametric Functions

Curves:

- 2D: x and y are functions of a parameter value t
- 3D: x , y , and z are functions of a parameter value t

$$C(t) := \begin{pmatrix} \cos(t) \\ \sin(t) \\ t \end{pmatrix}$$

© Wolfgang Heidrich



Parametric Functions

Surfaces:

- Surface S is defined as a function of *parameter values* s, t
- *Names of parameters can be different to match intuition:*

$$S(\phi, \theta) := \begin{pmatrix} \cos(\phi)\cos(\theta) \\ \sin(\phi)\cos(\theta) \\ \sin(\theta) \end{pmatrix}$$

© Wolfgang Heidrich



Geometry Database

Implicit Surfaces:

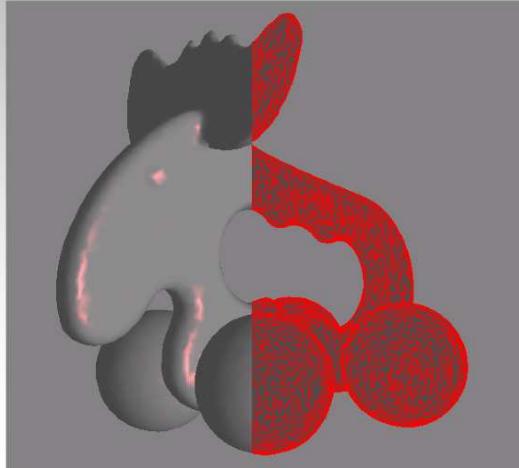
- Surface is defined implicitly via the roots of a function
- E.g:
$$S(x, y, z) : x^2 + y^2 + z^2 - 1 = 0$$

© Wolfgang Heidrich



Geometry Database

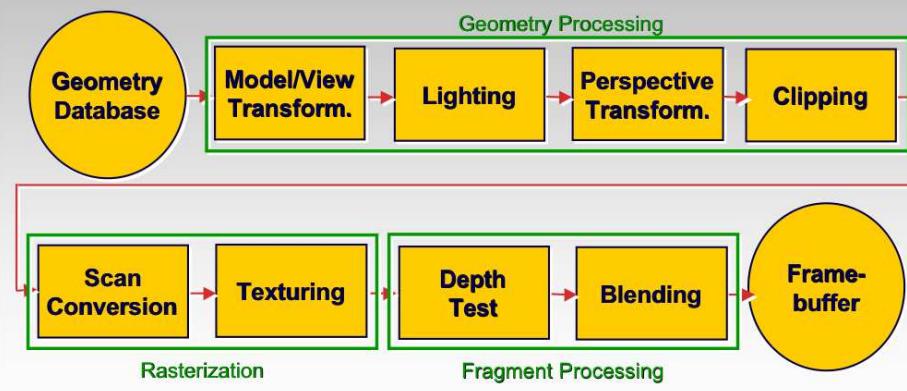
Triangles and Triangle Meshes:



© Wolfgang Heidrich



The Rendering Pipeline



© Wolfgang Heidrich



Modeling and Viewing Transformation

Modeling transformation:

- Map points from *object coordinate system* to *world coordinate system*
- *Same as placing objects*

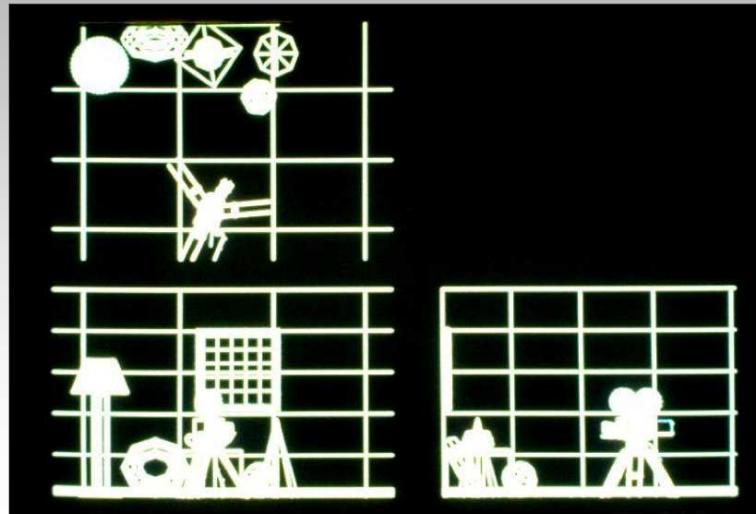
Viewing transformation:

- Map points from *world coordinate system* to *camera (or eye) coordinate system*
- *Same as placing camera*

© Wolfgang Heidrich



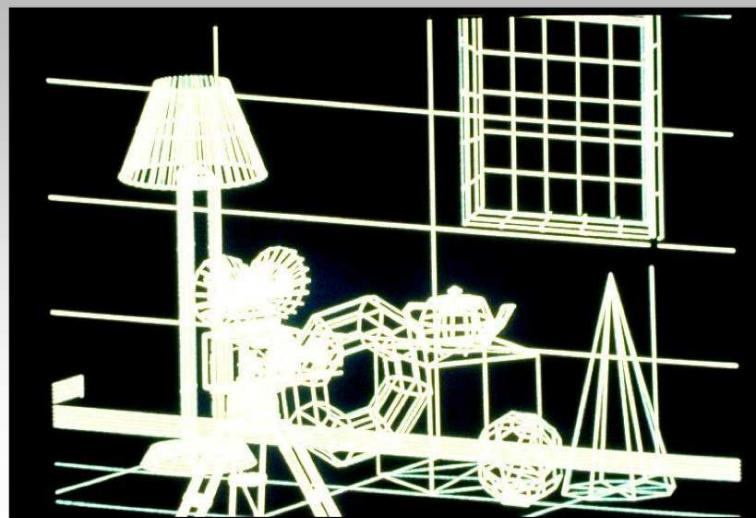
Modeling Transformation: Object Placement



© Wolfgang Heidrich



Viewing Transformation: Camera Placement



© Wolfgang Heidrich



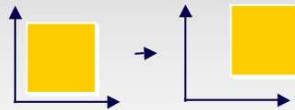
Modeling and Viewing Transformation

Types of transformations:

- Rotations, scaling, shearing



- Translations



- Other transformations (not handled by rendering pipeline):

- Freeform deformation



© Wolfgang Heidrich

Modeling and Viewing Transformation



Linear transformations

- Rotations, scaling, shearing
- Can be expressed as a 3×3 matrix
- E.g. rotation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

© Wolfgang Heidrich

Modeling and Viewing Transformation



Affine transformations

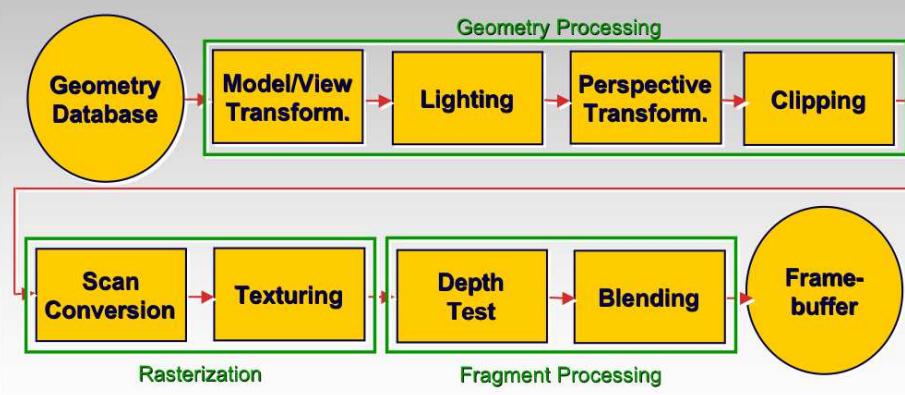
- Linear transformations + translations
- Can be expressed as a 3×3 matrix + 3 vector
- E.g. rotation + translation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \\ t_z \end{pmatrix}$$

- Another representation: *4x4 homogeneous matrix*

© Wolfgang Heidrich

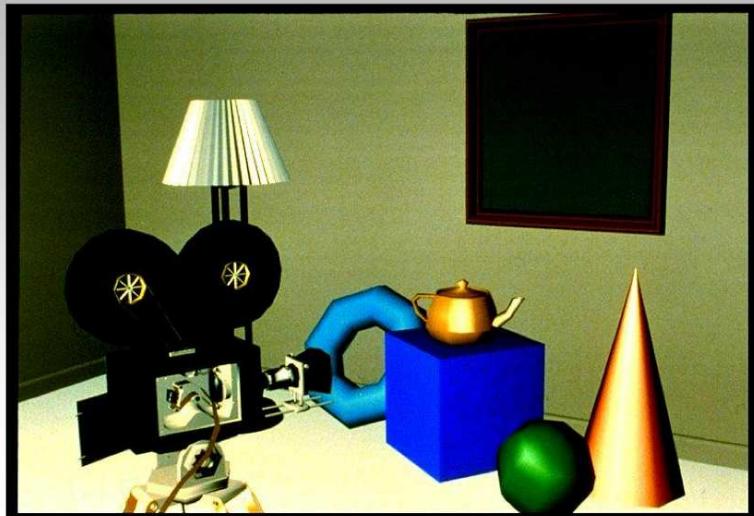
The Rendering Pipeline



© Wolfgang Heidrich



Lighting



© Wolfgang Heidrich



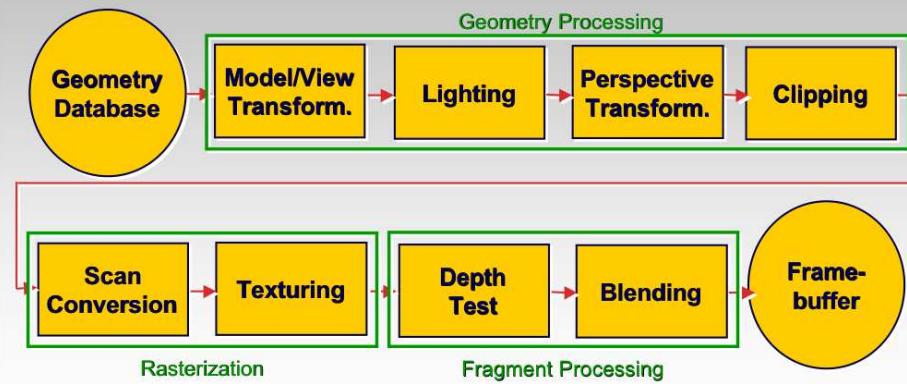
Complex Lighting and Shading



© Wolfgang Heidrich



The Rendering Pipeline



© Wolfgang Heidrich



Perspective Transformation

Purpose:

- Project 3D geometry onto a 2D image plane
- Simulates a camera

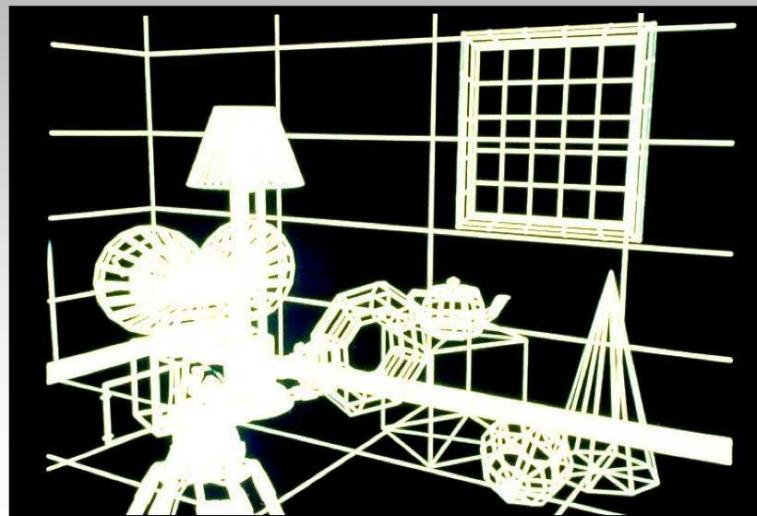
Camera model:

- Pinhole camera
- Other, more complex camera models also exist in computer graphics, but are less common
 - *Thin lens cameras*
 - *Full simulation of lens geometry*

© Wolfgang Heidrich



Perspective Projection



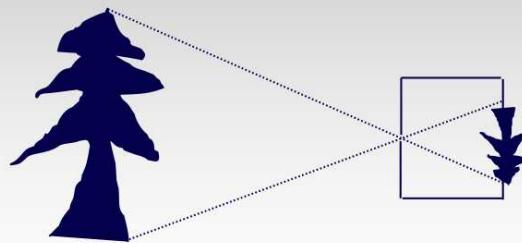
© Wolfgang Heidrich



Perspective Transformation

Pinhole Camera:

- Light shining through a tiny hole into a dark room yields upside-down image on wall



© Wolfgang Heidrich



Perspective Transformation

Pinhole Camera



© Wolfgang Heidrich



Pinhole Camera - Camera Obscura



© Wolfgang Heidrich



Perspective Transformation

In computer graphics:

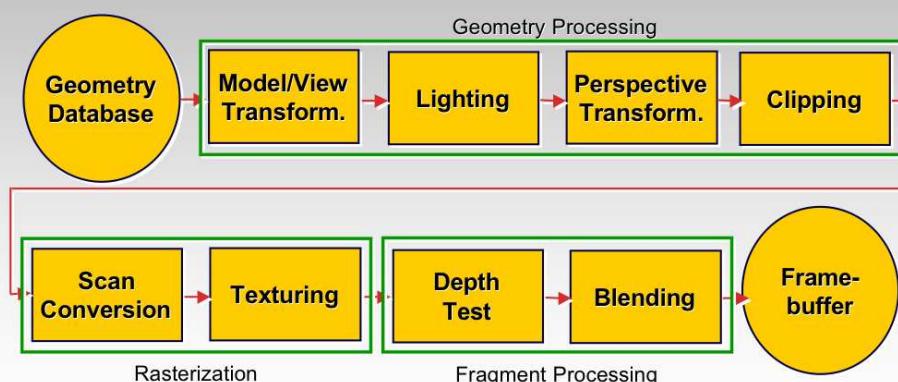
- Image plane is conceptually *in front* of the center of projection
- Perspective transformations belong to a class of operations that are called *projective transformations*
- Linear and affine transformations also belong to this class
- All projective transformations can be expressed as 4×4 matrix operations



© Wolfgang Heidrich



The Rendering Pipeline



© Wolfgang Heidrich

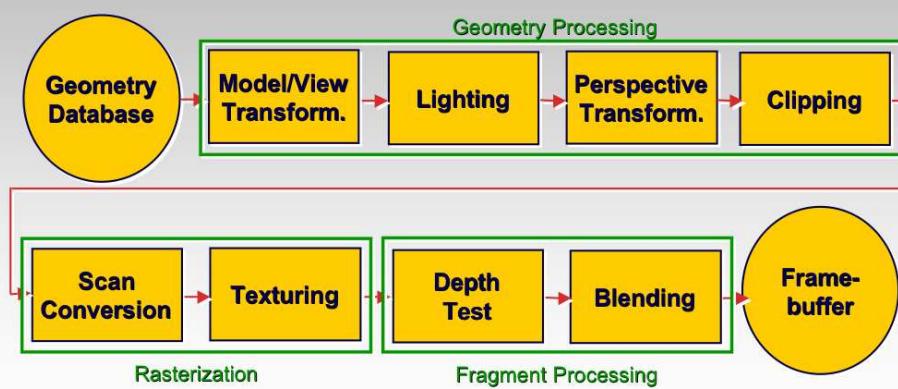


The Rendering Pipeline – A Second Look

Part 2: Rasterization & Fragment Processing

© Wolfgang Heidrich

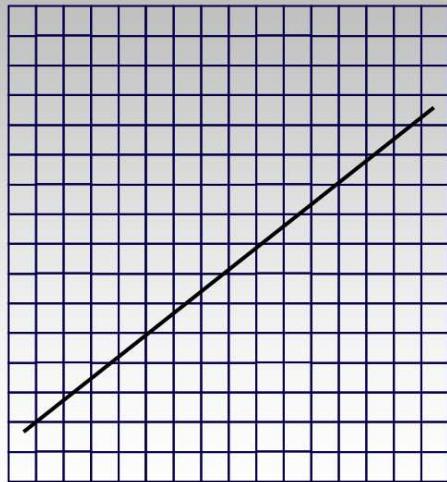
The Rendering Pipeline



© Wolfgang Heidrich



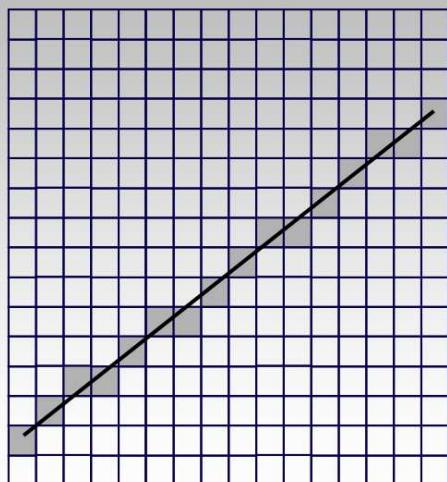
Scan Conversion



© Wolfgang Heidrich



Scan Conversion



© Wolfgang Heidrich



Scan Conversion

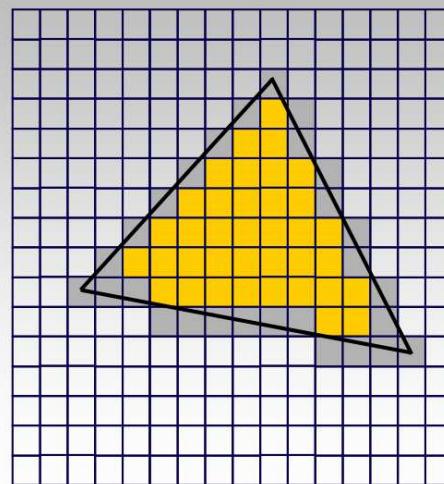
Problem:

- Line is infinitely thin, but image has finite resolution
- Results in steps rather than a smooth line
 - *Jaggies*
 - *Aliasing*
- One of the fundamental problems in computer graphics

© Wolfgang Heidrich



Scan Conversion



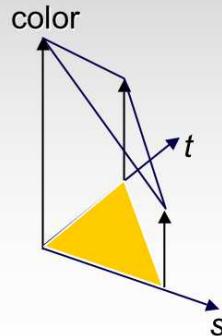
© Wolfgang Heidrich



Scan Conversion

Color interpolation

- Linearly interpolate per-pixel color from vertex color values
- Treat every channel of RGB color separately

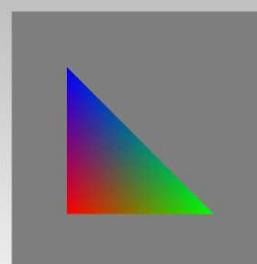
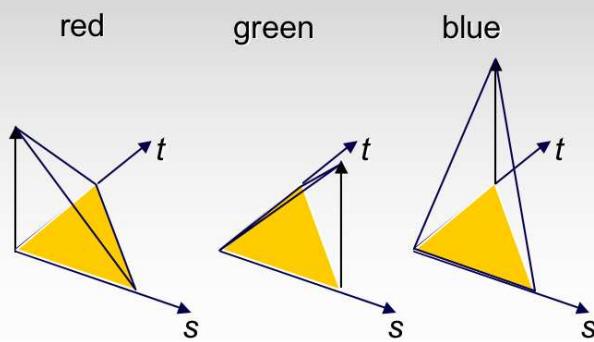


© Wolfgang Heidrich

Scan Conversion

Color interpolation

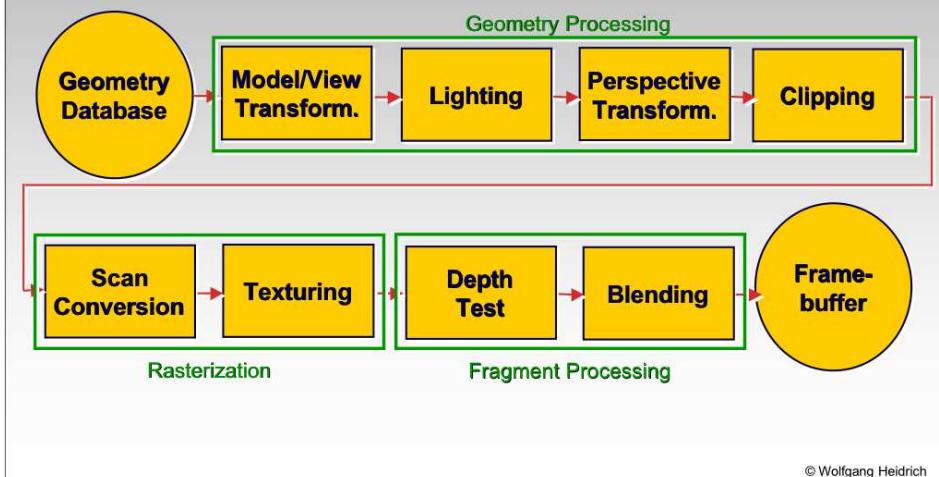
- Example:



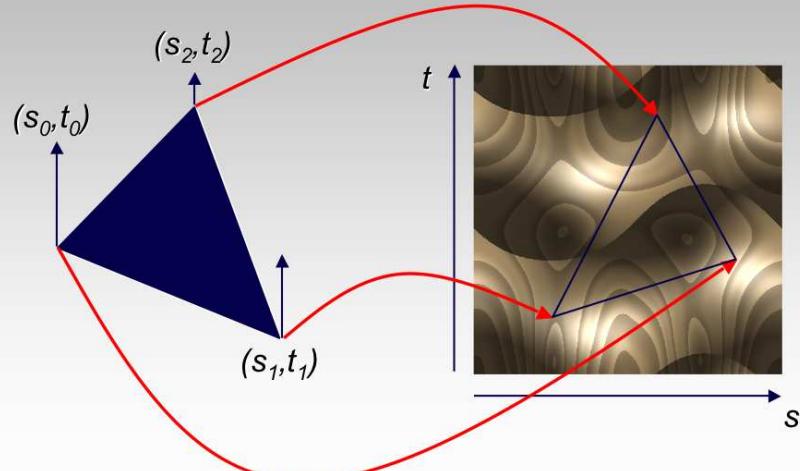
© Wolfgang Heidrich



The Rendering Pipeline



Texturing





Texture Mapping



© Wolfgang Heidrich

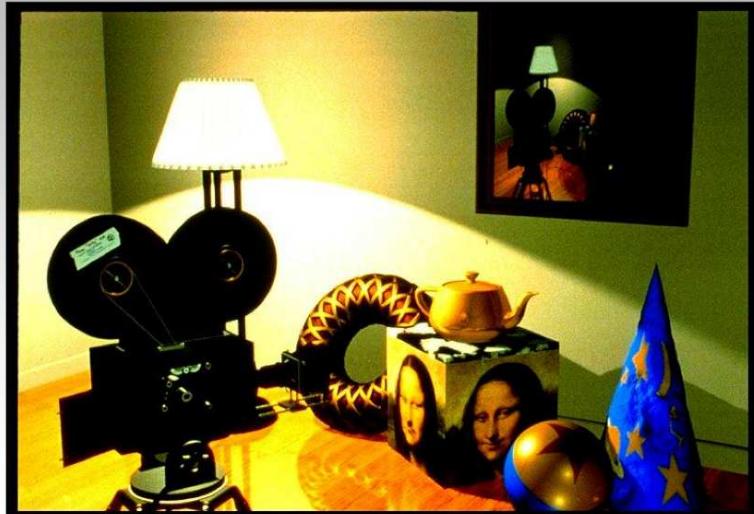


Displacement Mapping



© Wolfgang Heidrich

Reflection Mapping



© Wolfgang Heidrich

Texturing

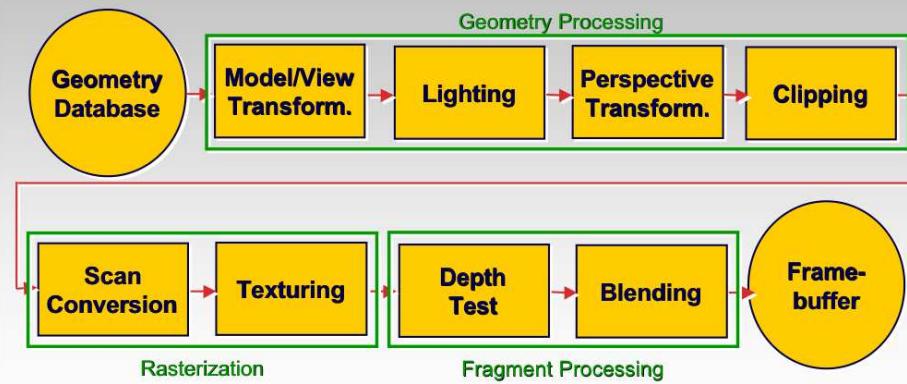
Issues:

- How to map pixel from texture (*texels*) to screen pixels
 - *Texture can appear widely distorted in rendering*
 - *Magnification / minification of textures*
- Filtering of textures
- Preventing aliasing (anti-aliasing)

© Wolfgang Heidrich



The Rendering Pipeline



© Wolfgang Heidrich



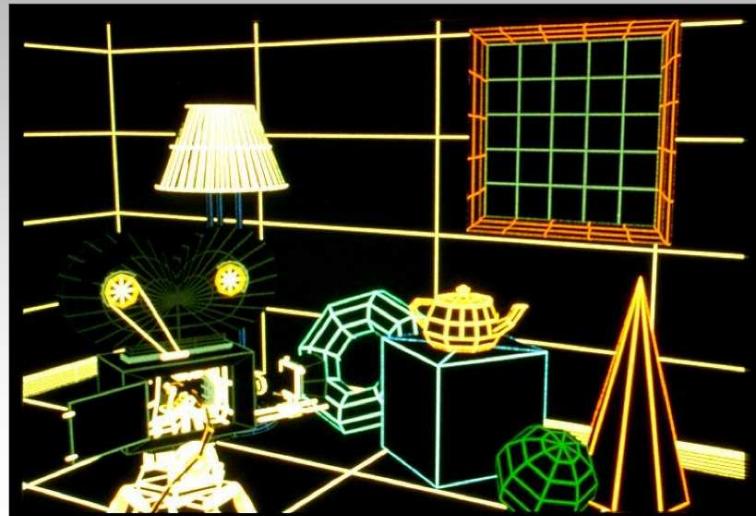
Without Hidden Line Removal



© Wolfgang Heidrich



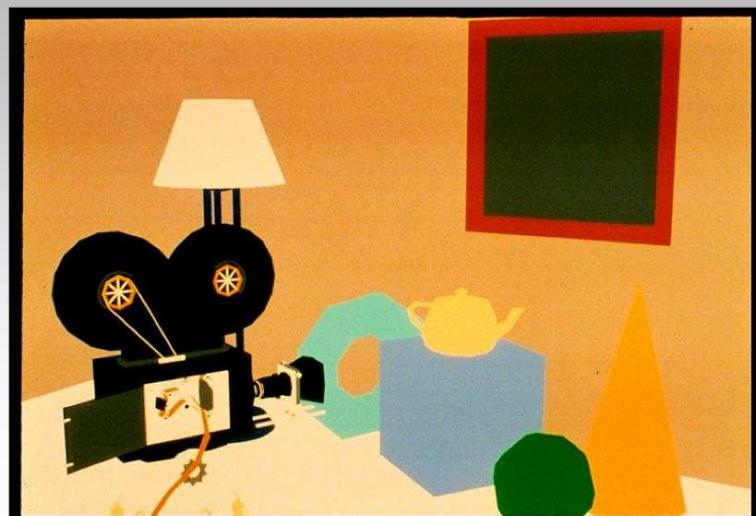
Hidden Line Removal



© Wolfgang Heidrich



Hidden Surface Removal



© Wolfgang Heidrich



Depth Test / Hidden Surface Removal

Remove *invisible geometry*

- Parts that are hidden behind other geometry

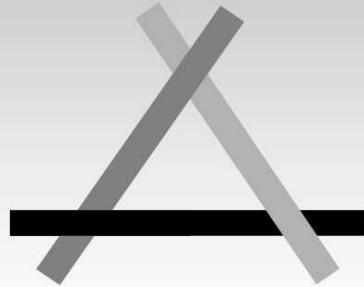
Possible Implementations:

- Per-fragment decision
 - Depth buffer
- Object space decision
 - Clipping polygons against each other
 - Sorting polygons by distance from camera

© Wolfgang Heidrich



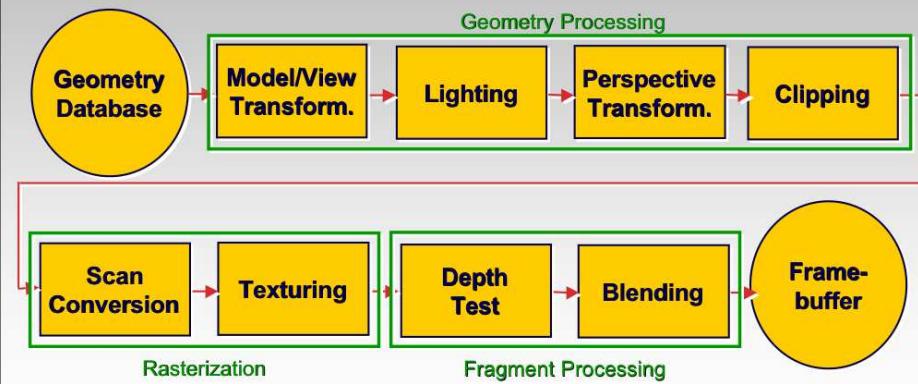
Depth Test / Hidden Surface Removal



© Wolfgang Heidrich



The Rendering Pipeline

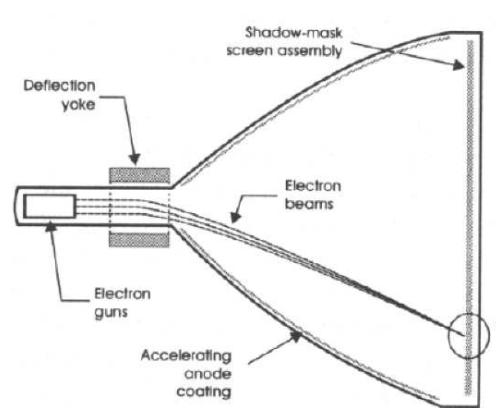


© Wolfgang Heidrich



Display Technology

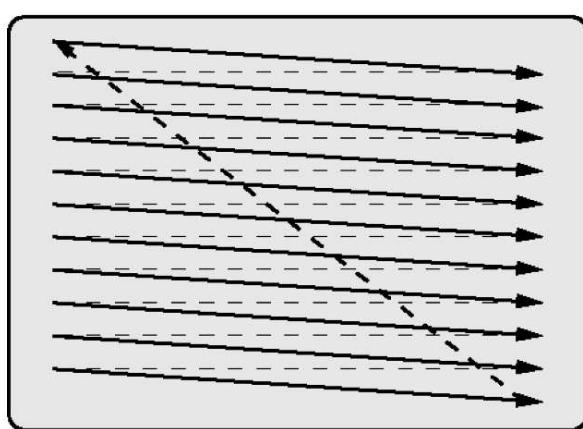
Cathod Ray Tubes (CRTs)



© Wolfgang Heidrich

Display Technology

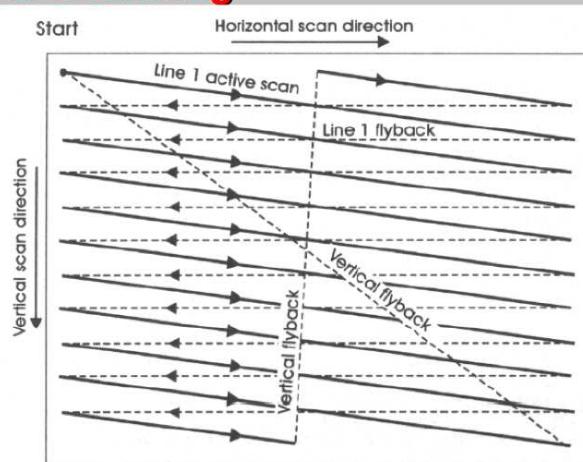
Raster Scan Electron Beam



© Wolfgang Heidrich

Display Technology

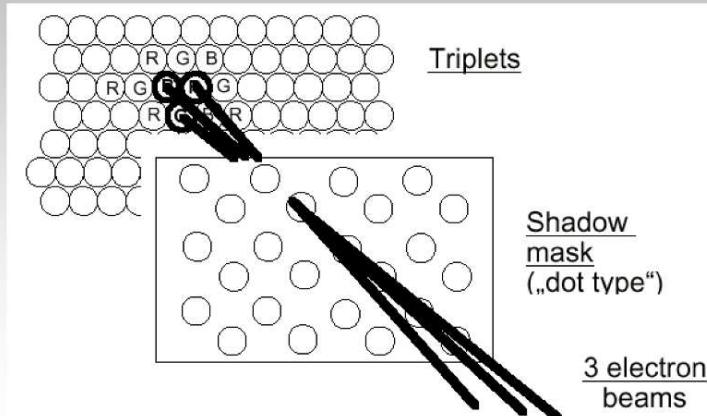
Interlaced Scanning



© Wolfgang Heidrich

Display Technology

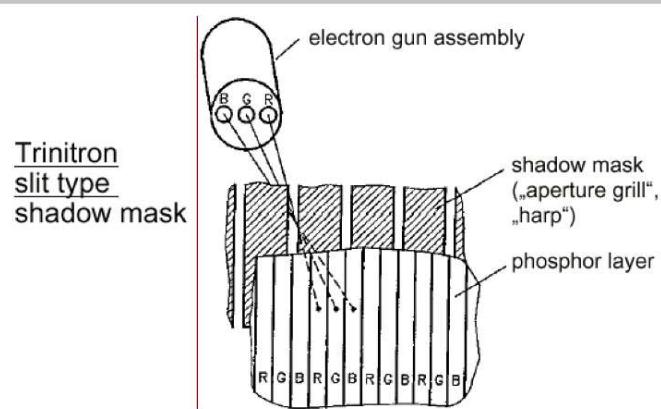
Color CRTs



© Wolfgang Heidrich

Display Technology

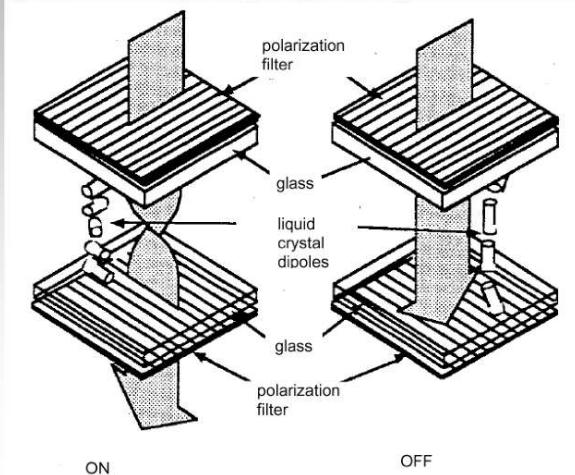
Trinitron CRTs



© Wolfgang Heidrich

Display Technology

Liquid Crystal Displays (LCD)



© Wolfgang Heidrich

Coming Up...

Thursday, Sep 13:

- Geometric Transformations (Affine)

Tuesday, Sep 18:

- Geometric Transformations (Perspective)

© Wolfgang Heidrich