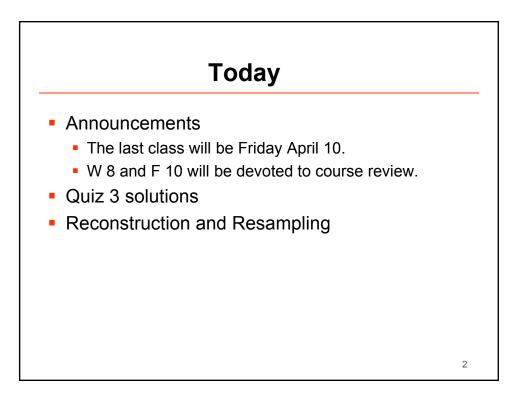
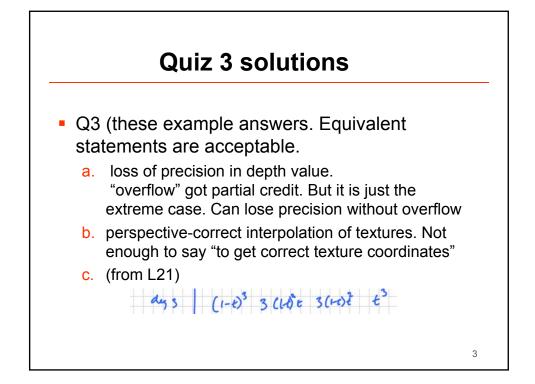
Reconstruction Q3 solution discussion

Dinesh K. Pai

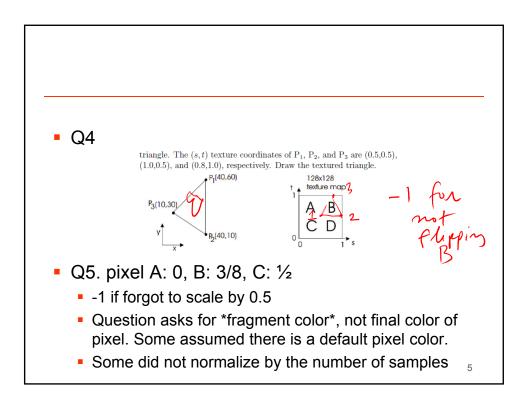
Textbook Chapter 18

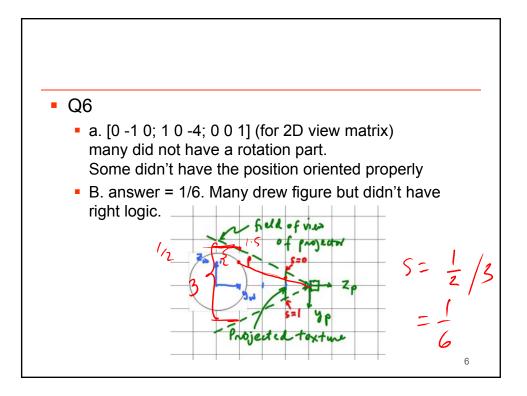
Several slides courtesy of M. Kim



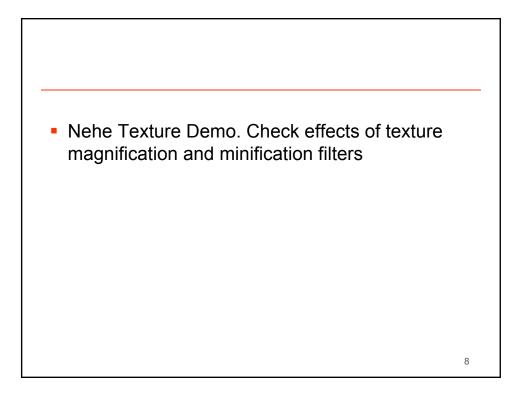


• Q3 continued • d. from L28, the viewport matrix: $ \begin{bmatrix} x_{w} \\ y_{w} \\ z_{w} \\ 1 \end{bmatrix} = \begin{bmatrix} W/2 & 0 & 0 & (W-1)/2 \\ 0 & H/2 & 0 & (H-1)/2 \\ 0 & 0 & 1/2 & 1/2 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{n} \\ y_{n} \\ z_{n} \\ 1 \end{bmatrix} $
substitute W=512 H=256 (Ok if you exchanged W and H)
 e. because (Answer given in class when describing A4)
4



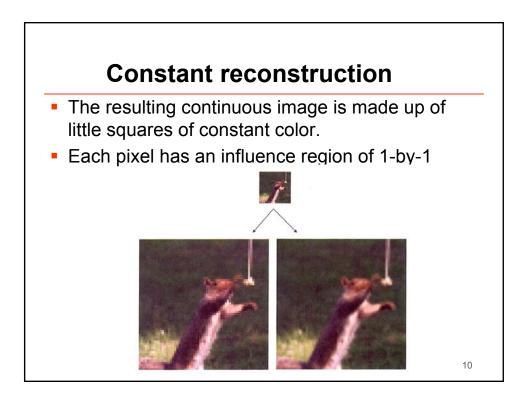


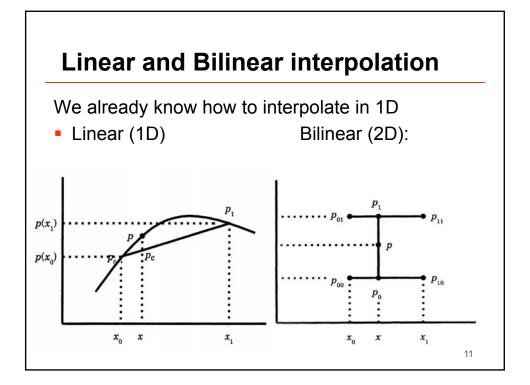


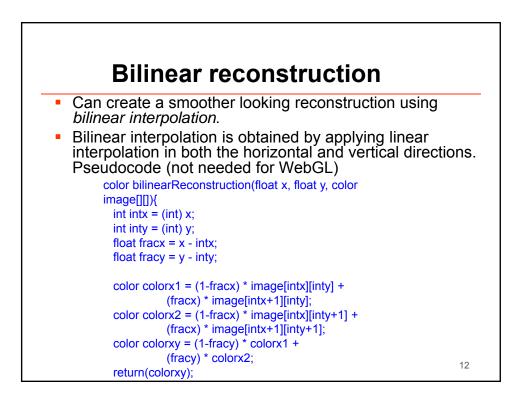




- Given a discrete image l[i][j], how do we create a continuous image l(x,y)?
- Is central to resize images and to texture mapping.
 - How to get a texture colors that fall in between texels.
- This process is called *reconstruction*.
- We already know the key idea, from L20-L21: Interpolation! So we will go over this quickly.







Bilinear properties

- At integer coordinates, we have *I(x,y)*=*I*[i][j]; the reconstructed continuous image *I* agrees with the discrete image *I*. => Interpolation
- In between integer coordinates, the color values are blended continuously.
- Each pixel influences, to a varying degree, each point within a 2-by-2 square region of the continuous image. => Local Support
- The horizontal/vertical ordering is irrelevant.
- Color over a square is bilinear function of (x,y).