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Recent example of using depth and compositing

- Depth cameras are now becoming available in mobile phones. Can use with compositing
- See <u>http://www.engadget.com/2014/03/25/htc-announces-the-new-one/</u> video around 0:50









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- Suppose we start with a texture image (discrete) T[k][I] and apply some 2D warp to this image to obtain an output image I[i][j].
- Reconstruct a continuous texture $T(x_t, y_t)$ using a set of basis functions $B_{k,l}(x_t, y_t)$.
- Apply the geometric wrap (at the view point) to the continuous image.
- Integrate against a set of filters $F_{k,l}(x_w, y_w)$ (a box filter) to obtain the discrete output image.

 $\begin{aligned} & (\text{Textbook description}) \\ & \text{Resampling equation} \\ \text{Section 1} & \text{Section 2} \\ \text{Section 2} & \text{Section 2} \\ & \text{Section 2} \\ & \text{Section 2} & \text{Section$





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- We tell OpenGL to do this using the call gITexParameteri(GL_TEXTURE_2D, GL_TEXTURE_MAG_FILTER, GL_LINEAR).
- For a single texture lookup in a fragment shader, the hardware needs to fetch 4 texture pixels and blend them appropriately.











