

# Coverage, compositing and the alpha channel + reconstruction

Dinesh K. Pai

Textbook Chapter 16,17

Several slides courtesy of M. Kim

1

## Compositing?

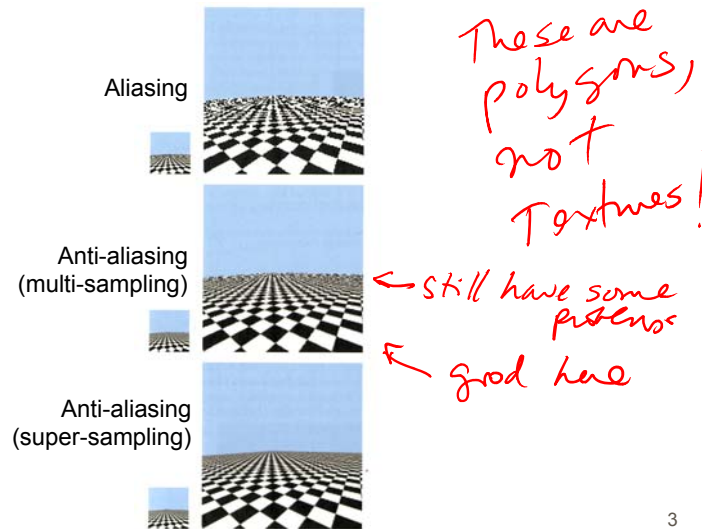
---

- Example of demo reel  
<http://vimeo.com/72617082>

2

## Recap: Aliasing and anti-aliasing

---



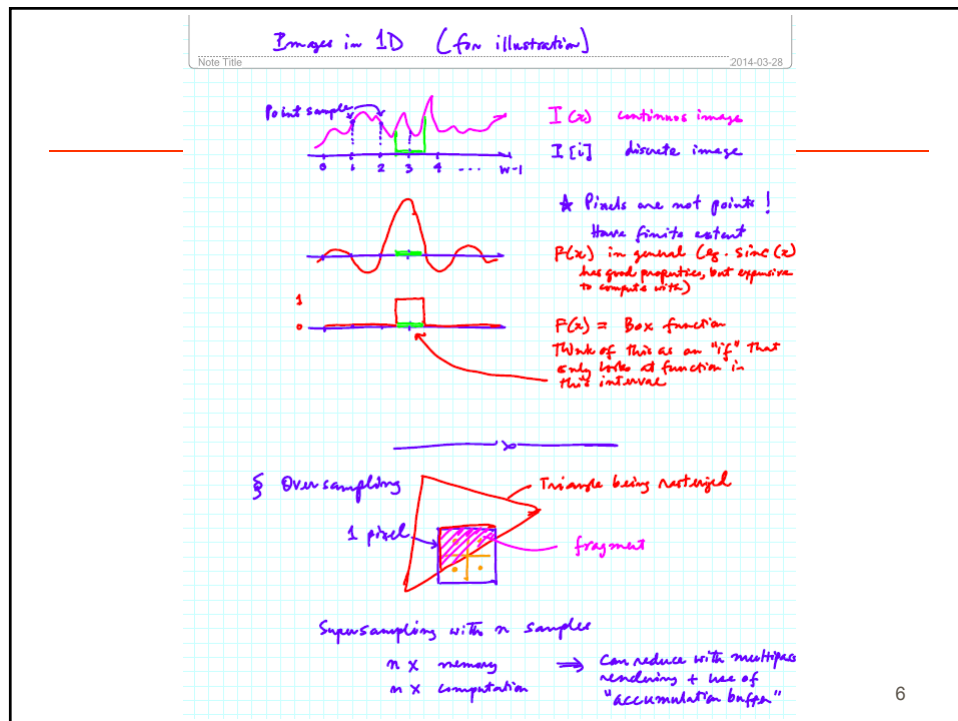
## C<sup>3</sup> Review: Sampling

---

- What causes aliasing?
  - a) Too much detail per pixel
  - b) Too many pixels per screen area
  - c) Incorrectly loaded texture
  - d) All of the above
  - e) None of the above

## C<sup>3</sup> Review: Sampling

- How to avoid aliasing?
  - a) Render to a display of higher resolution
  - b) Calculate some average value of several texels to display for each pixel**
  - c) Change to a texture of higher resolution
  - d) All of the above
  - e) None of the above



## Overview of Compositing

---

- Generalize idea of anti-aliasing to representing the “coverage” of each pixel by an object
- Essential for multi-pass rendering, requiring combination of images
- Historically, related to “matte”s in film, now done using the “alpha” channel in RGBA color images
- Importance increasing due to increasing availability of digital imagery
- Widely used: Visual Effects, “Sprites” in games, etc. Natively supported in most OS’s for GUI

7

## Image compositing

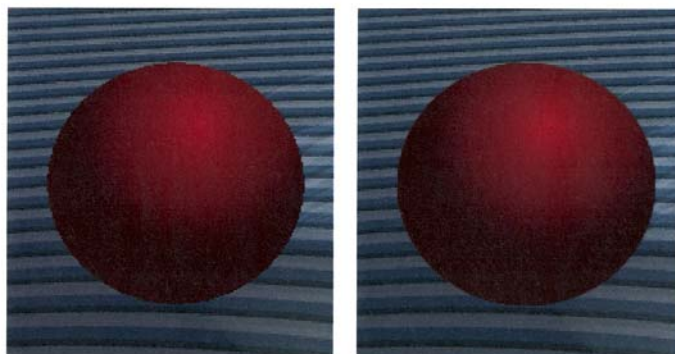
---

- Given two discrete images, a foreground,  $I^f$ , and background,  $I^b$ , that we want to combine into one image  $I^c$ .
- Simple: in composite, use foreground pixels where they are defined. Else use background pixels.
- This will give us a jagged boundary.
- Real image would have “boundary” pixels with blended colors.
- But this requires using “sub-pixel” information.

8

## Image compositing

---



9

## Alpha blending

---

- Associate with each pixel in each image layer, a value,  $\alpha[i][j]$ , that describes the overall opacity or coverage of the image layer at that pixel.
  - An alpha value of 1 represents a fully opaque/occupied pixel, while a value of 0 represents a fully transparent/empty one.
  - A fractional value represents a partially transparent (partially occupied) pixel.
- Alpha will be used during compositing.

10

## Alpha definition

- More specifically, let  $I(x, y)$  be a continuous image, and let  $C(x, y)$  be a binary valued  $(x, y)$  coverage function over the continuous domain, with a value of 1 at any point where the image is “occupied” and 0 where it is not.
- Let us store in our discrete image the values:

$$I[i][j] \leftarrow \iint_{\Omega_{i,j}} I(x, y) C(x, y) dx dy$$

$$\alpha[i][j] \leftarrow \iint_{\Omega_{i,j}} C(x, y) dx dy$$

11

## Over operation

Note: a technical term

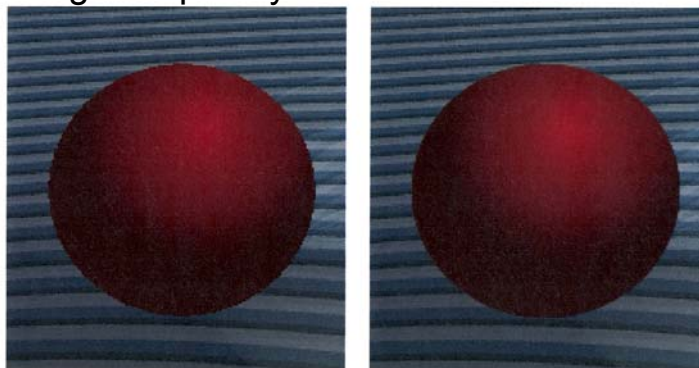
- To compose  $I^f[i][j]$  over  $I^b[i][j]$ , we compute the composite image colors,  $I^c[i][j]$ , using
 
$$I^c[i][j] \leftarrow I^f[i][j] + I^b[i][j] (1 - \alpha^f[i][j])$$
 That is, the amount of observed background color at a pixel is proportional to the transparency of the foreground layer at that pixel.
- Likewise, alpha for the composite image can be computed as:

$$\alpha^c[i][j] \leftarrow \alpha^f[i][j] + \alpha^b[i][j] (1 - \alpha^f[i][j])$$

## Over operation

---

- If background is opaque, so the composite pixel is opaque.
- But we can model more general case as part of blending multiple layers.



13

## Over properties

---

- This provides a reasonable approximation to the correctly rendered image.
- One can easily verify that the over operation is associative but not commutative. That is,

$$I^a \text{ over } (I^b \text{ over } I^c) = (I^a \text{ over } I^b) \text{ over } I^c$$

$$I^a \text{ over } I^b \neq I^b \text{ over } I^a$$

14

---

Chapter 17

## RECONSTRUCTION

(DISCRETE → CONTINUOUS)

15

---

## Reconstruction

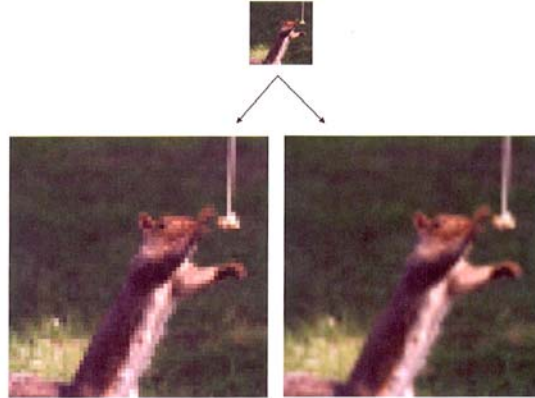
- Given a discrete image  $I[i][j]$ , how do we create a continuous image  $I(x,y)$ ?
- Is central to resize images and to texture mapping.
  - How to get a texture colors that fall in between texels.
- This process is called *reconstruction*.
- We already know the key idea, from L24-L26: Interpolation! So we will go over this quickly.

16



## Constant reconstruction

- The resulting continuous image is made up of little squares of constant color.
- Each pixel has an influence region of 1-by-1

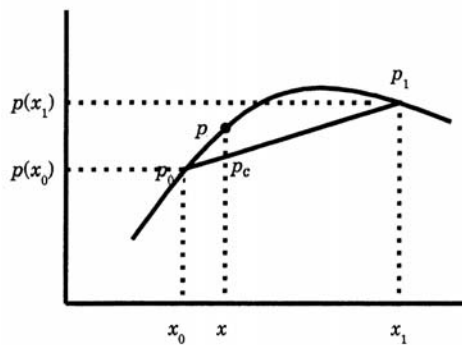


17

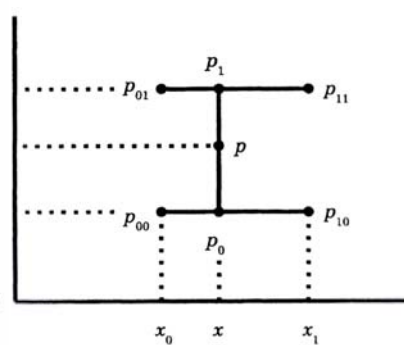
## Linear and Bilinear interpolation

We already know how to interpolate in 1D

- Linear (1D)



Bilinear (2D):



18

## Bilinear reconstruction

- Can create a smoother looking reconstruction using *bilinear interpolation*.
- Bilinear interpolation is obtained by applying linear interpolation in both the horizontal and vertical directions.

```

color bilinearReconstruction(float x, float y, color
image[][]){
    int intx = (int) x;
    int inty = (int) y;
    float fracx = x - intx;
    float fracy = y - inty;

    color colorx1 = (1-fracx) * image[intx][inty] +
        (fracx) * image[intx+1][inty];
    color colorx2 = (1-fracx) * image[intx][inty+1] +
        (fracx) * image[intx+1][inty+1];
    color colorxy = (1-fracy) * colorx1 +
        (fracy) * colorx2;
    return(colorxy);

```

19

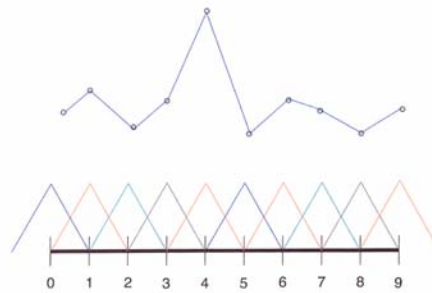
## Bilinear properties

- At integer coordinates, we have  $I(x,y)=I[i][j]$ ; the reconstructed continuous image  $I$  agrees with the discrete image  $I$ . => **Interpolation**
- In between integer coordinates, the color values are blended continuously.
- Each pixel influences, to a varying degree, each point within a 2-by-2 square region of the continuous image. => **Local Support**
- The horizontal/vertical ordering is irrelevant.
- Color over a square is bilinear function of  $(x,y)$ .

20

## Bilinear basis function

- Just as in L25,L26, we can think of interpolation as weighted combination of basis (or blending) functions B
- In 1D, we can define a univariate *hat function*  $H_i(x)$



$$H_i(x) = \begin{cases} x - i + 1 & \text{for } i - 1 < x < i \\ -x + i + 1 & \text{for } i < x < i + 1 \\ 0 & \text{else} \end{cases}$$

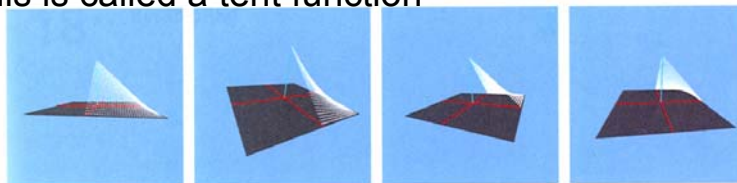
21

## Bilinear basis function

- In 2D (bilinear function), let  $T_{i,j}(x,y)$  be a bivariate function:

$$T_{i,j}(x,y) = H_i(x)H_j(y).$$

- This is called a tent function



- In constant reconstruction,  $B_{i,j}(x,y)$  is a box function that is zero everywhere except for the unit square surrounding the coordinates  $(i,j)$ , where it has constant value 1.

22