

Sampling

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Textbook Chapter 16

Several slides courtesy of M. Kim

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Announcements

- Final exam resources
 - It's not too early to start studying!
 - Extra office hours just before exam on 22nd, 23rd, 24th and 25th. 1-2pm in room 005
 - Review during last two classes
- Industry talk on VFX pipeline today at 3pm
- A personal note

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Visual Effects Industry talk

- By Andrew Kaufman, my former M.Sc. student, now at Image Engine in Vancouver
- "The VFX Pipeline", Fri March 28, 3pm, DMP 301
- Guest lecture in CPSC 426 Computer Animation class.

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C³ Survey

- How far along are you with Assignment 4
 - a) Not started
 - b) Can run template code
 - c) Finished at least one part
 - d) Finished all specified parts (1,2,3)
 - e) Finished everything

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C³ Review

- The z-buffer stores
 - a) A zipped version of the rendered image
 - b) Distance of a fragment in the eye frame
 - c) Nearness (1/depth) of a fragment in the eye frame
 - d) Shadows cast by the light source

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Two views of images

- A *continuous image*, $I(x_w, y_w)$, is a bivariate function.
 - range is a linear color space.
- A *discrete image* $I[i][j]$ is a two dimensional array of color values.
- We associate each pair of integers i, j , with the continuous image coordinates $x_w = i$ and $y_w = j$

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Sampling

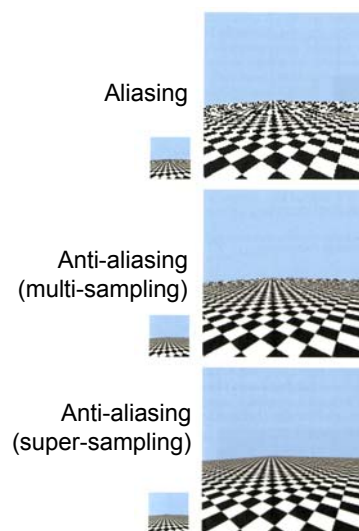
- The simplest and most obvious method to go from a continuous to a discrete image is by *point sampling*.
- To obtain the value of a pixel i, j , we sample the continuous image function at a single integer valued domain location:

$$I[i][j] \leftarrow I(i, j)$$

- This can result in unwanted artifacts.

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Aliasing and anti-aliasing



These are polygons,
not textures!

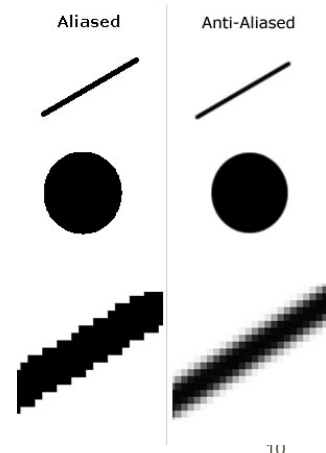
← still have some problems

← good here

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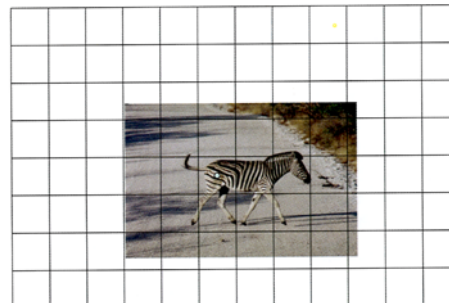
Aliasing

- Scene made up of black and white triangles: jaggies at boundaries
 - Jaggies will crawl during motion
- If triangles are small enough then we get random values or weird patterns.
 - Jaggies will crawl during motion



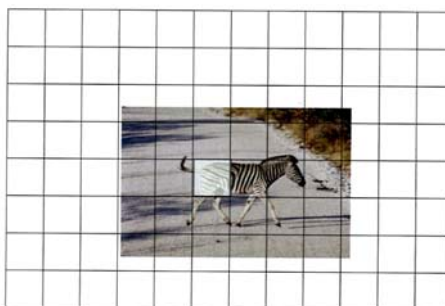
Aliasing

- The heart of the problem: too much information in one pixel



Anti-aliasing

- Intuitively: the single sample is a bad value, we would be better off setting the pixel value using some kind of average value over some appropriate region.
- In the above examples, perhaps some gray value.



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Anti-aliasing

- Mathematically this can be modeled using *Fourier analysis*.
 - Breaks up the data by “frequencies” and figures out what to do with the un-representable high frequencies.



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Anti-aliasing

- We can also model this as an optimization problem.
- These approaches lead to:

$$I[i][j] \leftarrow \iint_{\Omega} I(x,y)F_{i,j}(x,y)dxdy$$

- where $F_{i,j}(x,y)$ is some function that tells us how strongly the continuous image value at $[x,y]^t$ should influence the pixel value i, j

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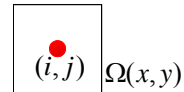
Anti-aliasing

- In this setting, the function $F_{i,j}(x,y)$ is called a *filter*.
 - In other words, the best pixel value is determined by performing some continuous weighted averaging near the pixel's location.
 - Effectively, this is like blurring the continuous image before point sampling it.

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Box filter

- We often choose the filters $F_{i,j}(x,y)$ to be something non-optimal, but that can more easily be computed with.
- The simplest such choice is a *box filter*, where $F_{i,j}(x,y)$ is zero everywhere except over the 1-by-1 square center at $x = i, y = j$.



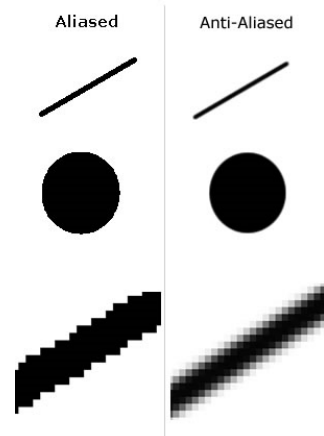
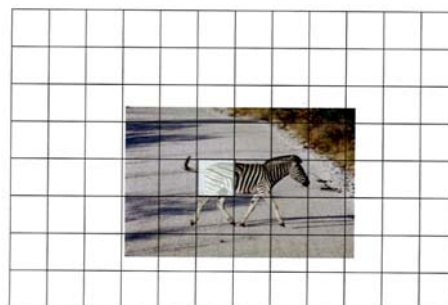
- Calling this square $\Omega_{i,j}$, we arrive at

$$I[i][j] \leftarrow \iint_{\Omega_{i,j}} I(x,y) dx dy$$

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Box filter

- In this case, the desired pixel value is simply the average of the continuous image over the pixel's square domain.



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Over-sampling

- Even that integral is not really easy to compute
- Instead, it is approximated by some sum of the form:

$$I[i][j] \leftarrow \frac{1}{n} \sum_{k=1}^n I(x_k, y_k)$$



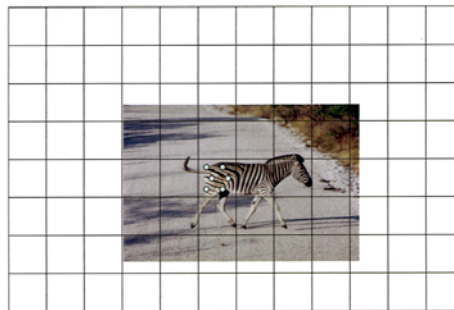
where k indexes some set of locations (x_k, y_k) called the sample locations.

- The renderer first produces a “high resolution” color and z-buffer “image”,
 - where we will use the term *sample* to refer to each of these high resolution pixels.

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Over-sampling

- Then, once rasterization is complete, groups of these samples are averaged together, to create the final lower resolution image.



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Super-sampling

- If the sample locations for the high resolution image form a regular, high resolution grid, then this is called *super sampling*.
- We can also choose other sampling patterns for the high resolution “image”,
 - Such less regular patterns can help us avoid systematic errors that can arise when using the sum to replace the integral.

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Multi-sampling

- Render to a “high resolution” color and z-buffer
- During the rasterization of each triangle, “coverage” and z-values are computed at this sample level.
- But for efficiency, the fragment shader is only called **only once per final resolution pixel**.
 - This color data is shared between all of the samples hit by the triangle in a single (final resolution) pixel.
- Once rasterization is complete, groups of these high resolution samples are averaged together.

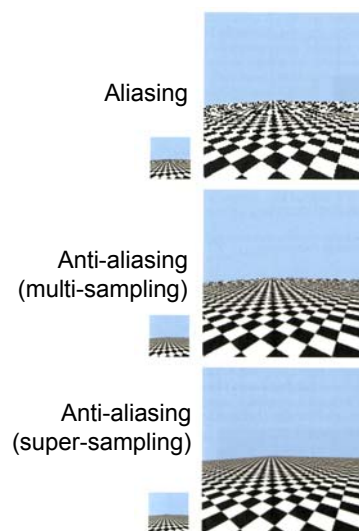
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Multi-sampling

- Multisampling can be an effective anti-aliasing method since, without texture mapping, colors tend to vary quite slowly over each triangle, and thus they do not need to be computed at high spatial resolution.
- To deal with aliasing that occurs during texture mapping, we have the advantage of possessing the texture image in hand at the outset of the rendering process.
- This leads to specialized techniques such as *mip mapping*.

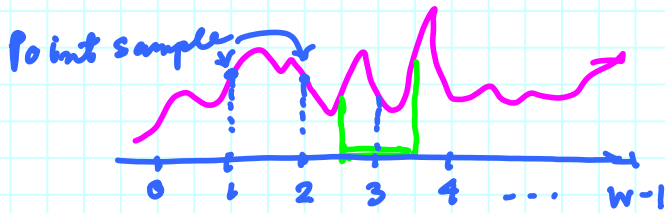
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Aliasing and anti-aliasing



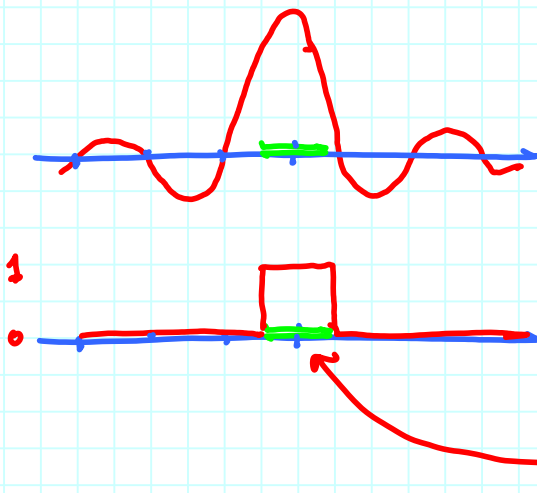
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Images in 1D (for illustration)



$I(x)$ continuous image

$I[i]$ discrete image



★ Pixels are not points!

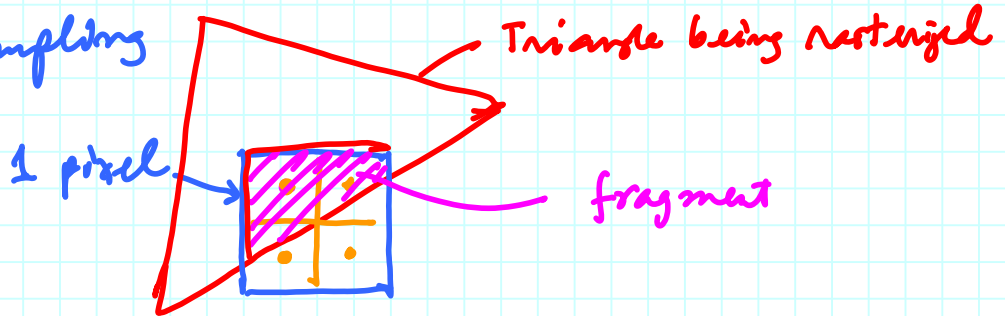
Have finite extent

$P(x)$ in general (eg. $\sin(x)$ has good properties, but expensive to compute with)

$F(x) =$ Box function

Think of this as an "if" that only looks at function in this interval

§ Over sampling



Supersampling with n samples

$n \times$ memory
 $n \times$ computation

⇒ Can reduce with multiple rendering + use of "accumulation buffer"