



Lighting Scan Conversion

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Course News

Assignment 2

- Due Monday, Feb 28

Homework 3

- Discussed in labs next wee

Quiz 1

- Discussed in labs this week

Reading

- Chapter 9, 3

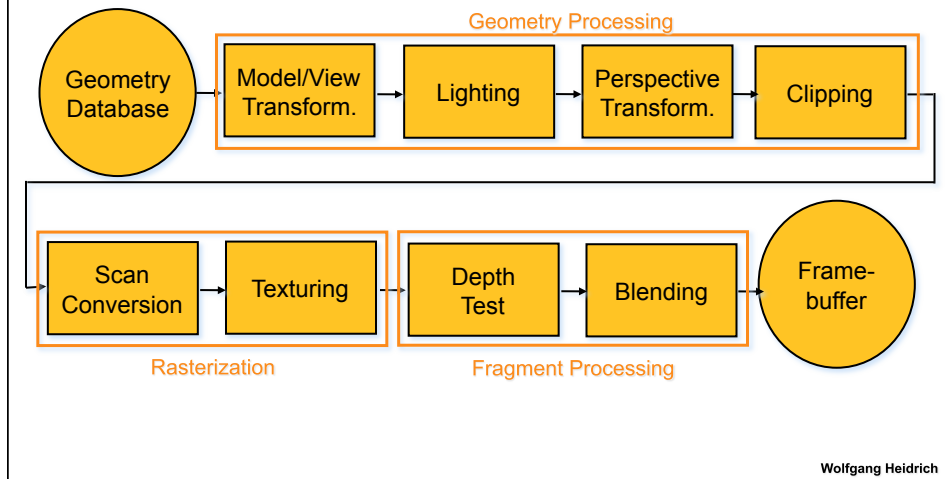
Out of Town Friday

- Anika will fill in for me

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The Rendering Pipeline



Lighting

Goal

- Model the interaction of light with surfaces to render realistic images

Contributing Factors

- Light sources
 - *Shape and color*
- Surface materials
 - *How surfaces reflect light*
- Transport of light
 - *How light moves in a scene (global illumination, later in the course)*

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Types of Reflection

- *Specular* (a.k.a. *mirror* or *regular*) reflection causes light to propagate without scattering.



- *Diffuse* reflection sends light in all directions with equal energy.



- *Mixed* reflection is a weighted combination of specular and diffuse.

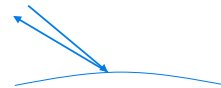


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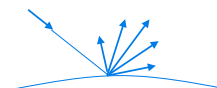


Types of Reflection

- *retro-reflection* occurs when incident energy reflects in directions close to the incident direction, for a wide range of incident directions.



- *gloss* is the property of a material surface that involves mixed reflection and is responsible for the mirror like appearance of rough surfaces.

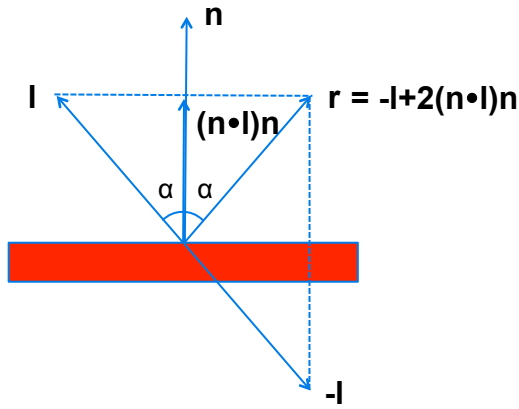


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Specular Reflection

Geometry of specular (mirror) reflection

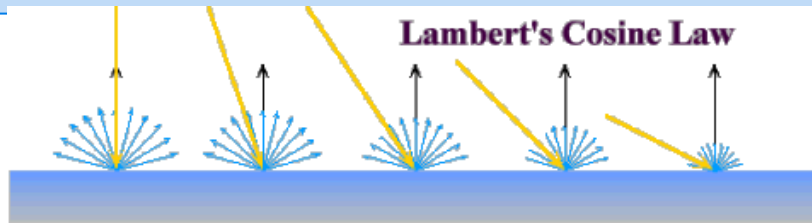


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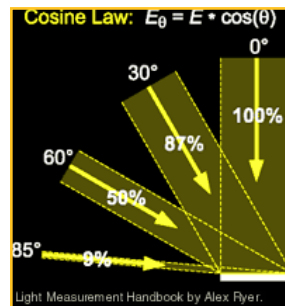


Lambert's "Law"

Lambert's Cosine Law



Intuitively: cross-sectional area of the "beam" intersecting an element of surface area is smaller for greater angles with the normal.

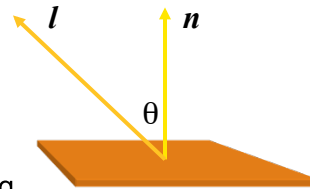


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Computing Diffuse Reflection

- Depends on **angle of incidence**: angle between surface normal and incoming light
 - $I_{diffuse} = k_d I_{light} \cos \theta$
- In practice use vector arithmetic
 - $I_{diffuse} = k_d I_{light} (\mathbf{n} \cdot \mathbf{l})$
- Always normalize vectors used in lighting
 - \mathbf{n} , \mathbf{l} should be unit vectors
- Scalar (B/W intensity) or 3-tuple or 4-tuple (color)
 - k_d : diffuse coefficient, surface color
 - I_{light} : incoming light intensity
 - $I_{diffuse}$: outgoing light intensity (for diffuse reflection)

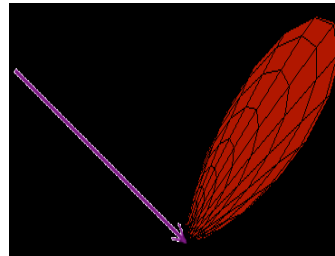
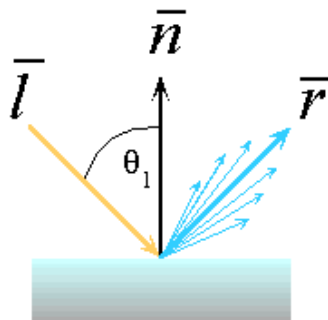


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Glossy Materials – Empirical Approximation

Angular falloff



how might we model this falloff?

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Phong Lighting

Most common lighting model in computer graphics

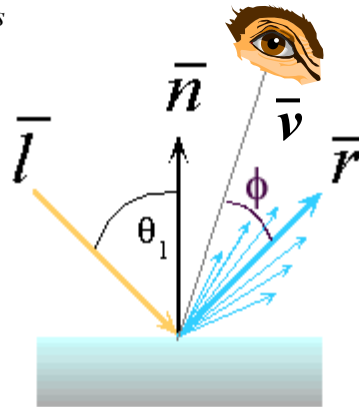
– (Phong Bui-Tuong, 1975)

$$I_{\text{specular}} = k_s I_{\text{light}} (\cos \phi)^{n_s}$$

n_s : purely empirical constant, varies rate of falloff

k_s : specular coefficient, highlight color

no physical basis, works ok in practice



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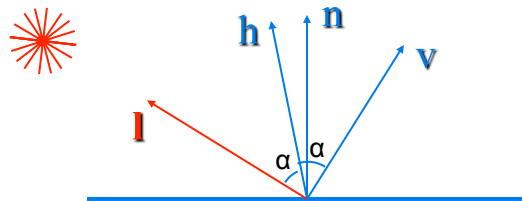
Alternative Model

Blinn-Phong model (Jim Blinn, 1977)

• Variation with better physical interpretation

– \mathbf{h} : halfway vector; r : roughness

$$I_{\text{out}}(\mathbf{x}) = k_s \cdot (\mathbf{h} \cdot \mathbf{n})^{1/r} \cdot I_{\text{in}}(\mathbf{x}); \text{ with } \mathbf{h} = (\mathbf{l} + \mathbf{v}) / 2$$



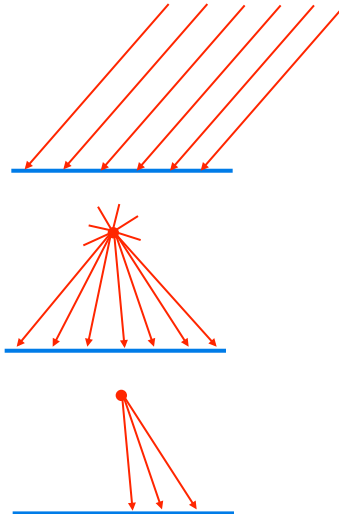
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Simple Light Sources

Types of light sources

- Directional/parallel lights
 - E.g. sun
 - Homogeneous vector
- (Homogeneous) point lights
 - Same intensity in all directions
 - Homogeneous point
- Spot lights
 - Limited set of directions
 - Point+direction+cutoff angle



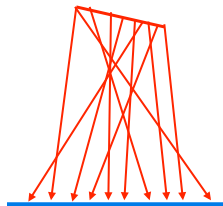
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Light Sources

Area lights:

- Light sources with a finite area
- Can be considered a continuum of point lights
- Not available in many rendering systems



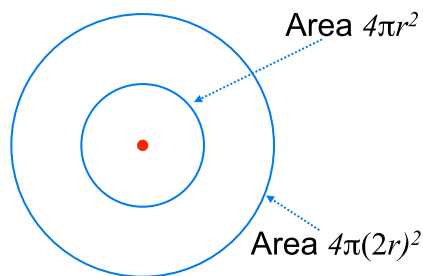
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Light Source Falloff

Quadratic falloff (point- and spot lights)

- Brightness of objects depends on power per unit area that hits the object
- The power per unit area for a point or spot light decreases quadratically with distance



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Light Source Falloff

Non-quadratic falloff

- Many systems allow for other falloffs
- Allows for faking effect of area light sources
- OpenGL / graphics hardware
 - I_o : intensity of light source
 - \mathbf{x} : object point
 - r : distance of light from \mathbf{x}

$$I_{in}(\mathbf{x}) = \frac{1}{ar^2 + br + c} \cdot I_0$$

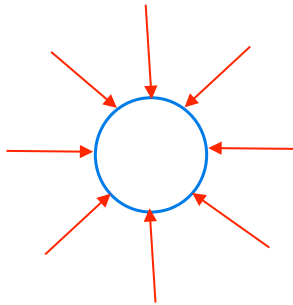
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Light Sources

Ambient lights

- No identifiable source or direction
- Hack for replacing true global illumination
 - (*light bouncing off from other objects*)

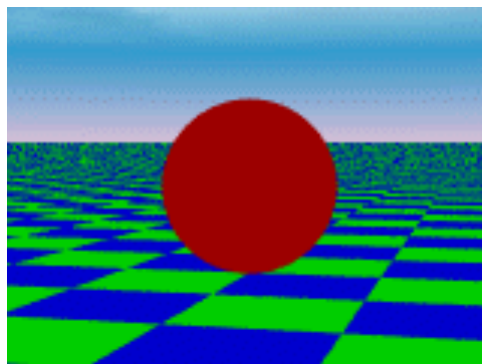


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Ambient Light Sources

- Scene lit only with an ambient light source



Light Position
Not Important

Viewer Position
Not Important

Surface Angle
Not Important

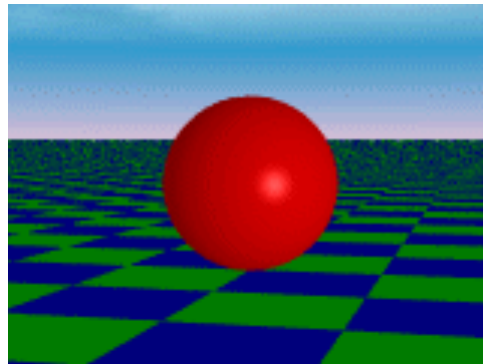
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Directional Light Sources

- Scene lit with directional and ambient light

Surface Angle
Important



Light Position
Not Important

Viewer Position
Not Important

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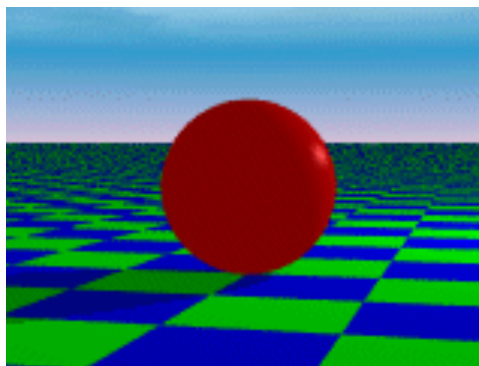
Point Light Sources

- Scene lit with ambient and point light source

Light Position
Important

Viewer Position
Important

Surface Angle
Important



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Light Sources & Transformations

Geometry: positions and directions

- Standard: world coordinate system
 - *Effect: lights fixed wrt world geometry*
 - *Demo: <http://www.xmission.com/~nate/tutors.html>*
- Alternative: camera coordinate system
 - *Effect: lights attached to camera (car headlights)*
- Points and directions undergo normal model/view transformation

Illumination calculations: camera coords

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Lighting Review

Lighting models

- Ambient
 - *Normals don't matter*
- Lambert/diffuse
 - *Angle between surface normal and light*
- Phong/specular
 - *Surface normal, light, and viewpoint*

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Lighting in OpenGL

Light source: amount of RGB light emitted

- Value represents percentage of full intensity
E.g., (1.0,0.5,0.5)
- Every light source emits ambient, diffuse, and specular light

Materials: amount of RGB light reflected

- Value represents percentage reflected
e.g., (0.0,1.0,0.5)

Interaction: multiply components

- Red light (1,0,0) x green surface (0,1,0) = black (0,0,0)

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Lighting in OpenGL

```
glLightfv(GL_LIGHT0, GL_AMBIENT, amb_light_rgba );  
glLightfv(GL_LIGHT0, GL_DIFFUSE, dif_light_rgba );  
glLightfv(GL_LIGHT0, GL_SPECULAR, spec_light_rgba );  
glLightfv(GL_LIGHT0, GL_POSITION, position);  
glEnable(GL_LIGHT0);
```

```
glMaterialfv( GL_FRONT, GL_AMBIENT, ambient_rgba );  
glMaterialfv( GL_FRONT, GL_DIFFUSE, diffuse_rgba );  
glMaterialfv( GL_FRONT, GL_SPECULAR, specular_rgba );  
glMaterialfv( GL_FRONT, GL_SHININESS, n );
```

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Lighting in Rendering Pipeline

Notes:

- Lighting is applied to every **vertex**
 - *i.e. the three vertices in a triangle*
 - *Per-vertex lighting*
- Will later see how the interior points of the triangle obtain their color
 - *This process is called **shading***
 - *Will discuss in the context of scan conversion*

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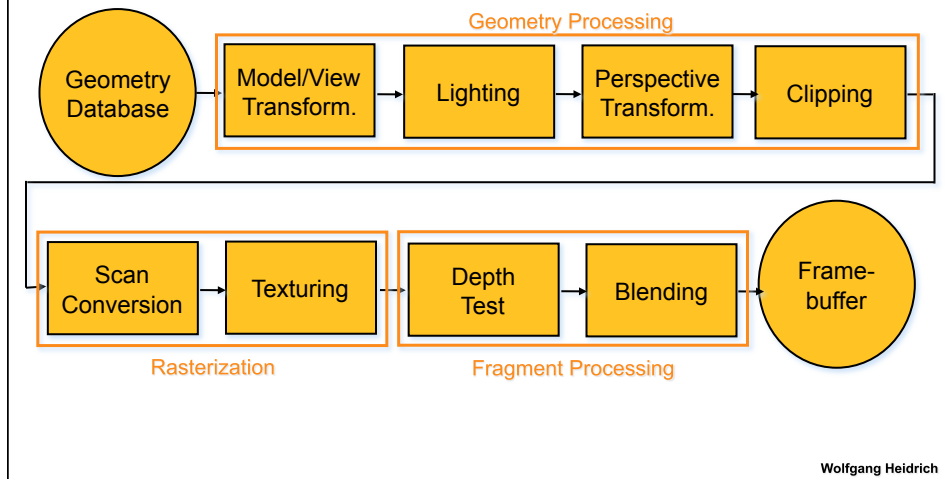
Scan Conversion

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The Rendering Pipeline



Scan Conversion - Rasterization

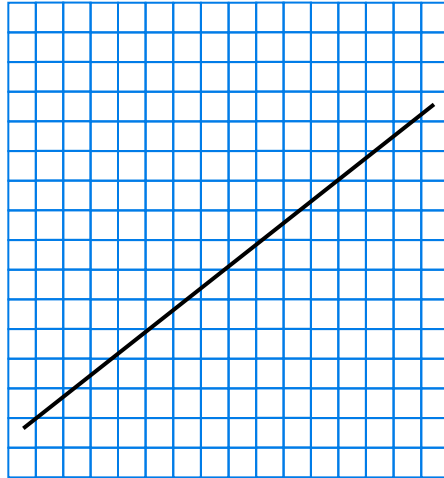
Convert continuous rendering primitives into discrete fragments/pixels

- Lines
 - *Midpoint/Bresenham*
- Triangles
 - *Flood fill*
 - *Scanline*
 - *Implicit formulation*
- Interpolation

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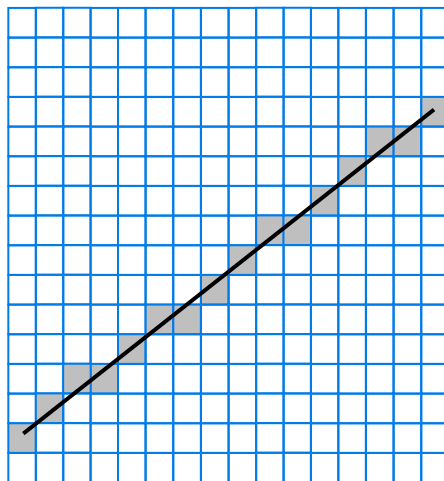
Scan Conversion - Lines



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Scan Conversion - Lines



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Scan Conversion - Lines

First Attempt:

- Line (s,e) given in device coordinates
- Create the thinnest line that connects start point and end point without gap

Assumptions for now:

- Start point to the left of end point: $x_s < x_e$
- Slope of the line between 0 and 1 (i.e. elevation between 0 and 45 degrees:

$$0 \leq \frac{y_e - y_s}{x_e - x_s} \leq 1$$

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Scan Conversion of Lines - Digital Differential Analyzer

First Attempt:

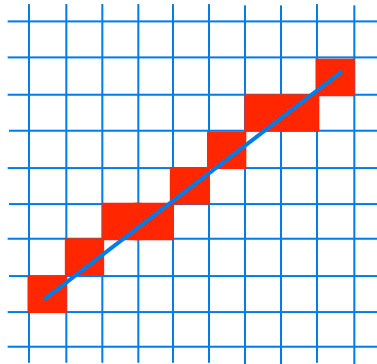
```
dda( float xs, ys, xe, ye ) {  
    // assume xs < xe, and slope m between 0 and 1  
    float m= (ye-ys)/(xe-xs);  
    float y= round( ys );  
    for( int x= round( xs ); x<= xe ; x++ ) {  
        drawPixel( x, round( y ) );  
        y= y+m;  
    }  
}
```

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Scan Conversion of Lines

DDA:



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Scan Conversion of Lines Midpoint Algorithm

Moving horizontally along x direction

- Draw at current y value, or move up vertically to y+1?
 - Check if midpoint between two possible pixel centers above or below line

Candidates

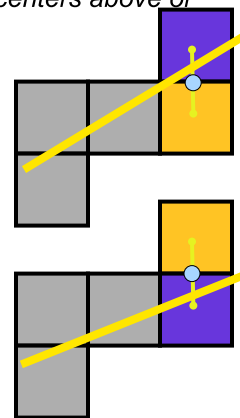
- Top pixel: $(x+1, y+1)$
- Bottom pixel: $(x+1, y)$

Midpoint: $(x+1, y+.5)$

Check if midpoint above or below line

- Below: top pixel
- Above: bottom pixel

Key idea behind Bresenham Alg.



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Scan Conversion of Lines

Idea: decision variable

```
dda( float xs, ys, xe, ye ) {  
    float d= 0.0;  
    float m= (ye-ys)/(xe-xs);  
    int y= round( ys );  
    for( int x= round( xs ) ; x<= xe ; x++ ) {  
        drawPixel( x, y );  
        d= d+m;  
        if( d>= 0.5 ) { d= d-1.0; y++; }  
    }  
}
```

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Scan Conversion of Lines Bresenham Algorithm ('63)

- Use decision variable to generate purely integer algorithm
- Explicit line equation:

$$y = \frac{(y_e - y_s)}{(x_e - x_s)}(x - x_s) + y_s$$

- Implicit version:

$$L(x, y) = \frac{(y_e - y_s)}{(x_e - x_s)}(x - x_s) - (y - y_s) = 0$$

- In particular for specific x, y, we have
 - $L(x, y) > 0$ if (x, y) below the line, and
 - $L(x, y) < 0$ if (x, y) above the line

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Scan Conversion of Lines Bresenham Algorithm



- Decision variable: after drawing point (x,y) decide whether to draw
 - $(x+1,y)$: case *E* (for “east”)
 - $(x+1,y+1)$: case *NE* (for “north-east”)
- Check whether $(x+1,y+1/2)$ is above or below line

$$d = L(x+1, y + \frac{1}{2})$$

- Point above line if and only if $d < 0$

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Scan Conversion of Lines



Bresenham Algorithm

- Problem: how to update d ?
- Case *E* (point above line, $d \leq 0$)
 - $x = x+1$;
 - $d = L(x+2, y+1/2) = d + (y_e - y_s)/(x_e - x_s)$
- Case *NE* (point below line, $d > 0$)
 - $x = x+1$; $y = y+1$;
 - $d = L(x+2, y+3/2) = d + (y_e - y_s)/(x_e - x_s) - 1$
- Initialization:
 - $d = L(x_s+1, y_s+1/2) = (y_e - y_s)/(x_e - x_s) - 1/2$

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Scan Conversion of Lines

Bresenham Algorithm

- This is still floating point
- But: only sign of d matters
- Thus: can multiply everything by $2(x_e - x_s)$

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Scan Conversion of Lines

Bresenham Algorithm

```
Bresenham( int xs, ys, xe, ye ) {  
    int y= ys;  
    incrE= 2(ye - ys);  
    incrNE= 2((ye - ys) - (xe-xs));  
    for( int x= xs ; x<= xe ; x++ ) {  
        drawPixel( x, y );  
        if( d<= 0 ) d+= incrE;  
        else { d+= incrNE; y++; }  
    }  
}
```

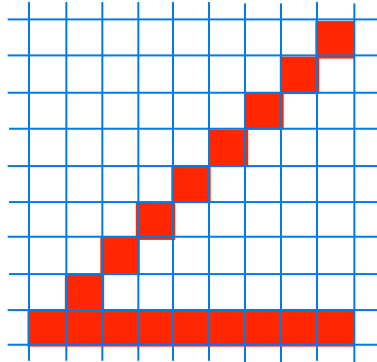
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Scan Conversion of Lines

Discussion

- Bresenham sets same pixels as DDA
- Intensity of line varies with its angle!



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Scan Conversion of Lines

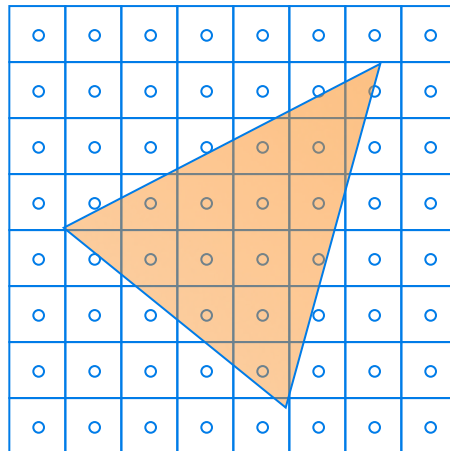
Discussion

- Bresenham
 - Good for hardware implementations (*integer!*)
- DDA
 - May be faster for software (*depends on system!*)
 - Floating point ops higher parallelized (*pipelined*)
 - E.g. RISC CPUs from MIPS, SUN
 - No if statements in inner loop
 - More efficient use of processor pipelining

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Scan Conversion of Polygons

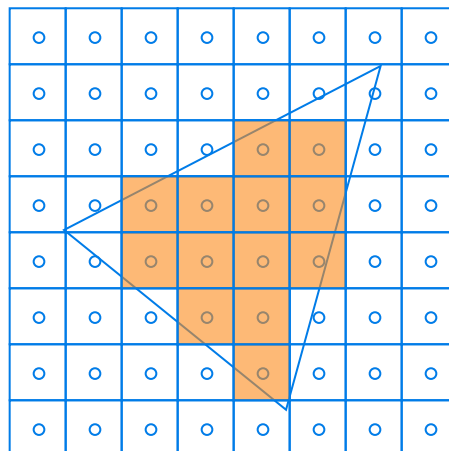


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Scan Conversion of Polygons

One possible scan conversion



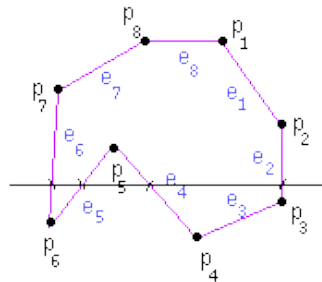
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Scan Conversion of Polygons

A General Algorithm

- Intersect each scanline with all edges
- Sort intersections in x
- Calculate parity to determine in/out
- Fill the 'in' pixels

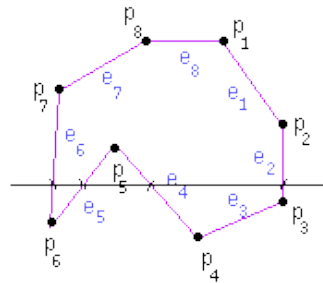


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Scan Conversion of Polygons

- Works for arbitrary polygons
- Efficiency improvement:
 - Exploit row-to-row coherence using “edge table”



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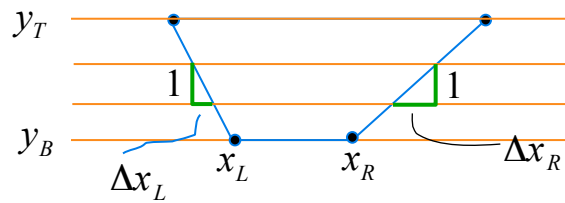


Edge Walking

Past graphics hardware

- Exploit continuous L and R edges on trapezoid

`scanTrapezoid($x_L, x_R, y_B, y_T, \Delta x_L, \Delta x_R$)`

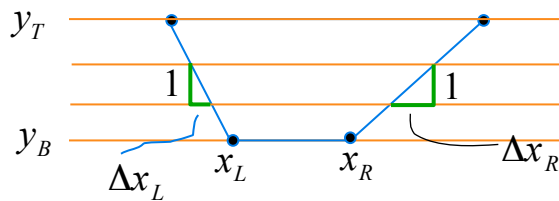


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Edge Walking

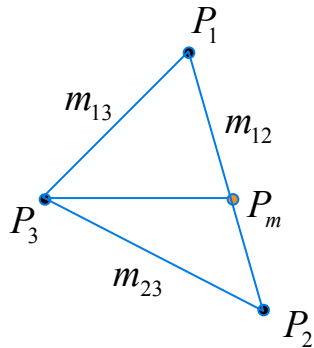
```
for (y=yB; y<=yT; y++) {  
  for (x=xL; x<=xR; x++)  
    setPixel(x,y);  
  xL += DxL;  
  xR += DxR;  
}
```



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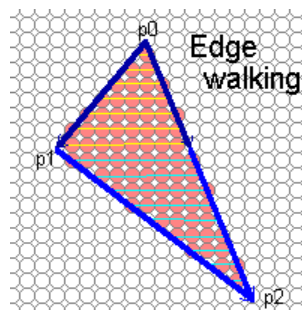
Edge Walking Triangles

- Split triangles into two regions with continuous left and right edges



$\text{scanTrapezoid}(x_3, x_m, y_3, y_1, \frac{1}{m_{13}}, \frac{1}{m_{12}})$

$\text{scanTrapezoid}(x_2, x_m, y_2, y_3, \frac{1}{m_{23}}, \frac{1}{m_{12}})$



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Edge Walking Triangles

Issues

- Many applications have small triangles
 - Setup cost is non-trivial
- Clipping triangles produces non-triangles
 - This can be avoided through re-triangulation, as discussed

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Coming Up:

Friday

- More scan conversion
- Lecture by Anika

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