


Transformation Hierarchies

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Course News

Assignment 1

- Due January 31

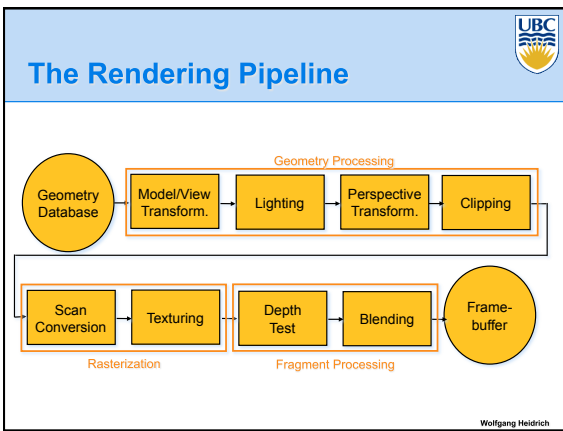
Homework 2


- Exercise problems for perspective
- Discussed in labs next week

Reading

- Chapter 7 (new book) or 6 (old book)

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Rendering Geometry in OpenGL

Example:

```
glBegin( GL_TRIANGLES );
  glColor3f( 1.0, 0.0, 0.0 );
  glVertex3f( 1.0, 0.0, 0.0 );
  glColor3f( 0.0, 0.0, 1.0 );
  glVertex3f( 0.0, 1.0, 0.0 );
  glVertex3f( 0.0, 0.0, 0.0 );
glEnd();
```



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Recap: Rendering Geometry in OpenGL


Additional attributes

- glColor3f: RGB color value (0...1 per component)
- glNormal3f: normal vector
- glTexCoord2f: texture coordinate (explained later)

OpenGL is state machine:

- Every vertex gets color, normal etc. that corresponds to last specified value

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Recap: Interpreting Composite OpenGL Transformations

Example for earlier lectures:

- Rotation around arbitrary center
- In OpenGL:

```
// initialization of matrix
glMatrixMode( GL_MODELVIEW );
glLoadIdentity();

glTranslatef( 4, 3 );
glRotatef( 30, 0.0, 0.0, 1.0 );
glTranslatef( -4, -3 );

glBegin( GL_TRIANGLES );
// specify object geometry...
```

Top-to-bottom:
 ↓
 transf. of
 coordinate frame


 Bottom-to-top:
 ↑
 transf. of
 object

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Transformation Hierarchies

Scene may have a hierarchy of coordinate systems

- Stores matrix at each level with incremental transform from parent's coordinate system



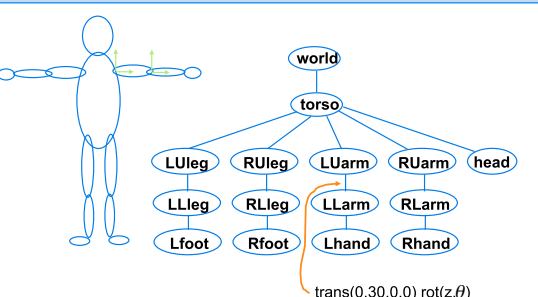
Scene graph

```

    graph TD
      road((road)) --- stripe1((stripe1))
      road --- stripe2((stripe2))
      road --- dots1[...]
      road --- car1((car1))
      road --- car2((car2))
      road --- dots2[...]
      car1 --- w1((w1))
      car1 --- w2((w2))
      car1 --- w3((w3))
      car1 --- w4((w4))
  
```

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Transformation Hierarchy Example 1



```

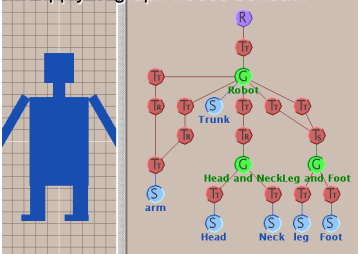
    graph TD
      world((world)) --- torso((torso))
      torso --- LUleg((LUleg))
      torso --- RUleg((RUleg))
      torso --- LUarm((LUarm))
      torso --- RUarm((RUarm))
      torso --- head((head))
      LUleg --- LLleg((LLleg))
      RUleg --- RLleg((RLleg))
      LUarm --- LLarm((LLarm))
      RUarm --- RLarm((RLarm))
      LLleg --- Lfoot((Lfoot))
      RLleg --- Rfoot((Rfoot))
      LLarm --- Lhand((Lhand))
      RLarm --- Rhand((Rhand))
  
```

$\text{trans}(0.30,0,0) \text{rot}(z,\theta)$

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Transformation Hierarchies

- Hierarchies don't fall apart when changed
- transforms apply to graph nodes beneath




```

    graph TD
      Robot((Robot)) --- R((R))
      Robot --- Trunk((Trunk))
      Robot --- Head((Head))
      Robot --- Neck((Neck))
      Robot --- leg((leg))
      Robot --- Foot((Foot))
      Trunk --- arm((arm))
      Trunk --- Head2((Head))
      Trunk --- Neck2((Neck))
      Trunk --- leg2((leg))
      Trunk --- Foot2((Foot))
  
```

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Brown Applets

<http://www.cs.brown.edu/exploratories/freeSoftware/catalogs/scenegraphs.html>

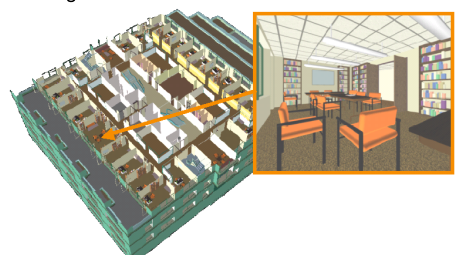


- Have a look later

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Transformation Hierarchy Example 2

- Draw same 3D data with different transformations: instancing

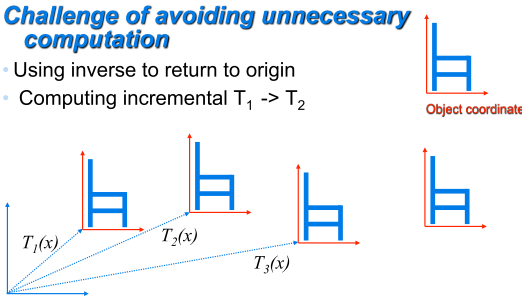


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Matrix Stacks

Challenge of avoiding unnecessary computation


- Using inverse to return to origin
- Computing incremental $T_1 \rightarrow T_2$



World coordinates

Object coordinates

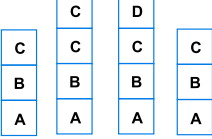
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Matrix Stacks

`glPushMatrix()`
`glPopMatrix()`

$D = C \text{ scale}(2,2,2) \text{ trans}(1,0,0)$




```

DrawSquare()
glPushMatrix()
glScale3f(2,2,2)
glTranslate3f(1,0,0)
DrawSquare()
glPopMatrix()

```

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Modularization

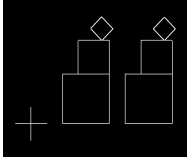
Drawing a scaled square

- Push/pop ensures no coord system change


```

void drawBlock(float k) {
    glPushMatrix();
    glScalef(k,k,k);
    glBegin(GL_LINE_LOOP);
    glVertex3f(0,0,0);
    glVertex3f(1,0,0);
    glVertex3f(1,1,0);
    glVertex3f(0,1,0);
    glEnd();
    glPopMatrix();
}

```



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Matrix Stacks


Advantages

- No need to compute inverse matrices all the time
- Modularize changes to pipeline state
- Avoids incremental changes to coordinate systems
 - Accumulation of numerical errors

Practical issues

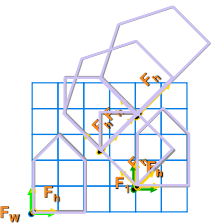
- In graphics hardware, depth of matrix stacks is limited
 - (typically 16 for model/view and about 4 for projective matrix)

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Transformation Hierarchy

Example 3




```

glLoadIdentity();
glTranslatef(4,1,0);
glPushMatrix();
glRotatef(45,0,0,1);
glTranslatef(0,2,0);
glScalef(2,1,1);
glTranslate(1,0,0);
glPopMatrix();

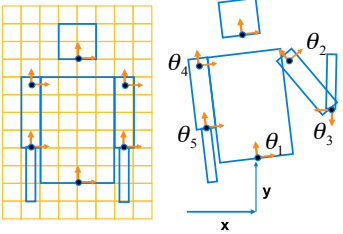
```

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Transformation Hierarchy

Example 4




```

glTranslatef(x,y,0);
glRotatef(theta,0,0,1);
DrawBody();
glPushMatrix();
glTranslatef(0,7,0);
DrawHead();
glPopMatrix();
glPushMatrix();
glTranslatef(2.5,5.5,0);
glRotatef(theta_2,0,0,1);
DrawUArm();
glTranslatef(0,-3.5,0);
glRotatef(theta_3,0,0,1);
DrawLArm();
glPopMatrix();
... (draw other arm)

```

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Hierarchical Modeling


Advantages

- Define object once, instantiate multiple copies
- Transformation parameters often good control knobs
- Maintain structural constraints if well-designed

Limitations

- Expressivity: not always the best controls
- Can't do closed kinematic chains
 - Keep hand on hip

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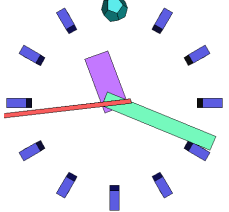


Single Parameter: simple

Parameters as functions of other params

- Clock: control all hands with seconds s

$m = s/60, h=m/60,$
 $\text{theta}_s = (2 \pi s) / 60,$
 $\text{theta}_m = (2 \pi m) / 60,$
 $\text{theta}_h = (2 \pi h) / 60$



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Single Parameter: complex

Mechanisms not easily expressible with affine transforms



<http://www.flying-pig.co.uk>


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Representing Complex Geometry

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Display Lists

Concept:


- If multiple copies of an object are required, it can be compiled into a display list:

```

glNewList( listId, GL_COMPILE );
glBegin( ... );
... // geometry goes here
glEndList();
// render two copies of geometry offset by 1 in z-direction:
glCallList( listId );
glTranslatef( 0.0, 0.0, 1.0 );
glCallList( listId );

```

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Display Lists

Advantages:

- More efficient than individual function calls for every vertex/attribute
- Can be cached on the graphics board (bandwidth!)
- Display lists exist across multiple frames
 - Represent static objects in an interactive application

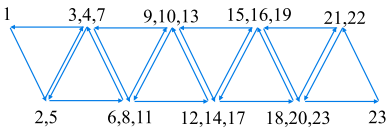
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Shared Vertices

Triangle Meshes

- Multiple triangles share vertices
- If individual triangles are sent to graphics board, every vertex is sent and transformed multiple times!
 - Computational expense
 - Bandwidth



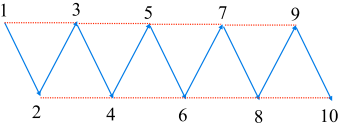
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Triangle Strips

Idea:

- Encode neighboring triangles that share vertices
- Use an encoding that requires only a constant-sized part of the whole geometry to determine a single triangle
- N triangles need n+2 vertices



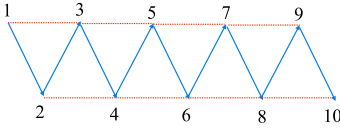
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Triangle Strips

Orientation:

- Strip starts with a counter-clockwise triangle
- Then alternates between clockwise and counter-clockwise



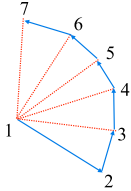
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Triangle Fans

Similar concept:

- All triangles share on center vertex
- All other vertices are specified in CCW order



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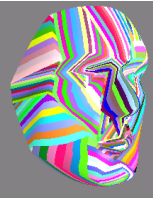
Triangle Strips and Fans

Transformations:


- n+2 for n triangles
- Only requires 3 vertices to be stored according to simple access scheme
- Ideal for pipeline (local knowledge)

Generation

- E.g. from directed edge data structure
- Optimize for longest strips/fans



Strippification by Dana Sharon
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Vertex Arrays

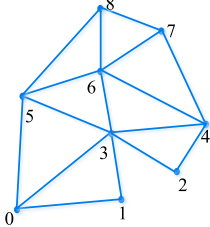
Concept:

- Store array of vertex data for meshes with arbitrary connectivity (topology)


```

GLfloat *points[3*nvertices];
GLfloat *colors[3*nvertices];
GLint *tris[numtris]=
{0,1,3, 3,2,4, ...};
glVertexPointer( ..., points);
glColorPointer( ..., colors);
glDrawElements(
GL_TRIANGLES,...,tris);

```



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Vertex Arrays

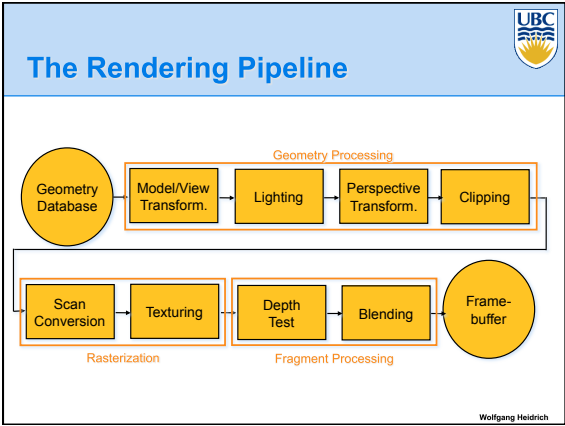
Benefits:

- Ideally, vertex array fits into memory on GPU
- Then all vertices are transformed exactly once

In practice:

- Graphics memory may not be sufficient to hold model
- Then either:
 - Cache only parts of the vertex array on board (may lead to cache trashing!)
 - Transform everything in software and just send results for individual triangles (bandwidth problem: multiple transfers of same vertex!)

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Coming Up:

This Week:

- Perspective projection

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