


The Rendering Pipeline – A First Look

Wolfgang Heidrich



Your Tasks Until Monday

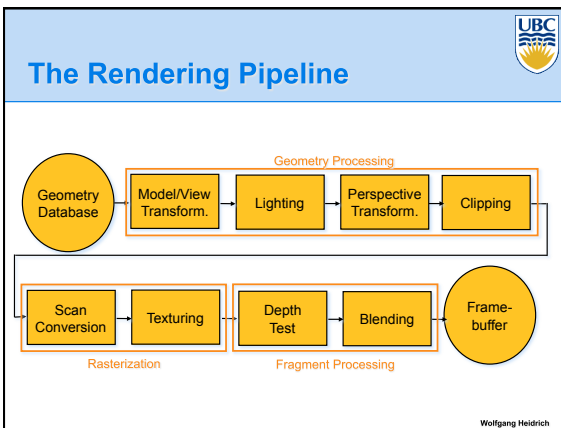
Assignment 0


- Refresher of linear algebra
- Set up programming environment on lab computers

Reading (in Shirley: Introduction to CG)

- Math refresher: Chapters 2, 4
 - *Optional (for now): 2.5-2.9*
- Background on graphics: Chapter 1

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The Rendering Pipeline

What is it? All of this:

- Abstract model for sequence of operations to transform a geometric model into a digital image
- An abstraction of the way graphics hardware works
- The underlying model for application programming interfaces (APIs) that allow the programming of graphics hardware
 - *OpenGL*
 - *Direct 3D*

Actual implementations of the rendering pipeline will vary in the details

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Rendering Pipeline

Advantages of a pipeline structure

- Logical separation of the different components, modularity
- Easy to parallelize:
 - *Earlier stages can already work on new data while later stages still work with previous data*
 - *Similar to pipelining in modern CPUs*
 - *But much more aggressive parallelization possible (special purpose hardware!)*
 - *Important for hardware implementations!*
- Only local knowledge of the scene is necessary

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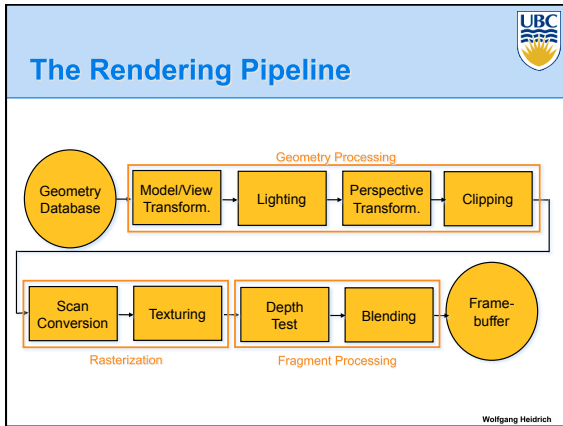


Rendering Pipeline

Disadvantages:

- Limited flexibility
- Some algorithms would require different ordering of pipeline stages
 - *Hard to achieve while still preserving compatibility*
- Only local knowledge of scene is available
 - *Shadows*
 - *Global illumination*

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Geometry Database

Needs to represent models for

- Geometric primitives
- Relations between different primitives (transformations)
- Object materials
- Light sources
- Camera

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Geometric Primitives

Different philosophies:

- Collections of complex shapes
 - Spheres, cones, cylinders, tori, ...
- One simple type of geometric primitive
 - Triangles or triangle meshes
- Small set of complex primitives with adjustable parameters
 - E.g. “all polynomials of degree 2”
 - Splines, NURBS (details in CPSC 424)
 - Fractals

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Geometric Primitives

Mathematical representations:

- Explicit functions
- Parametric functions
- Implicit functions

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Explicit Functions

Curves:

- y is a function of x: $y := \sin(x)$
- Only works in 2D

Surfaces:

- z is a function of x and y: $z := \sin(x) + \cos(y)$
- Cannot define arbitrary shapes in 3D

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Parametric Functions

Curves:

- 2D: x and y are functions of a parameter value t
- 3D: x, y, and z are functions of a parameter value t

$$C(t) := \begin{pmatrix} \cos(t) \\ \sin(t) \\ t \end{pmatrix}$$

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Parametric Functions

Surfaces:

- Surface S is defined as a function of *parameter values* s, t
- Names of parameters can be different to match intuition:

$$S(\phi, \theta) := \begin{pmatrix} \cos(\phi) \cos(\theta) \\ \sin(\phi) \cos(\theta) \\ \sin(\theta) \end{pmatrix}$$

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Geometry Database

Implicit Surfaces:

- Surface is defined implicitly via the roots of a function
- E.g:

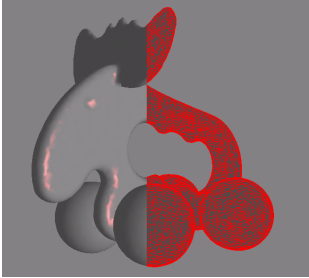
$$S(x, y, z) : x^2 + y^2 + z^2 - 1 = 0$$

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Geometry Database

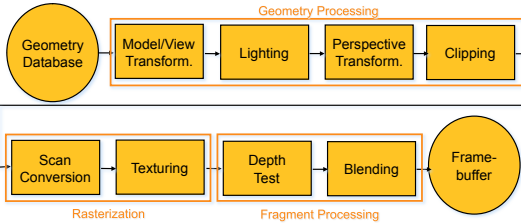
Triangles and Triangle Meshes:




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The Rendering Pipeline



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Modeling and Viewing Transformation


Modeling transformation:

- Map points from *object coordinate system* to *world coordinate system*
- Same as placing objects

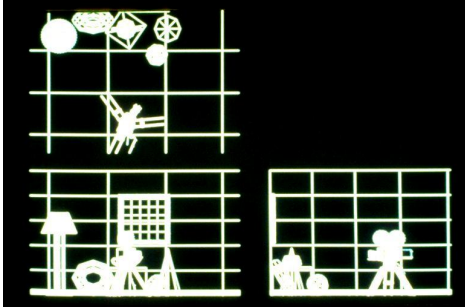
Viewing transformation:

- Map points from *world coordinate system* to *camera (or eye) coordinate system*
- Same as placing camera

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Modeling Transformation: Object Placement



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Viewing Transformation: Camera Placement

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Modeling and Viewing Transformation

Types of transformations:

- Rotations, scaling, shearing
- Translations
- Other transformations (not handled by rendering pipeline):
 - Freeform deformation

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Modeling and Viewing Transformation

Linear transformations

- Rotations, scaling, shearing
- Can be expressed as a 3x3 matrix
- E.g. rotation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

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Modeling and Viewing Transformation

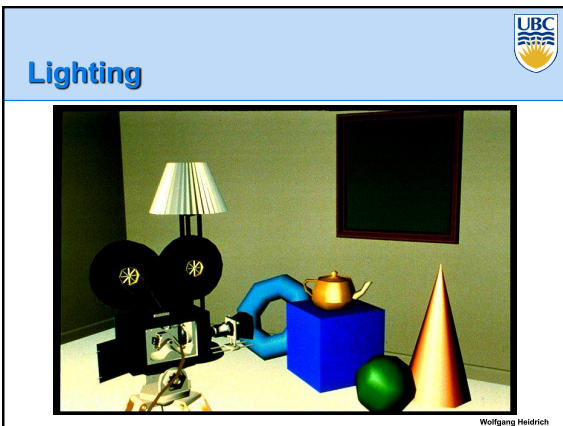
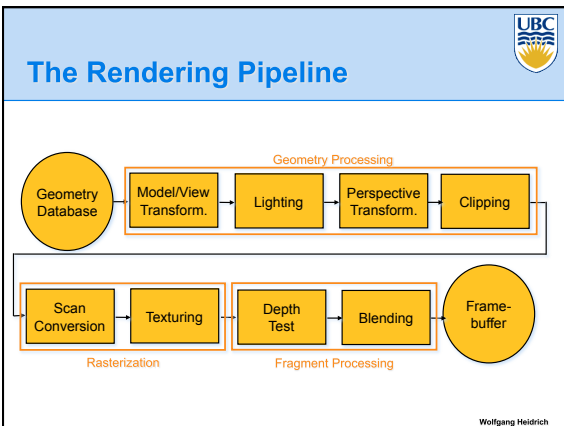
Affine transformations

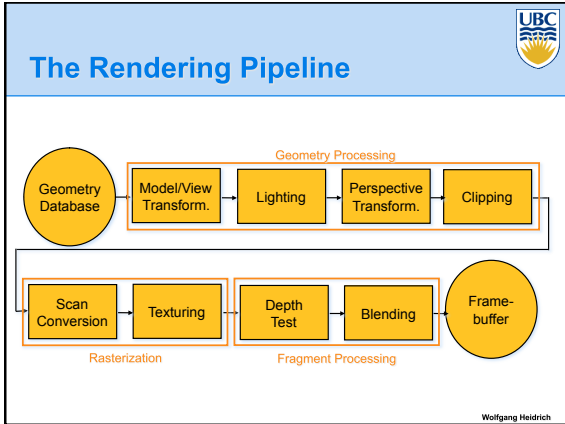
- Linear transformations + translations
- Can be expressed as a 3x3 matrix + 3 vector
- E.g. rotation + translation:

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 0 \\ \sin(\phi) & \cos(\phi) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \\ t_z \end{pmatrix}$$

- Another representation: 4x4 homogeneous matrix

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Perspective Transformation

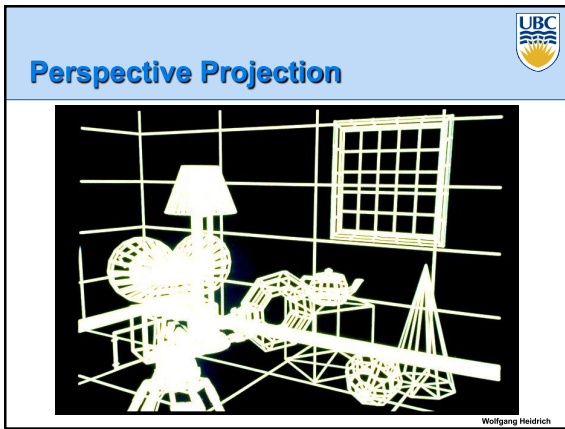
Purpose:

- Project 3D geometry onto a 2D image plane
- Simulates a camera

Camera model:

- Pinhole camera
- Other, more complex camera models also exist in computer graphics, but are less common
 - Thin lens cameras
 - Full simulation of lens geometry

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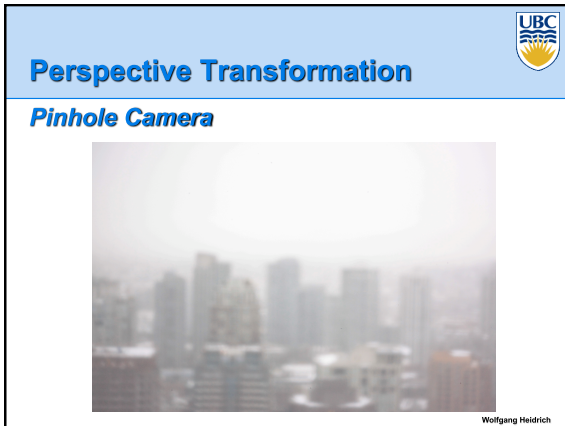


Perspective Transformation

Pinhole Camera:

- Light shining through a tiny hole into a dark room yields upside-down image on wall

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Pinhole Camera - Camera Obscura

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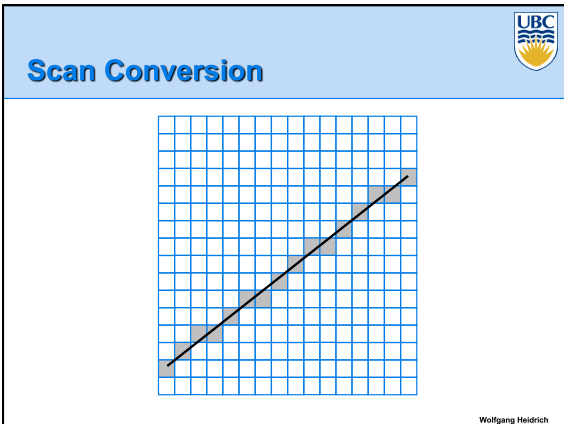
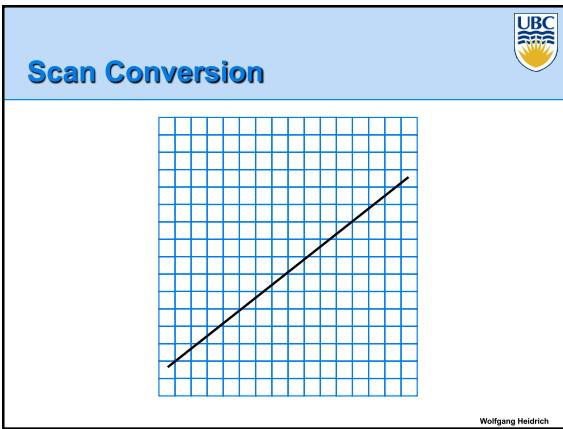
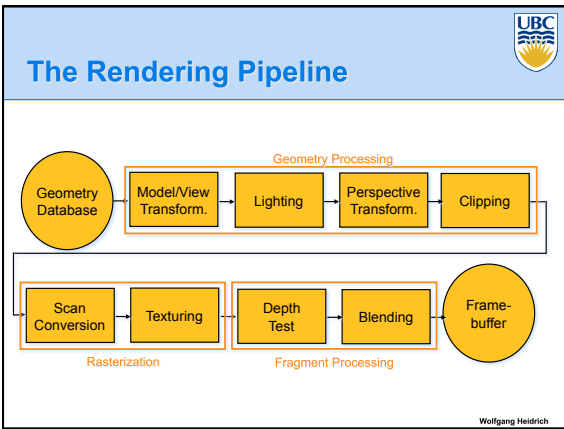
Perspective Transformation

In computer graphics:

- Image plane is conceptually *in front* of the center of projection

- Perspective transformations belong to a class of operations that are called *projective transformations*
- Linear and affine transformations also belong to this class
- All* projective transformations can be expressed as 4×4 matrix operations

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Scan Conversion

Problem:

- Line is infinitely thin, but image has finite resolution
- Results in steps rather than a smooth line
 - *Jaggies*
 - *Aliasing*
- One of the fundamental problems in computer graphics

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Scan Conversion

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Scan Conversion

Color interpolation

- Linearly interpolate per-pixel color from vertex color values
- Treat every channel of RGB color separately

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Scan Conversion

Color interpolation

Example:

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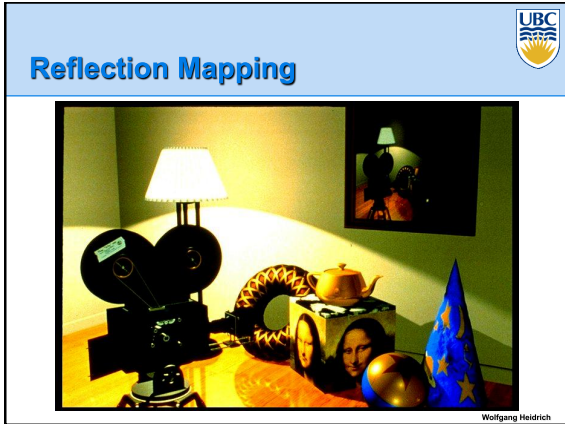
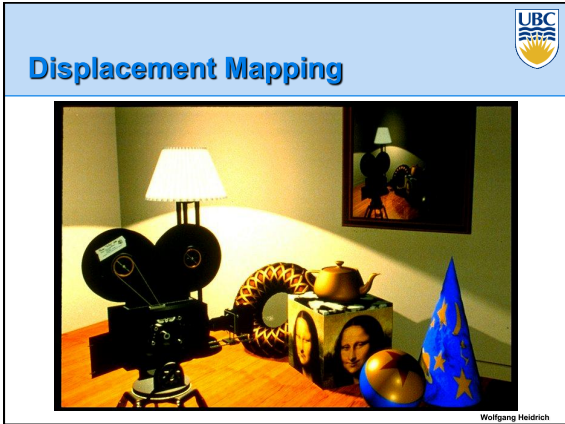
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Texturing

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Texture Mapping

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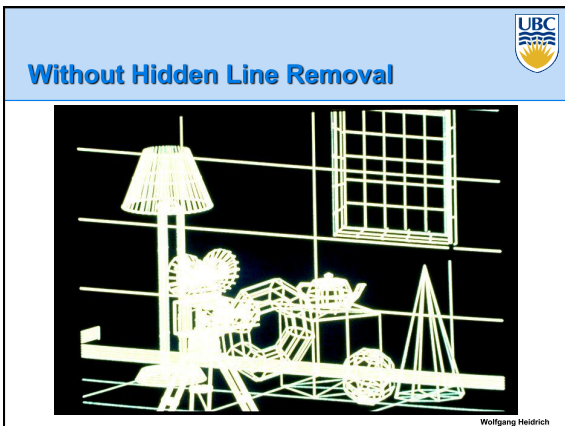
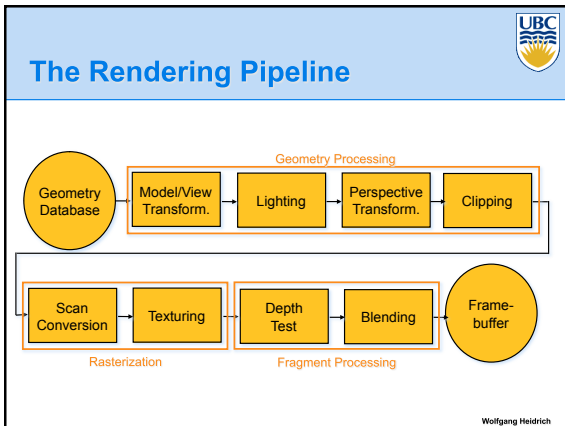


Texturing

Issues:

- How to map pixel from texture (*texels*) to screen pixels
 - Texture can appear widely distorted in rendering
 - Magnification / minification of textures
- Filtering of textures
- Preventing aliasing (anti-aliasing)

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Hidden Surface Removal

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Depth Test / Hidden Surface Removal

Remove invisible geometry

- Parts that are hidden behind other geometry

Possible Implementations:

- Per-fragment decision
 - Depth buffer
- Object space decision
 - Clipping polygons against each other
 - Sorting polygons by distance from camera

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Depth Test / Hidden Surface Removal

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The Rendering Pipeline

```

    graph LR
      subgraph Geometry_Processing [Geometry Processing]
        GD((Geometry Database)) --> MVT[Model/View Transform.]
        MVT --> L[Lighting]
        L --> PT[Perspective Transform.]
        PT --> C[Clipping]
      end
      subgraph Rasterization
        C --> SC[Scan Conversion]
        SC --> T[Texturing]
        T --> DT[Depth Test]
        DT --> B[Blending]
      end
      subgraph Fragment_Processing [Fragment Processing]
        B --> FB((Frame-buffer))
      end
  
```

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Display Technology

Cathod Ray Tubes (CRTs)

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Display Technology

Raster Scan Electron Beam

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Display Technology

Interlaced Scanning

Start Horizontal scan direction

Vertical scan direction

Line 1 active scan

Line 1 flyback

Vertical flyback

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Display Technology

Color CRTs

Triplets

Shadow mask („dot type“)

3 electron beams

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Display Technology

Trinitron CRTs

electron gun assembly

Trinitron slit type shadow mask

shadow mask („aperture grill“, „harp“)

phosphor layer

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Display Technology

Liquid Crystal Displays (LCD)

ON OFF

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Display Technology

High Dynamic Range Displays

Luminance (log cd/m²)

-6 -4 -2 0 2 4 6 8

starlight moonlight indoor lighting sunlight

Range of Illumination

scotopic mesopic photopic

Visual Function

No colour vision Good colour vision

Poor acuity Good acuity

Human Simultaneous Visual Range

Conventional Display Luminance

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Display Technology

HDR Display Principle

High resolution Colour Image


High Dynamic Range Display

Low resolution Luminance Modulated Second Image

Low resolution LED Array

- Modulated LED array
- Conventional LCD
- Image compensation

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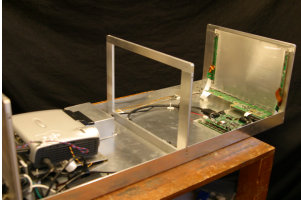
**Prototype Setup:
Projector/LCD Panel** 

Hardware setup:

- Remove backlight from LCD panel
- Shine image from video projector onto back of panel
 - (Fresnel lens for focusing)
- Multiplies dynamic range of LCD and projector

Measured:

- Contrast: 50,000:1
- Intensity: 2,700 cd/m²



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**Brightside Technologies / Dolby
Commercial Display** 

18" prototype:
Zeetzen 5



37" commercial prototype
DR-37P



**LG Philips -
"Local Area Luminance Control"** 




47-inch LED Backlight System 

High Color Gamut and Local Area Luminance Control

- Active Area : 1029.88 (H) X 584.82 (V) mm
- Resolution : 1024 (H) X 768 (V)
- Pixel Density : 47 ppi
- Number of Colors : 1.07 Billion
- Color Gamut : 100 %
- Color Temperature : 12,000 K
- Luminance : 500 cd/m²
- Contrast Ratio : Mega CR
- Display Mode : 5-IPS
- Viewing Angle : 178°, 178° (D.O. B.I.)
- Response Time : 4 ms (GTR)
- Power Consumption : < 200 W @ Dynamic

AVING news network
LG PHILIPS LED

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Coming Up... 

Next week:

- Geometric Transformations (Affine, Perspective)

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