



University of British Columbia
CPSC 314 Computer Graphics
Jan-Apr 2010

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Viewing/Projection VI, Vision/Color

Week 5, Wed Feb 2

<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2010>

News

- showing up for your project grading slot is **not** optional
 - 2% penalty for noshows
- signing up for your project grading slot is **not** optional
 - 2% penalty for nosignups within two days of due date
 - your responsibility to sign up for slot
 - not ours to hunt you down if you chose to skip class on signup days
- we do make best effort to accomodate change requests via email to grader for that project
- take a few minutes to review your code/README to reload your mental buffers
 - TA will ask you questions about how you did things

News

- Homework 2 out
 - due Fri Feb 12 5pm
- Project 2 out
 - due Tue Mar 2 5pm
 - moved due date to after break after pleas of pre-break overload with too many assignments due
 - start early, do *not* leave until late in break!!
- reminder
 - extra handouts in lab

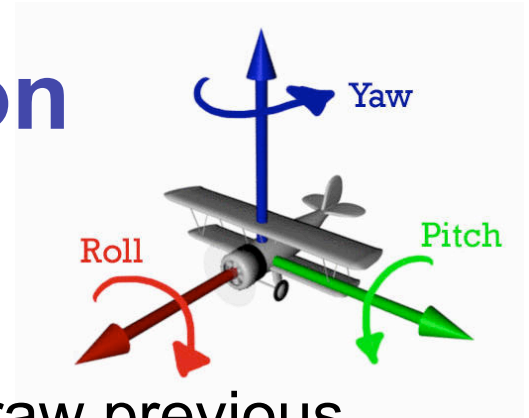
Project 2: RCSS

- solar system
 - planets spin around own axis and sun
 - moon spins around earth
- two spaceships: mothership and scoutship
 - one window for each
 - may see geometry of one spaceship through window of other
- navigation modes
 - solar system coord (absolute) rotate/translate
 - through the lens flying (relative to camera)
 - geosynchronous orbit around planet
 - zoom in/out towards center of planet

Project 2 Hints

- don't forget to keep viewing and projections in their respective stacks
- try drawing scene graphs to help you figure out how to place multiple cameras
 - especially geosynchronous: camera as child of object in world in the scene graph
 - geometric representation of camera vs. what is shown through its window
- disk for Saturn rings: try scaling sphere by 0
- OK to reset camera position between absolute/relative navigation modes
- OK to have camera jumpcut to different orientation when new planet picked in geosync mode

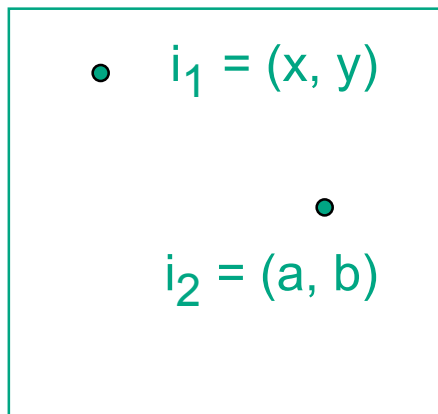
Review/More: Relative Motion



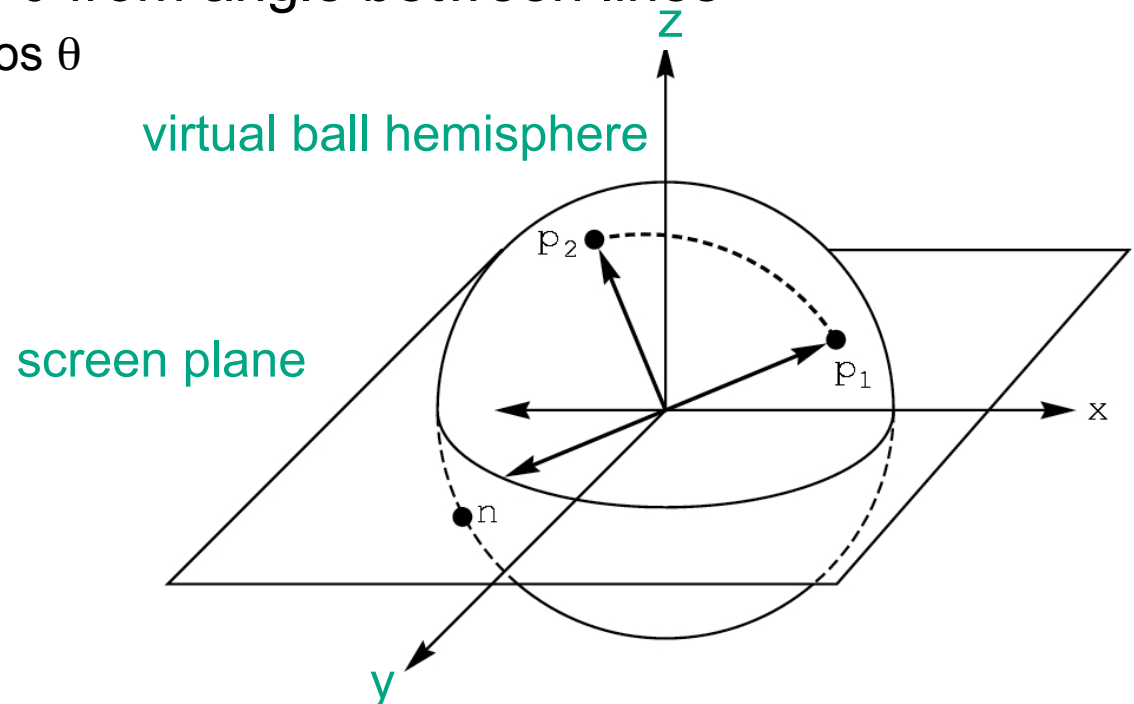
- how to move relative to current camera?
 - what you see in the window
- computation in coordinate system used to draw previous frame is simple:
 - incremental change I to current C
 - each time we just want to premultiply by new matrix
 - $p' = I C p$
 - but we know that OpenGL only supports postmultiply by new matrix
 - $p' = C I p$
- use OpenGL matrix stack as calculator/storage!
 - dump out modelview matrix **from previous frame** with `glGetDoublev()`
 - C = current camera coordinate matrix
 - wipe the matrix stack with `glLoadIdentity()`
 - apply incremental update matrix I
 - apply current camera coord matrix C

Review/Clarify: Trackball Rotation

- user drags between two points on image plane
 - mouse down at $i_1 = (x, y)$, mouse up at $i_2 = (a, b)$
- find corresponding points on virtual ball
 - $p_1 = (x, y, z)$, $p_2 = (a, b, c)$
- compute rotation angle and axis for ball
 - axis of rotation is plane normal: cross product $p_1 \times p_2$
 - amount of rotation θ from angle between lines
 - $p_1 \cdot p_2 = |p_1| |p_2| \cos \theta$



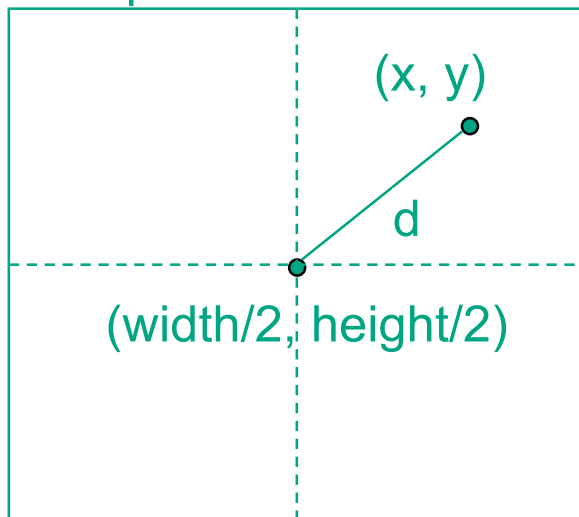
screen plane



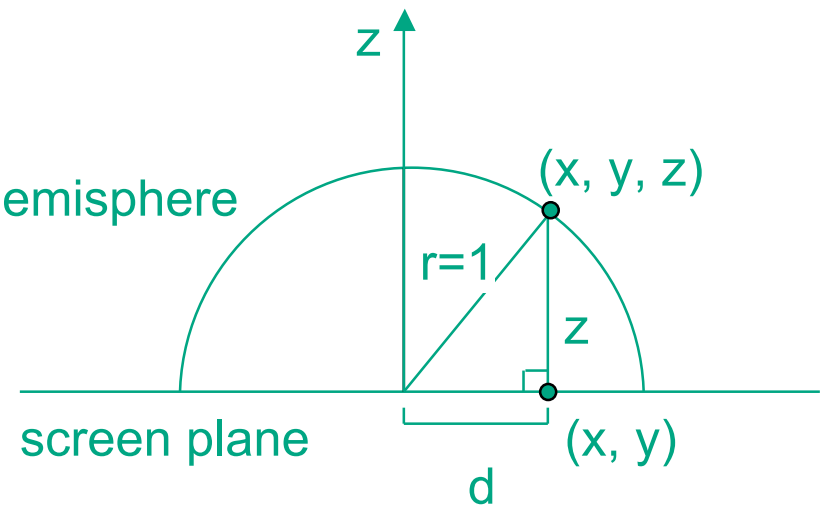
Clarify: Trackball Rotation

- finding location on ball corresponding to click on image plane
 - ball radius r is 1

screen plane

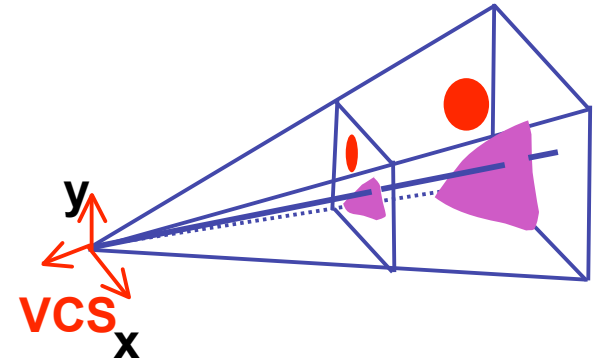


virtual ball hemisphere

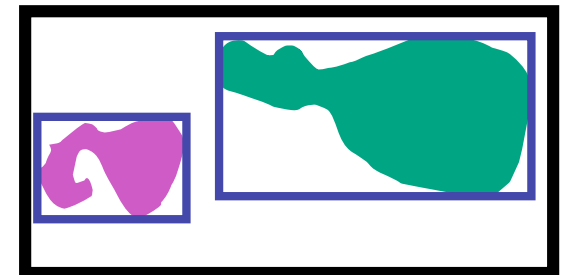


Review: Picking Methods

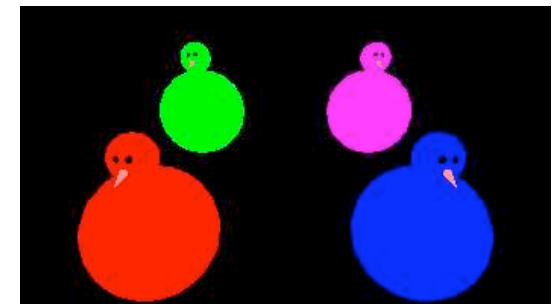
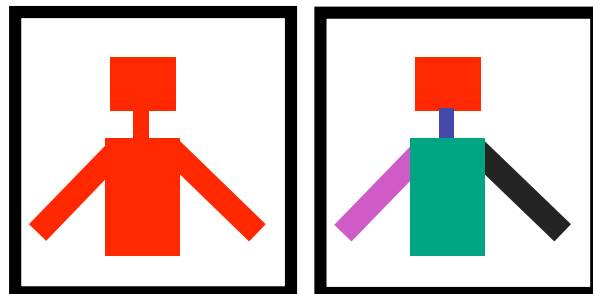
- manual ray intersection



- bounding extents



- backbuffer coding



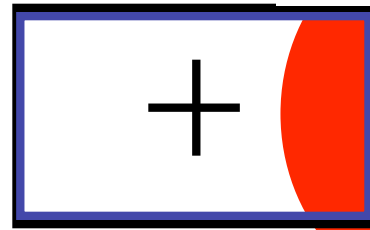
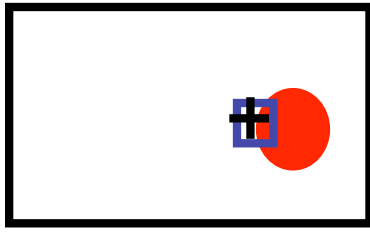
Review: Select/Hit Picking

- use small region around cursor for viewport
- assign per-object integer keys (names)
- redraw in special mode
- store hit list of objects in region
- examine hit list

- OpenGL support

Viewport

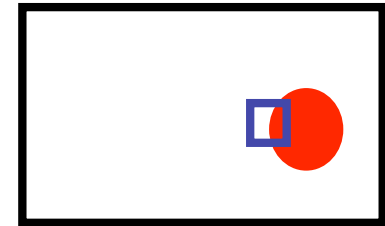
- small rectangle around cursor
 - change coord sys so fills viewport



- why rectangle instead of point?
 - people aren't great at positioning mouse
 - Fitts' Law: time to acquire a target is function of the distance to and size of the target
 - allow several pixels of slop

Viewport

- nontrivial to compute
 - invert viewport matrix, set up new orthogonal projection
- simple utility command
 - `gluPickMatrix(x,y,w,h,viewport)`
 - `x,y`: cursor point
 - `w,h`: sensitivity/slop (in pixels)
 - push old setup first, so can pop it later



Render Modes

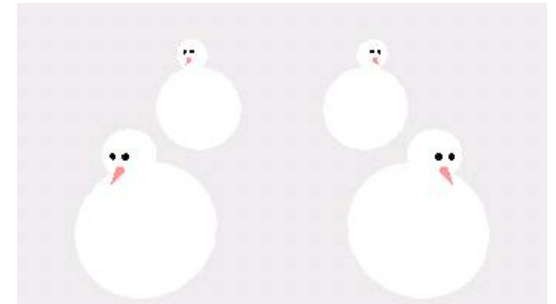
- `glRenderMode(mode)`
 - `GL_RENDER`: normal color buffer
 - default
 - `GL_SELECT`: selection mode for picking
 - (`GL_FEEDBACK`: report objects drawn)

Name Stack

- again, "names" are just integers
 - glInitNames()
- flat list
 - glLoadName(name)
- or hierarchy supported by stack
 - glPushName(name), glPopName
 - can have multiple names per object

Hierarchical Names Example

```
for(int i = 0; i < 2; i++) {  
    glPushName(i);  
    for(int j = 0; j < 2; j++) {  
        glPushMatrix();  
        glPushName(j);  
        glTranslatef(i*10.0,0,j * 10.0);  
        glPushName(HEAD);  
        glCallList(snowManHeadDL);  
        glLoadName(BODY);  
        glCallList(snowManBodyDL);  
        glPopName();  
    }  
    glPopName();  
    glPopMatrix();  
}
```



<http://www.lighthouse3d.com/opengl/picking/>

Hit List

- `glSelectBuffer(bufferSize, *buffer)`
 - where to store hit list data
- on hit, copy entire contents of name stack to output buffer.
- hit record
 - number of names on stack
 - minimum and minimum depth of object vertices
 - depth lies in the NDC z range [0,1]
 - format: multiplied by $2^{32} - 1$ then rounded to nearest int

Integrated vs. Separate Pick Function

- integrate: use same function to draw and pick
 - simpler to code
 - name stack commands ignored in render mode
- separate: customize functions for each
 - potentially more efficient
 - can avoid drawing unpickable objects

Select/Hit

- advantages
 - faster
 - OpenGL support means hardware acceleration
 - avoid shading overhead
 - flexible precision
 - size of region controllable
 - flexible architecture
 - custom code possible, e.g. guaranteed frame rate
- disadvantages
 - more complex

Hybrid Picking

- select/hit approach: fast, coarse
 - object-level granularity
- manual ray intersection: slow, precise
 - exact intersection point
- hybrid: both speed and precision
 - use select/hit to find object
 - then intersect ray with that object

High-Precision Picking with OpenGL

- gluUnproject
 - transform window coordinates to object coordinates given current projection and modelview matrices
 - use to create ray into scene from cursor location
 - call gluUnProject twice with same (x,y) mouse location
 - z = near: (x,y,0)
 - z = far: (x,y,1)
 - subtract near result from far result to get direction vector for ray
- use this ray for line/polygon intersection

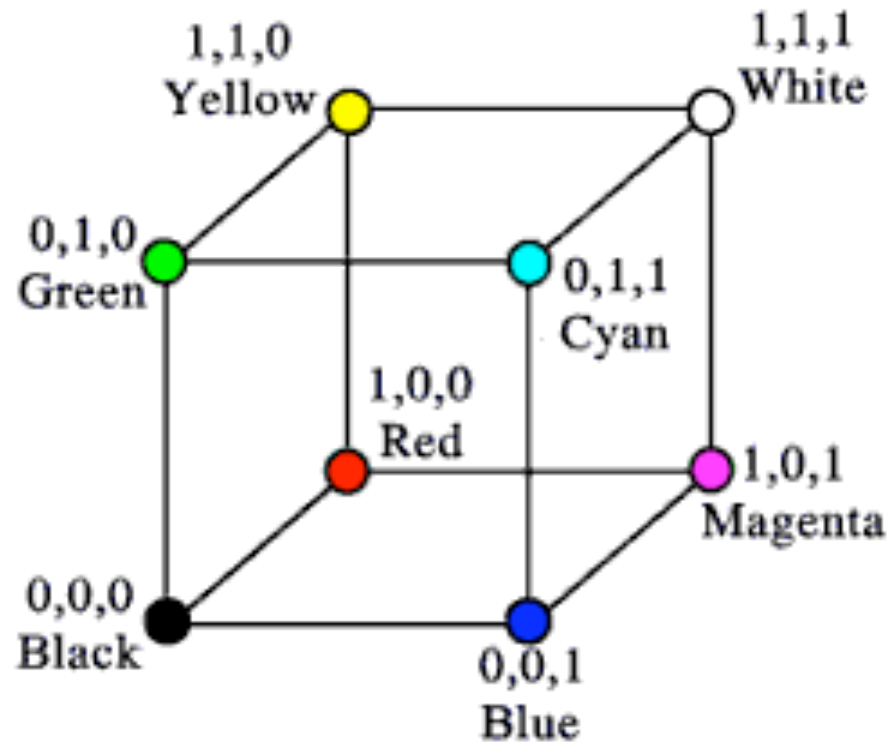
Vision/Color

Reading for Color

- RB Chap Color
- FCG Sections 3.2-3.3
- FCG Chap 20 Color
- FCG Chap 21.2.2 Visual Perception (Color)

RGB Color

- triple (r, g, b) represents colors with amount of red, green, and blue
 - hardware-centric
 - used by OpenGL



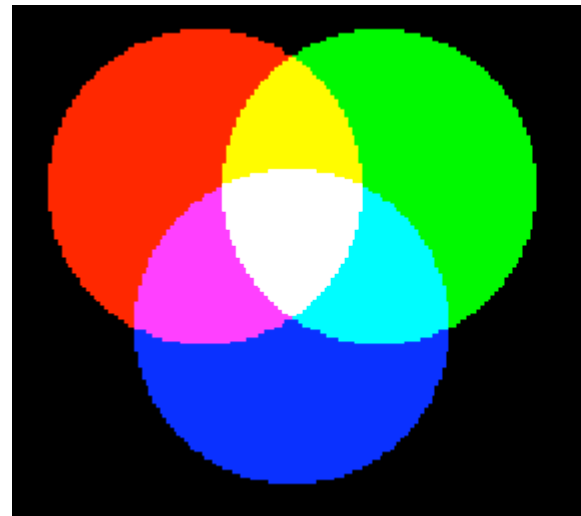
Alpha

- fourth component for transparency
 - (r, g, b, α)
- fraction we can see through
 - $c = \alpha c_f + (1 - \alpha) c_b$
- more on compositing later

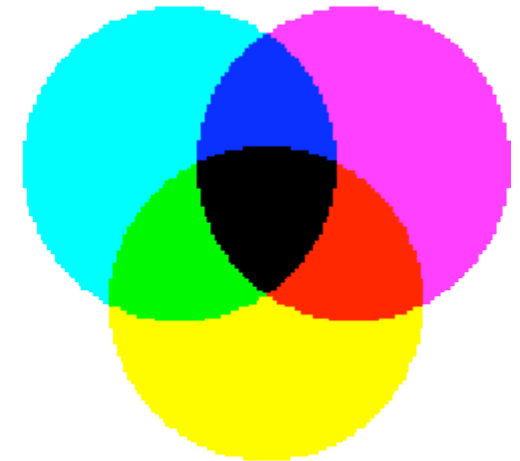
Additive vs. Subtractive Colors

- additive: light
 - monitors, LCDs
 - RGB model
- subtractive: pigment
 - printers
 - CMY model
 - dyes absorb light

$$\begin{bmatrix} C \\ M \\ Y \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$



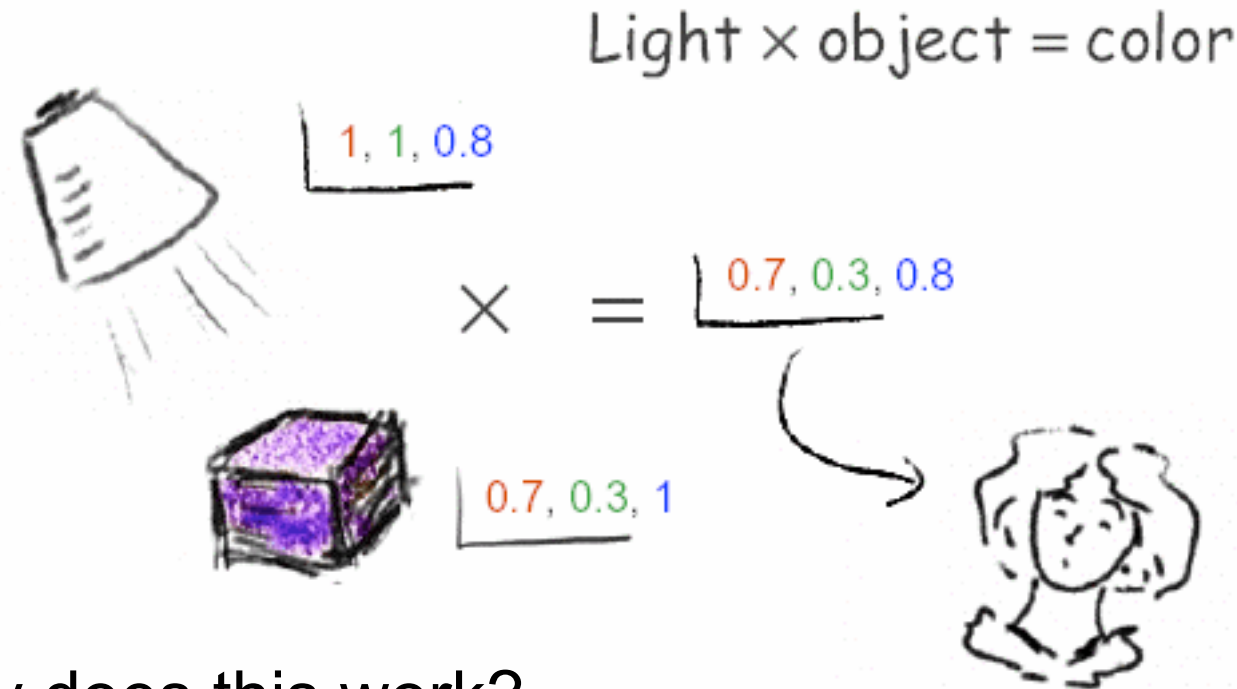
additive



subtractive₂₅

Component Color

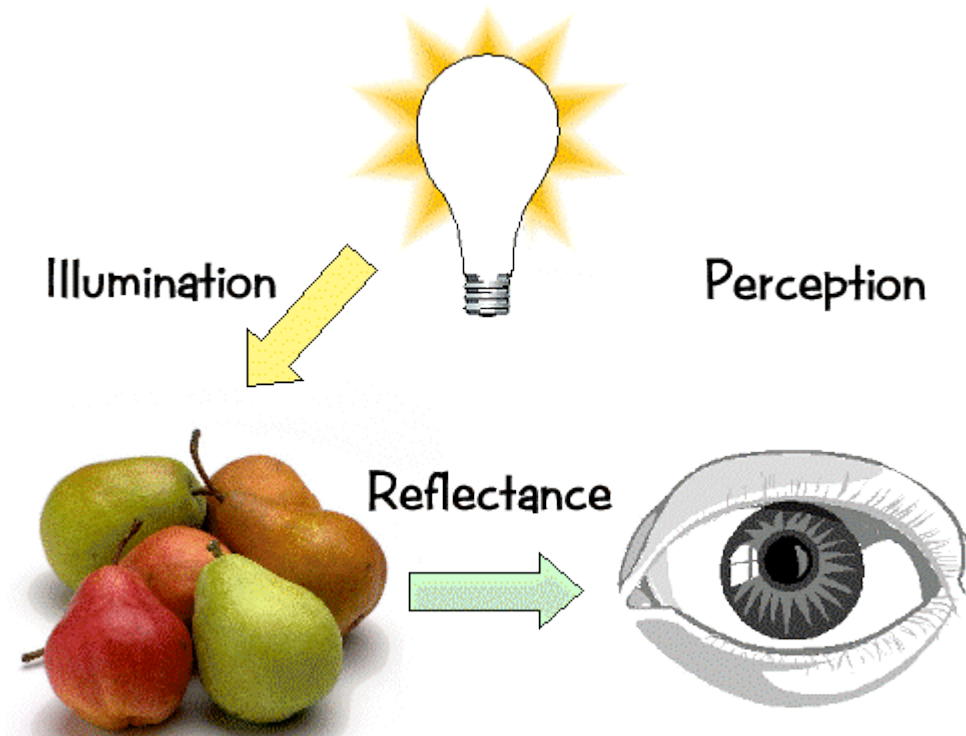
- component-wise multiplication of colors
 - $(a_0, a_1, a_2) * (b_0, b_1, b_2) = (a_0 * b_0, a_1 * b_1, a_2 * b_2)$



- why does this work?
 - must dive into light, human vision, color spaces

Basics Of Color

- elements of color:



Basics of Color

- physics
 - illumination
 - electromagnetic spectra
 - reflection
 - material properties
 - surface geometry and microgeometry
 - polished versus matte versus brushed
- perception
 - physiology and neurophysiology
 - perceptual psychology

Light Sources

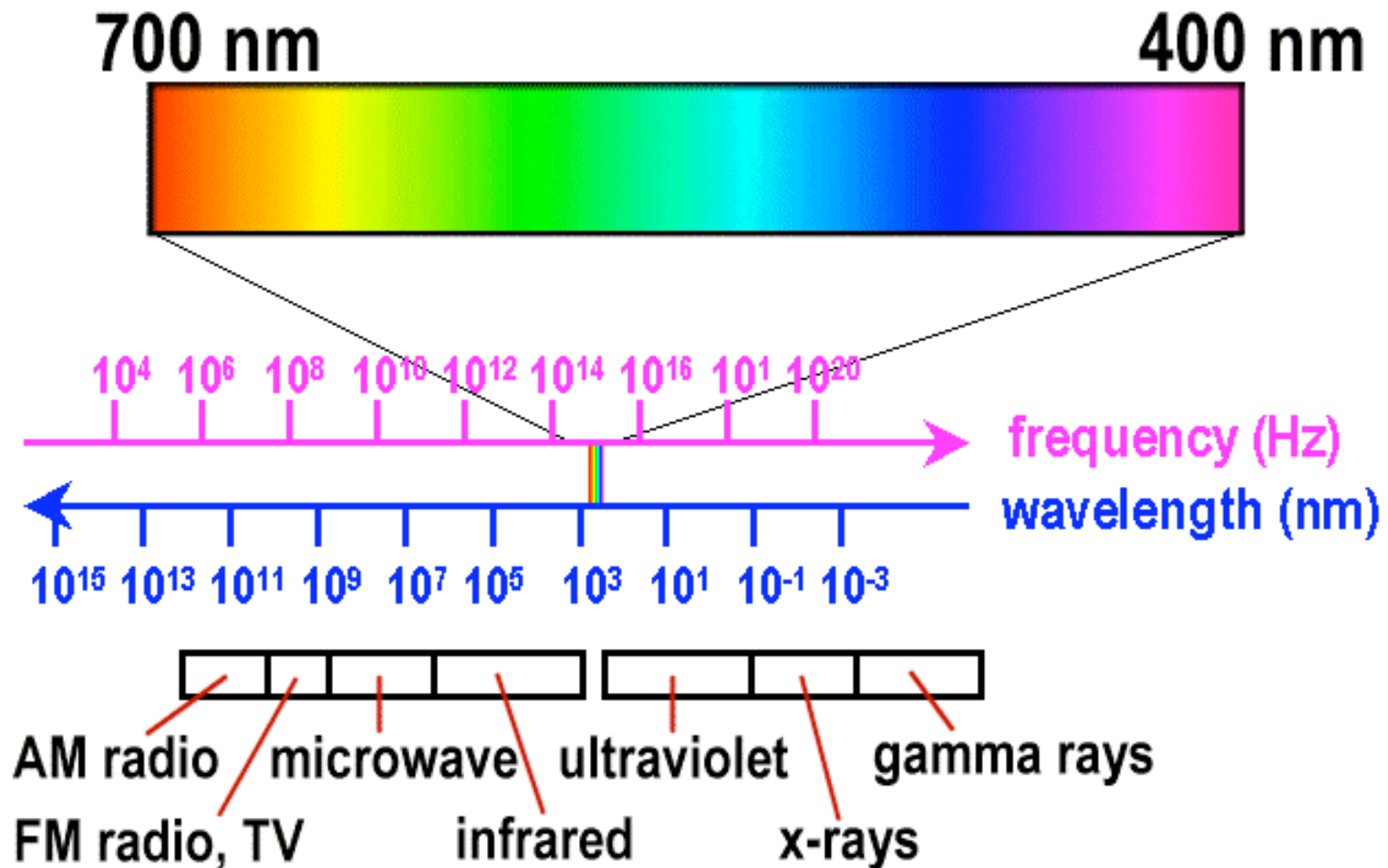
- common light sources differ in kind of spectrum they emit:
 - continuous spectrum
 - energy is emitted at all wavelengths
 - blackbody radiation
 - tungsten light bulbs
 - certain fluorescent lights
 - sunlight
 - electrical arcs
 - line spectrum
 - energy is emitted at certain discrete frequencies

Blackbody Radiation

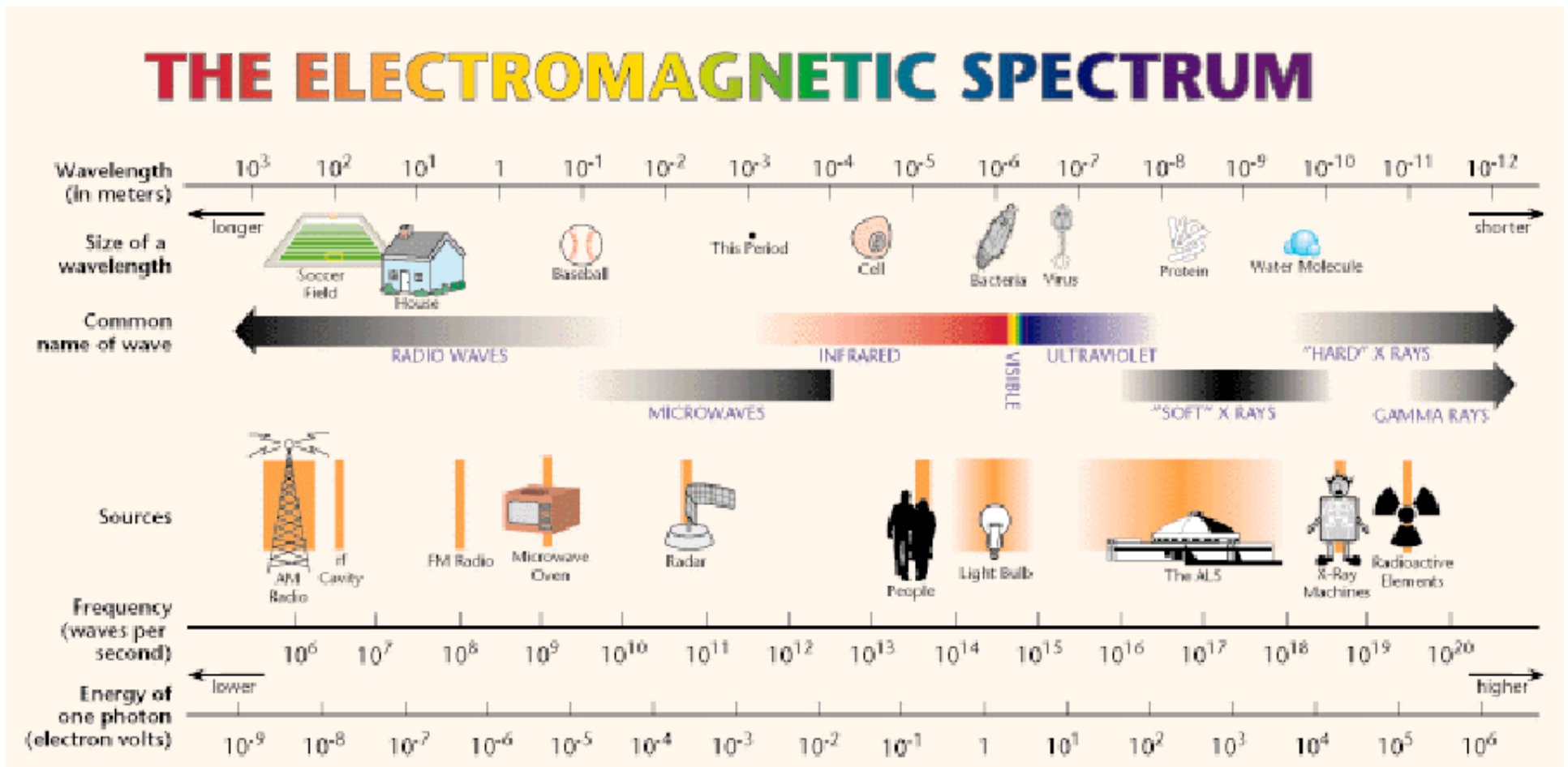
- black body
 - dark material, so that reflection can be neglected
 - spectrum of emitted light changes with temperature
 - this is the origin of the term “color temperature”
 - e.g. when setting a white point for your monitor
 - cold: mostly infrared
 - hot: reddish
 - very hot: bluish
 - demo:



Electromagnetic Spectrum

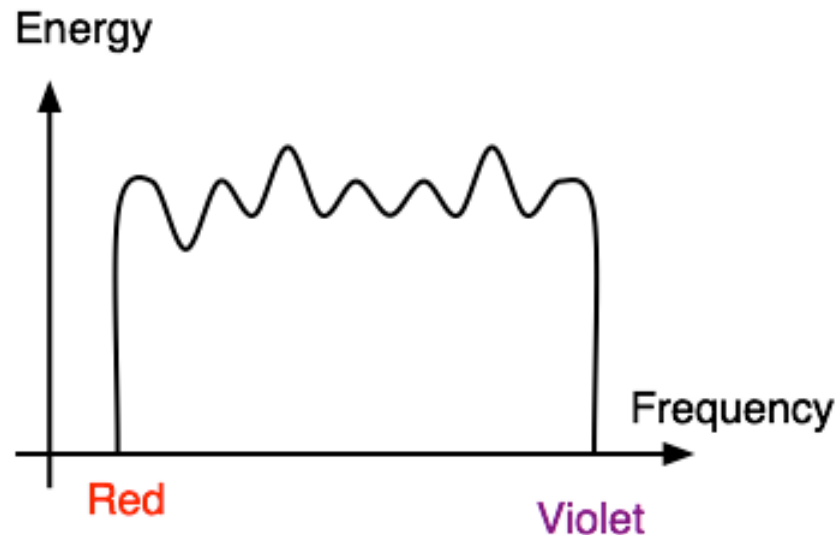


Electromagnetic Spectrum



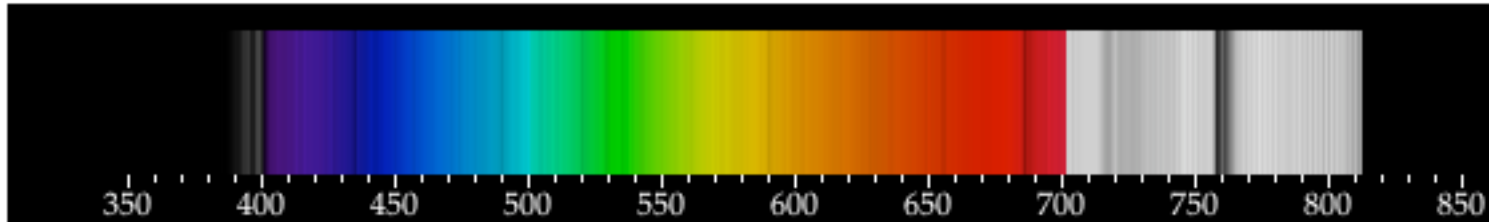
White Light

- sun or light bulbs emit all frequencies within visible range to produce what we perceive as "white light"

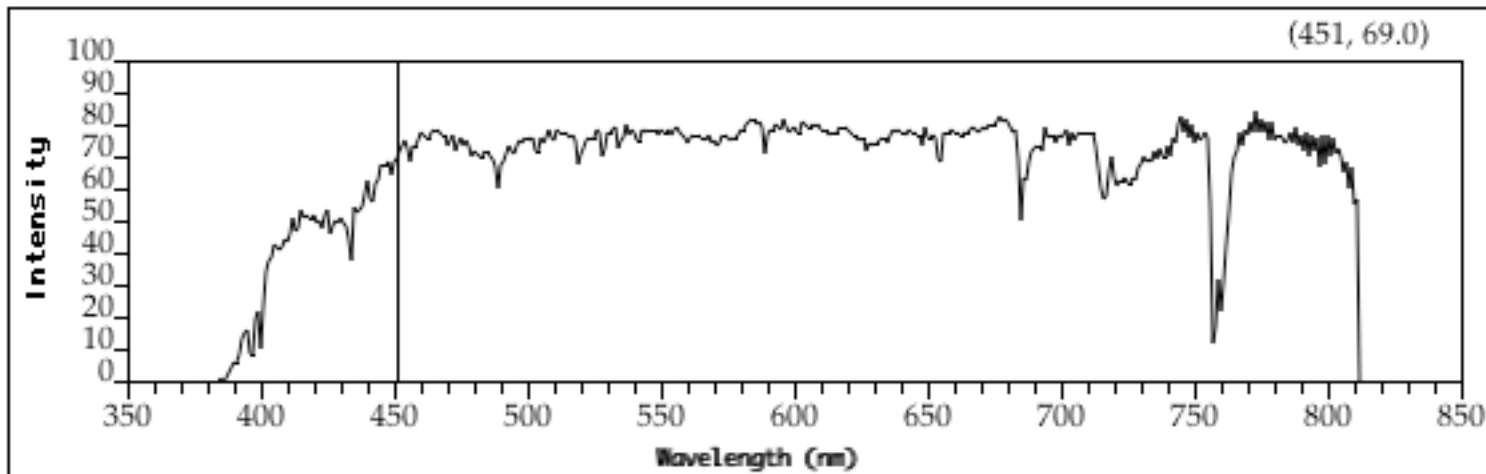


Sunlight Spectrum

- spectral distribution: power vs. wavelength



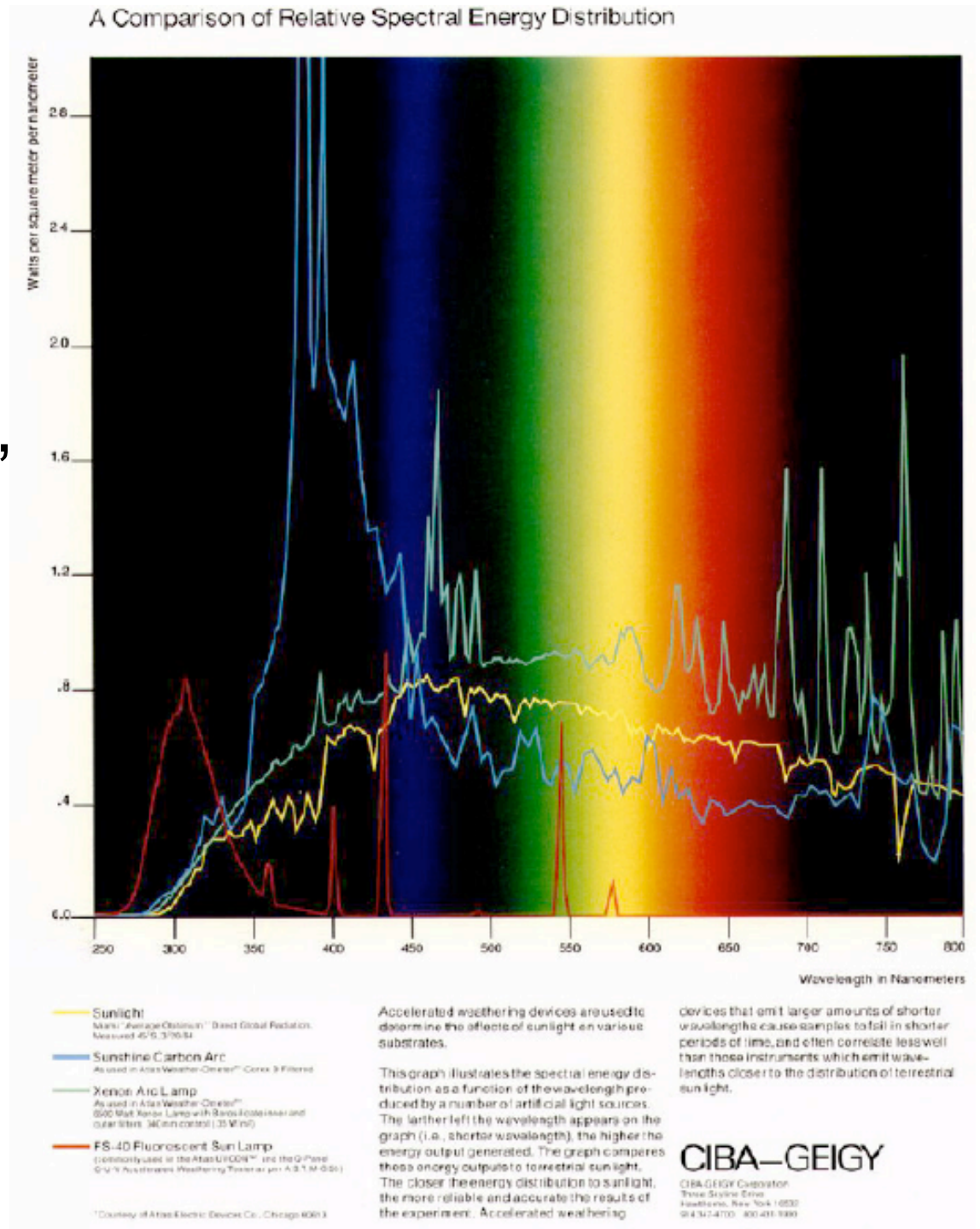
Emission Graph



Electromagnetic Spectrum

Continuous Spectrum

- sunlight
- various “daylight” lamps

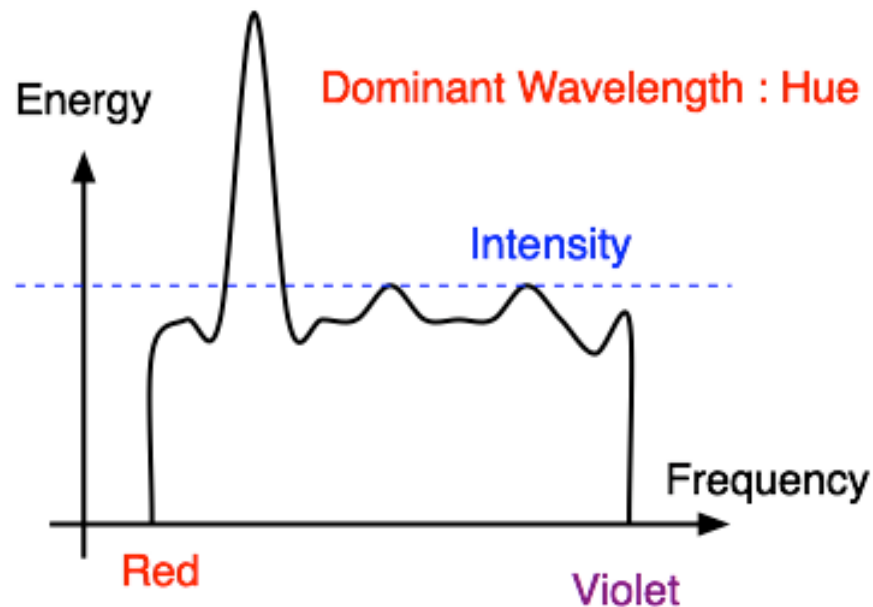


White Light and Color

- when white light is incident upon an object, some frequencies are reflected and some are absorbed by the object
- combination of frequencies present in the reflected light that determines what we perceive as the color of the object

Hue

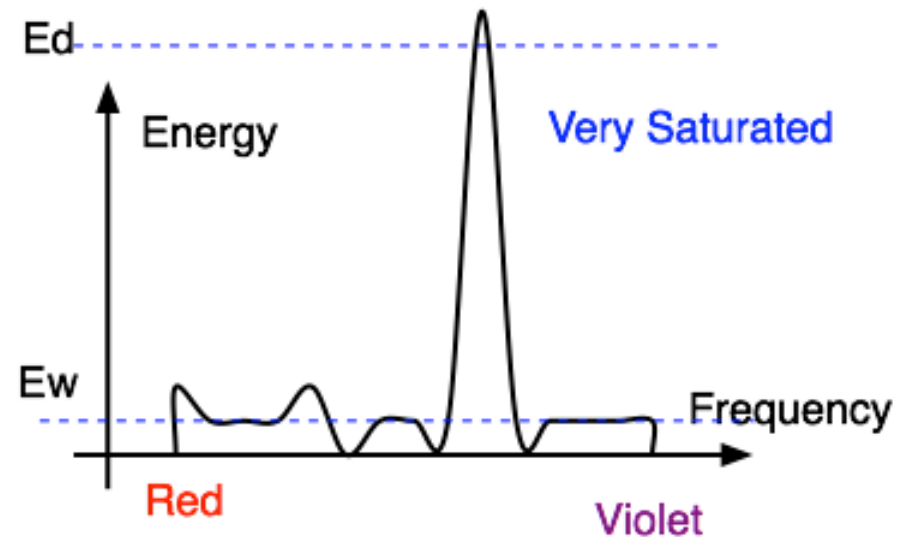
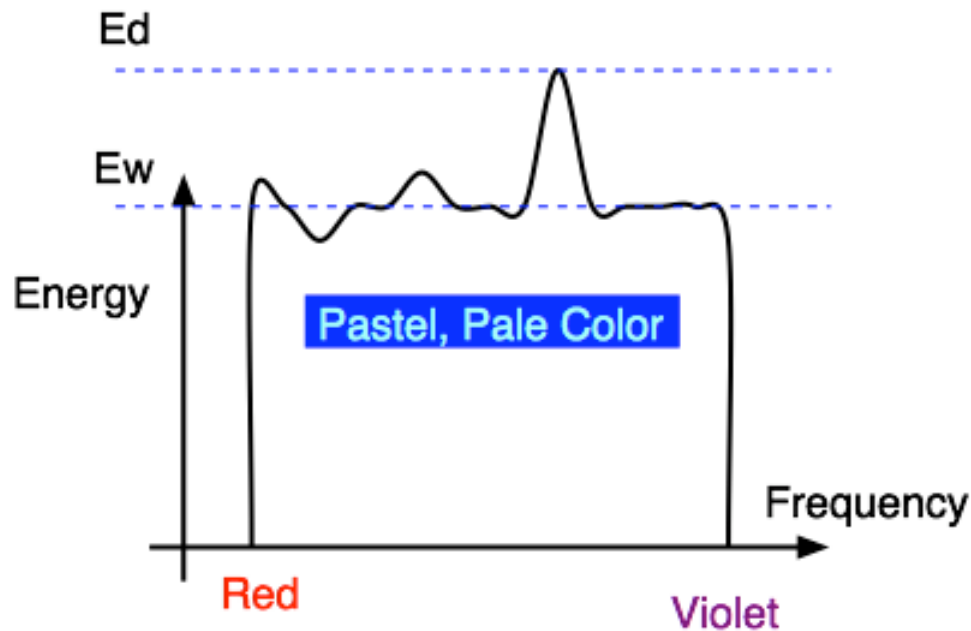
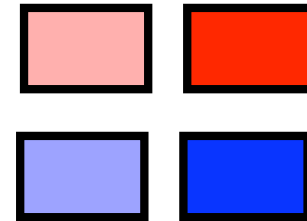
- hue (or simply, "color") is dominant wavelength/frequency



- integration of energy for all visible wavelengths is proportional to intensity of color

Saturation or Purity of Light

- how washed out or how pure the color of the light appears
 - contribution of dominant light vs. other frequencies producing white light
 - saturation: how far is color from grey
 - pink is less saturated than red
 - sky blue is less saturated than royal blue



Intensity vs. Brightness

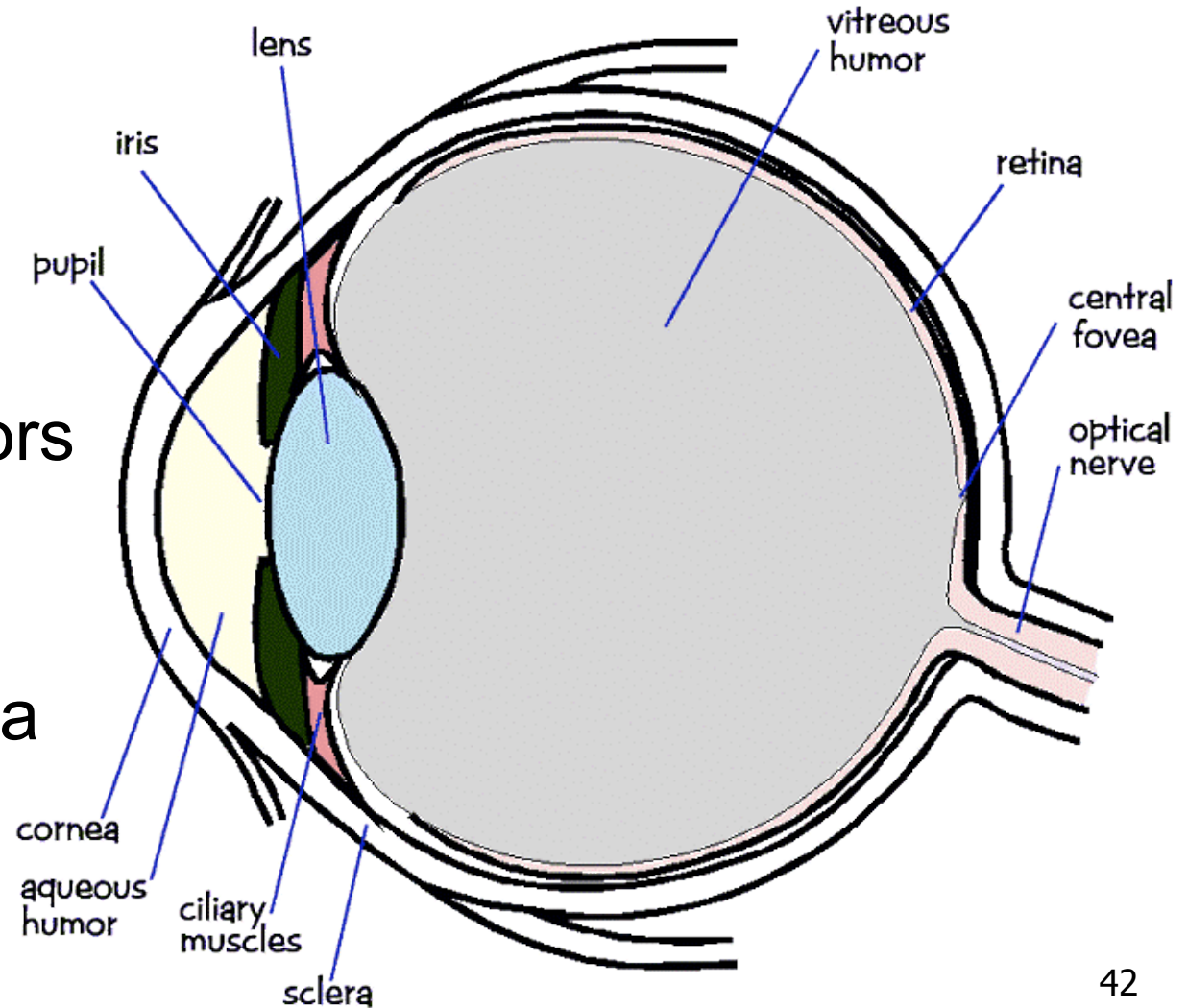
- intensity : physical term
 - **measured** radiant energy emitted per unit of time, per unit solid angle, and per unit projected area of the source (related to the luminance of the source)
- lightness/brightness: **perceived** intensity of light
 - nonlinear

Perceptual vs. Colorimetric Terms

- Perceptual
 - Hue
 - Saturation
 - Lightness
 - *reflecting objects*
 - Brightness
 - *light sources*
- Colorimetric
 - Dominant wavelength
 - Excitation purity
 - Luminance
 - Luminance

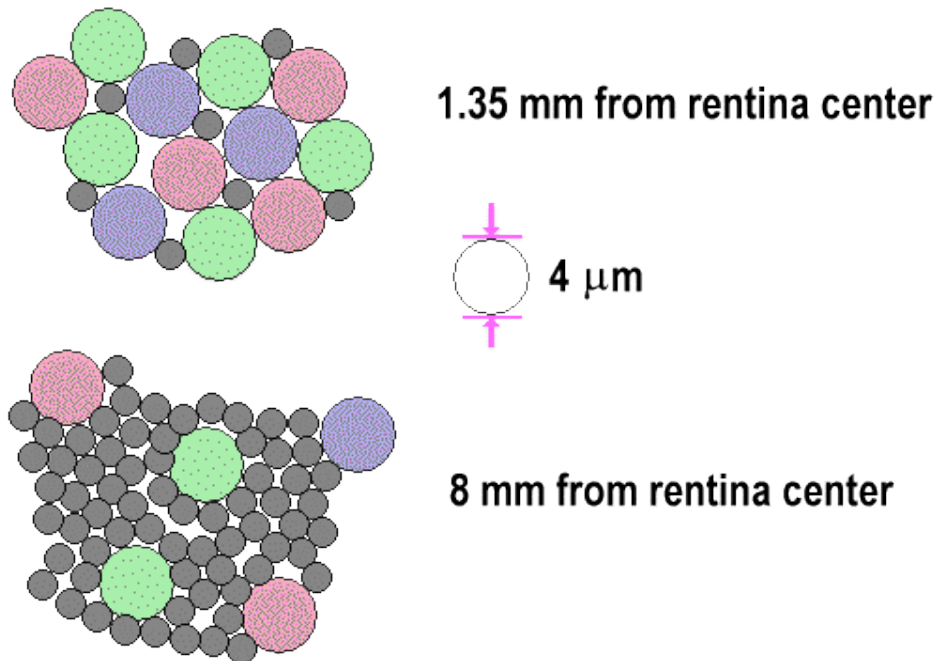
Physiology of Vision

- the retina
 - rods
 - b/w, edges
 - **cones**
 - 3 types
 - **color** sensors
 - uneven distribution
 - dense fovea



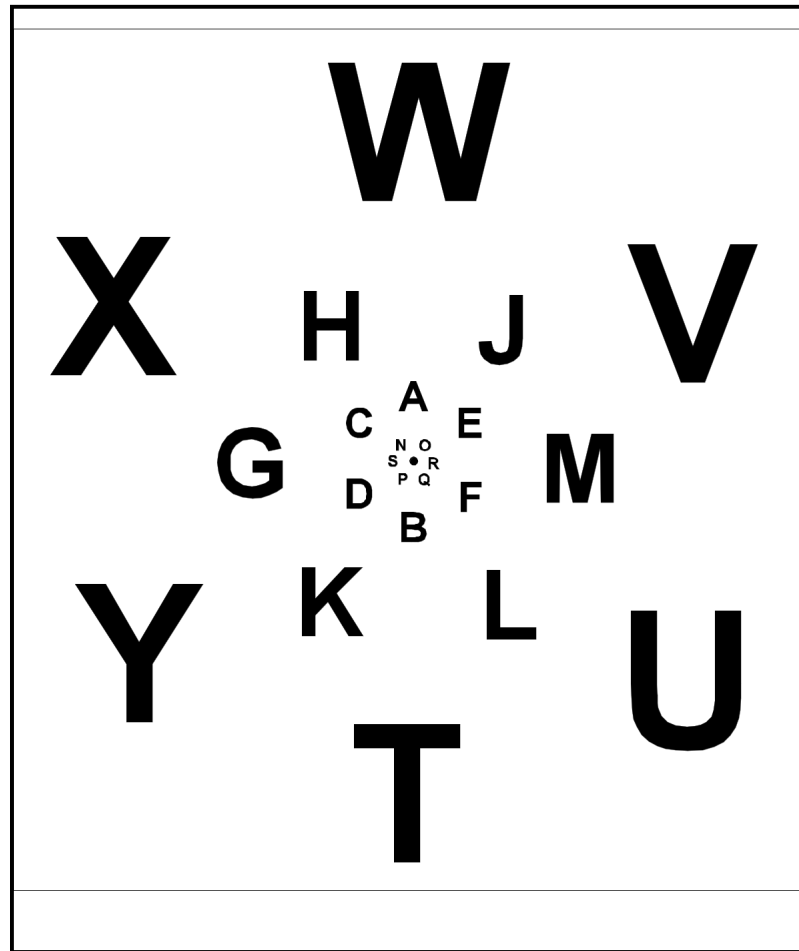
Physiology of Vision

- Center of retina is densely packed region called the *fovea*.
 - Cones much denser here than the *periphery*



Foveal Vision

- hold out your thumb at arm's length

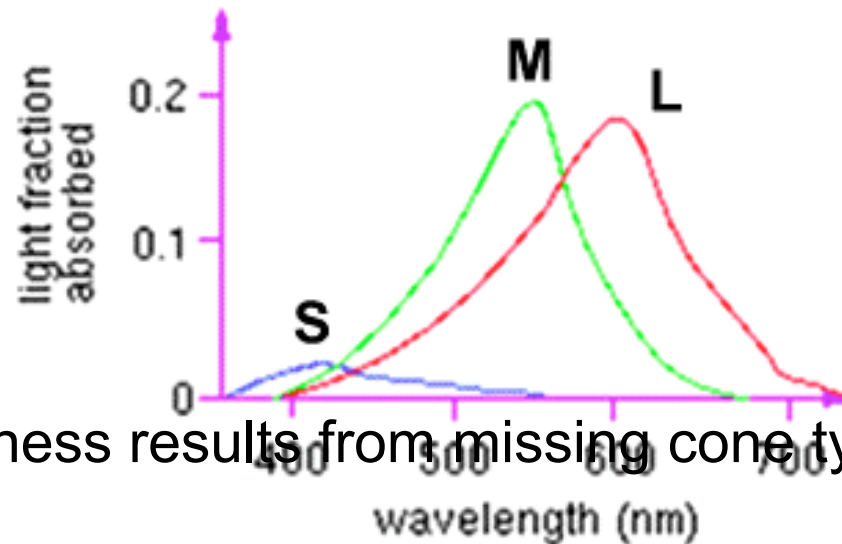


Tristimulus Theory of Color Vision

- Although light sources can have extremely complex spectra, it was empirically determined that colors could be described by only 3 primaries
- Colors that look the same but have different spectra are called metamers

Trichromacy

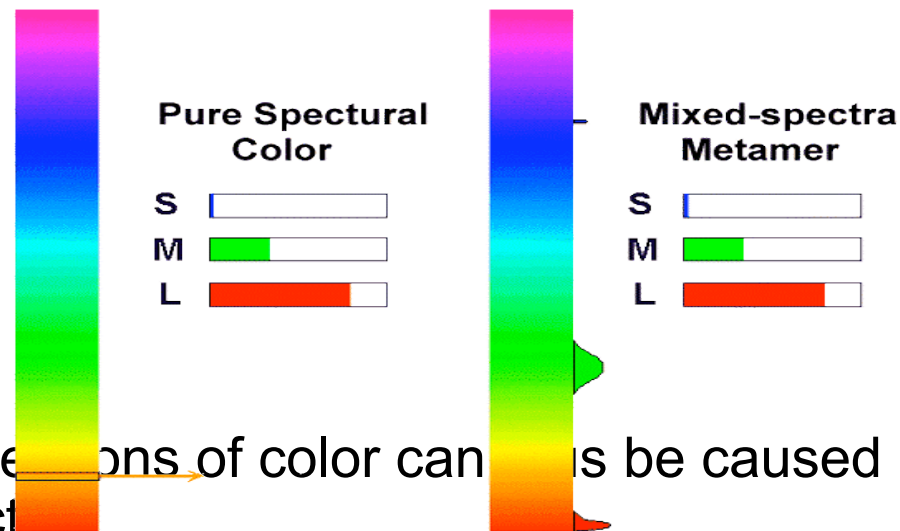
- three types of cones
 - L or R, most sensitive to red light (610 nm)
 - M or G, most sensitive to green light (560 nm)
 - S or B, most sensitive to blue light (430 nm)



- color blindness results from missing cone type(s)

Metamers

- a given perceptual sensation of color derives from the stimulus of all three cone types

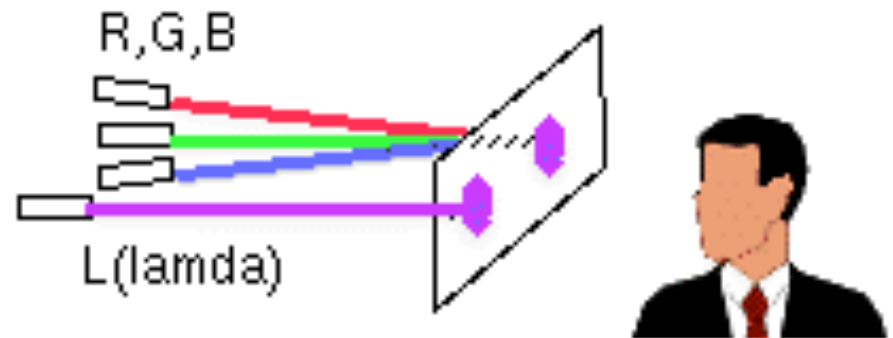


- identical perceptions of color can be caused by very different spectra
- demo

http://www.cs.brown.edu/exploratories/freeSoftware/catalogs/color_theory.html

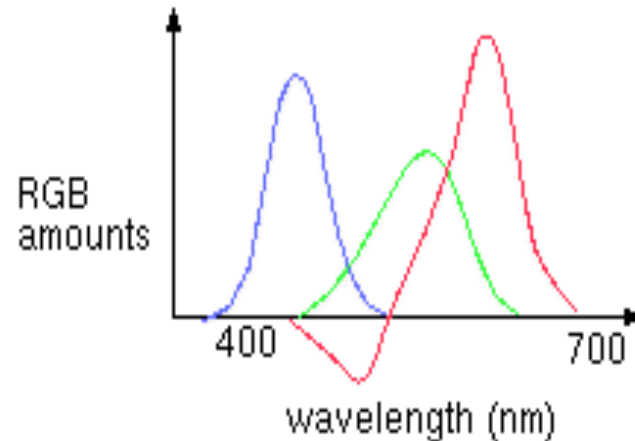
Color Spaces

- three types of cones suggests color is a 3D quantity. how to define 3D color space?



- idea: perceptually based measurement
 - shine given wavelength (λ) on a screen
 - user must control three pure lights producing three other wavelengths
 - used R=700nm, G=546nm, and B=436nm
 - adjust intensity of RGB until colors are identical
 - this works because of metamers!
 - experiments performed in 1930s

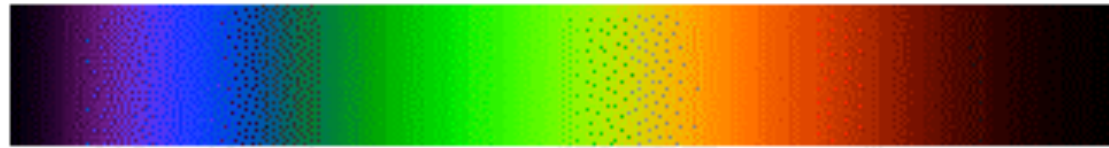
Negative Lobes



- sometimes need to point red light to shine on target in order to match colors
 - equivalent mathematically to "removing red"
 - but physically impossible to remove red from CRT phosphors
- can't generate all other wavelenths with any set of three positive monochromatic lights!
- solution: convert to new synthetic coordinate system to make the job easy

CIE Color Space

- CIE defined 3 “imaginary” lights X, Y, Z
 - any wavelength λ can be matched perceptually by positive combinations

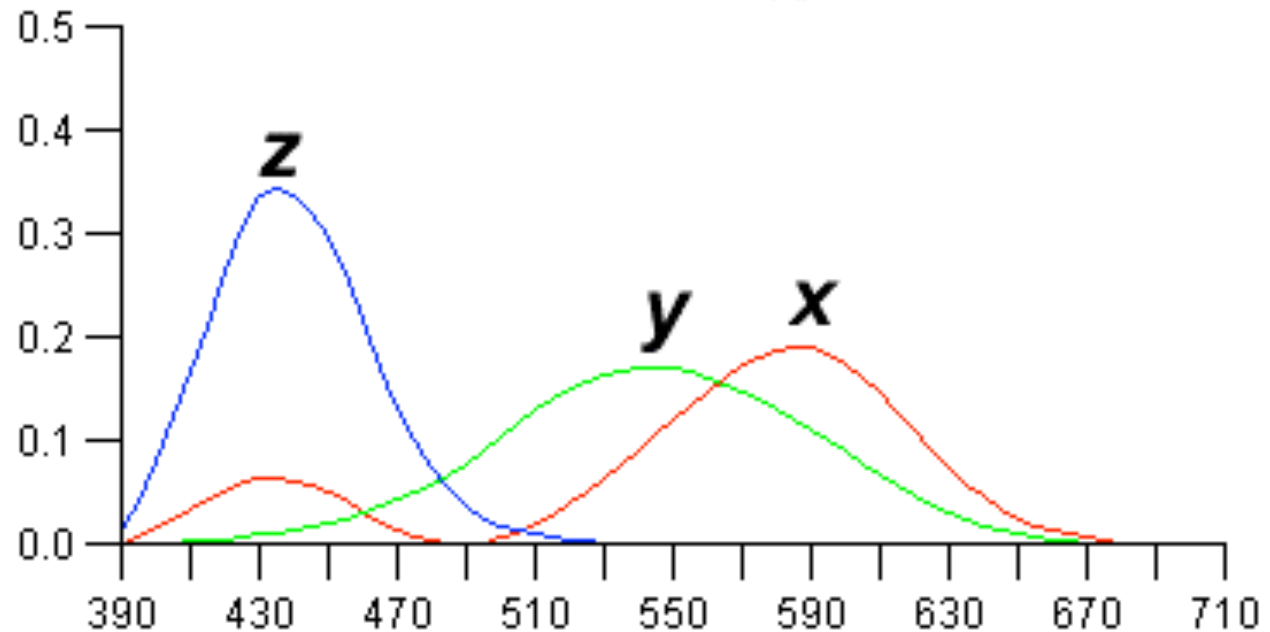


Note that:

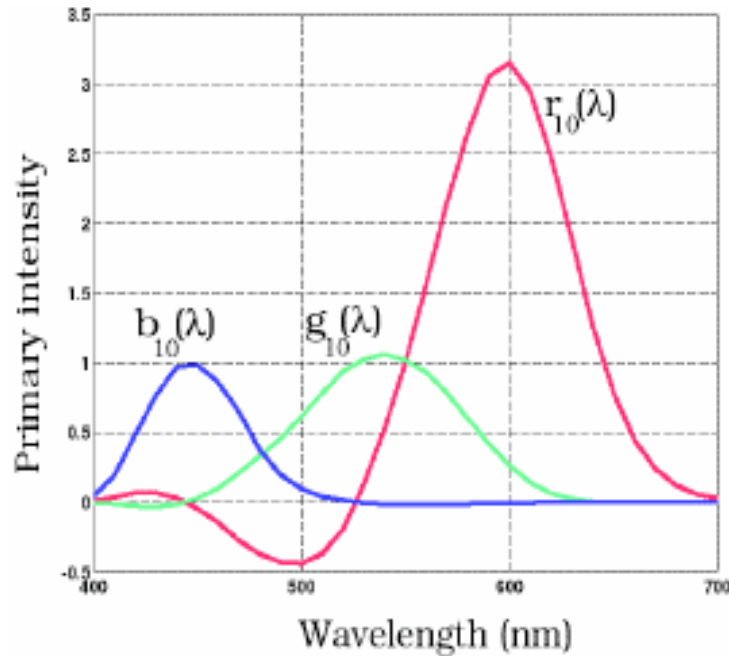
X ~ R

Y ~ G

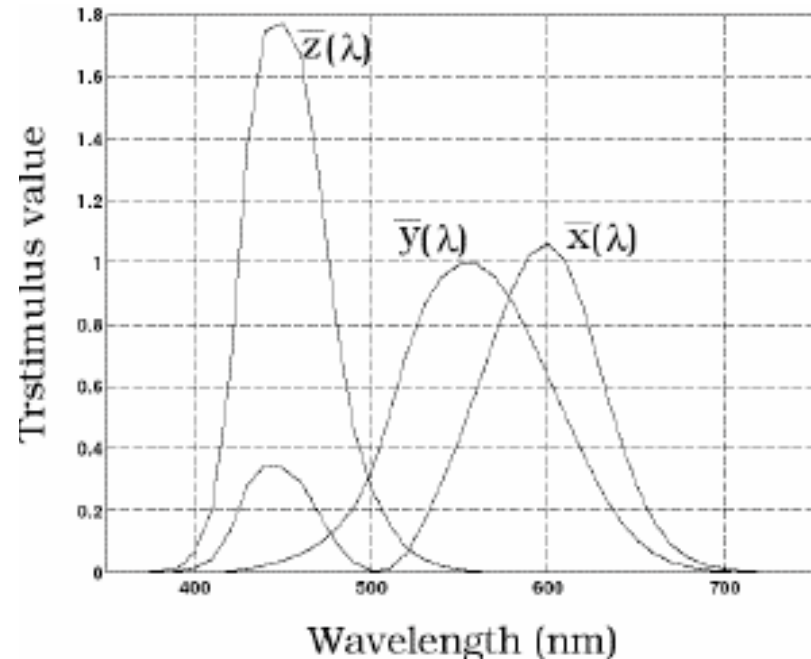
Z ~ B



Measured vs. CIE Color Spaces



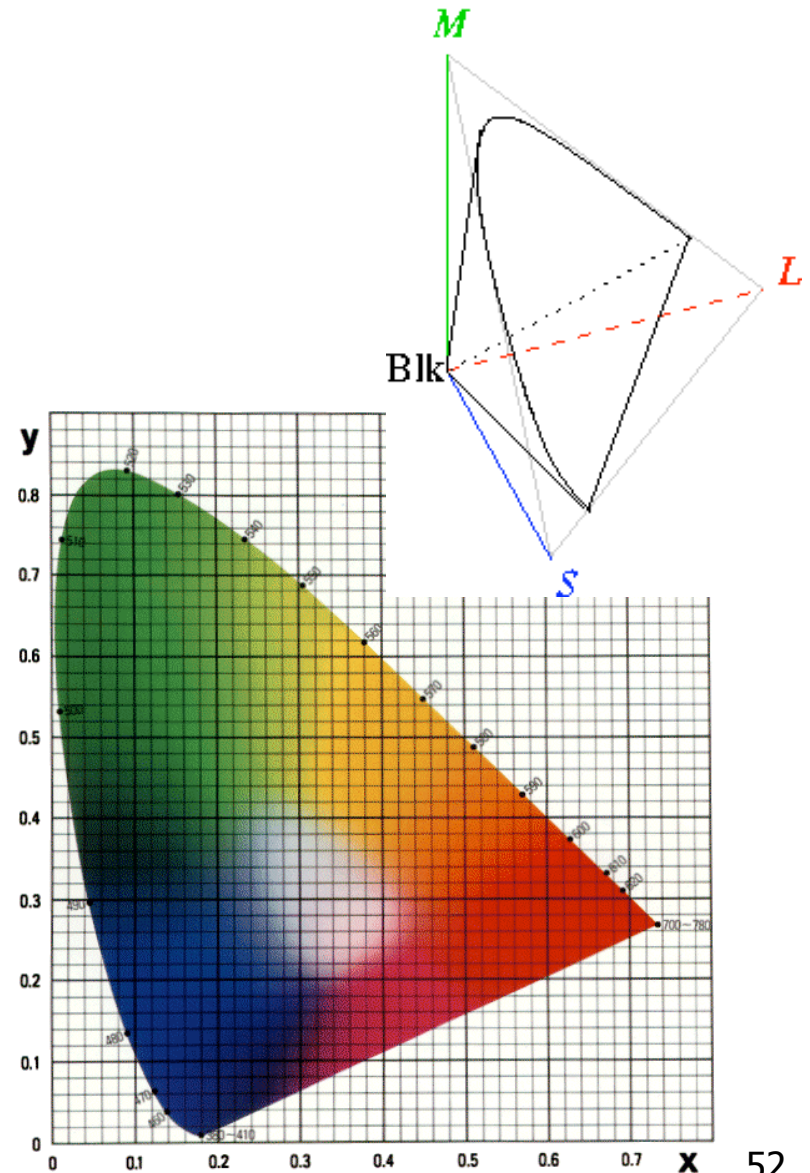
- measured basis
 - monochromatic lights
 - physical observations
 - negative lobes



- transformed basis
 - “imaginary” lights
 - all positive, unit area
 - Y is luminance, no hue
 - X,Z no luminance

CIE and Chromaticity Diagram

- X, Y, Z form 3D shape
- project X, Y, Z on $X+Y+Z=1$ plane for 2D color space
 - chromaticity diagram
 - separate color from brightness
 - $x = X / (X+Y+Z)$
 - $y = Y / (X+Y+Z)$



CIE “Horseshoe” Diagram Facts

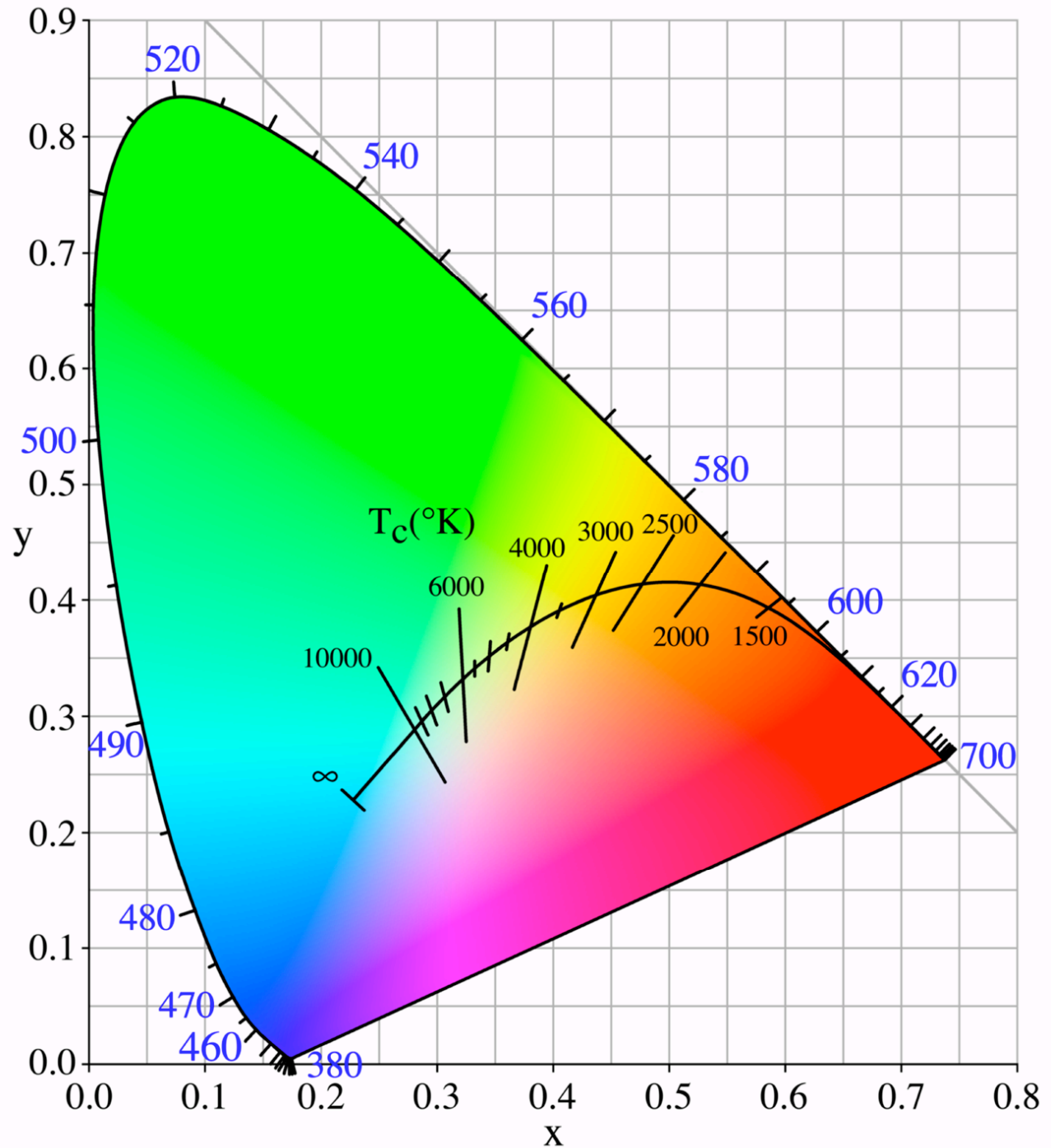
- all visible colors lie inside the horseshoe
 - result from color matching experiments
- spectral (monochromatic) colors lie around the border
 - straight line between blue and red contains purple tones
- colors combine linearly (i.e. along lines), since the xy -plane is a plane from a linear space

CIE “Horseshoe” Diagram Facts

- can choose a point C for a white point
 - corresponds to an illuminant
 - usually on curve swept out by black body radiation spectra for different temperatures

Blackbody Curve

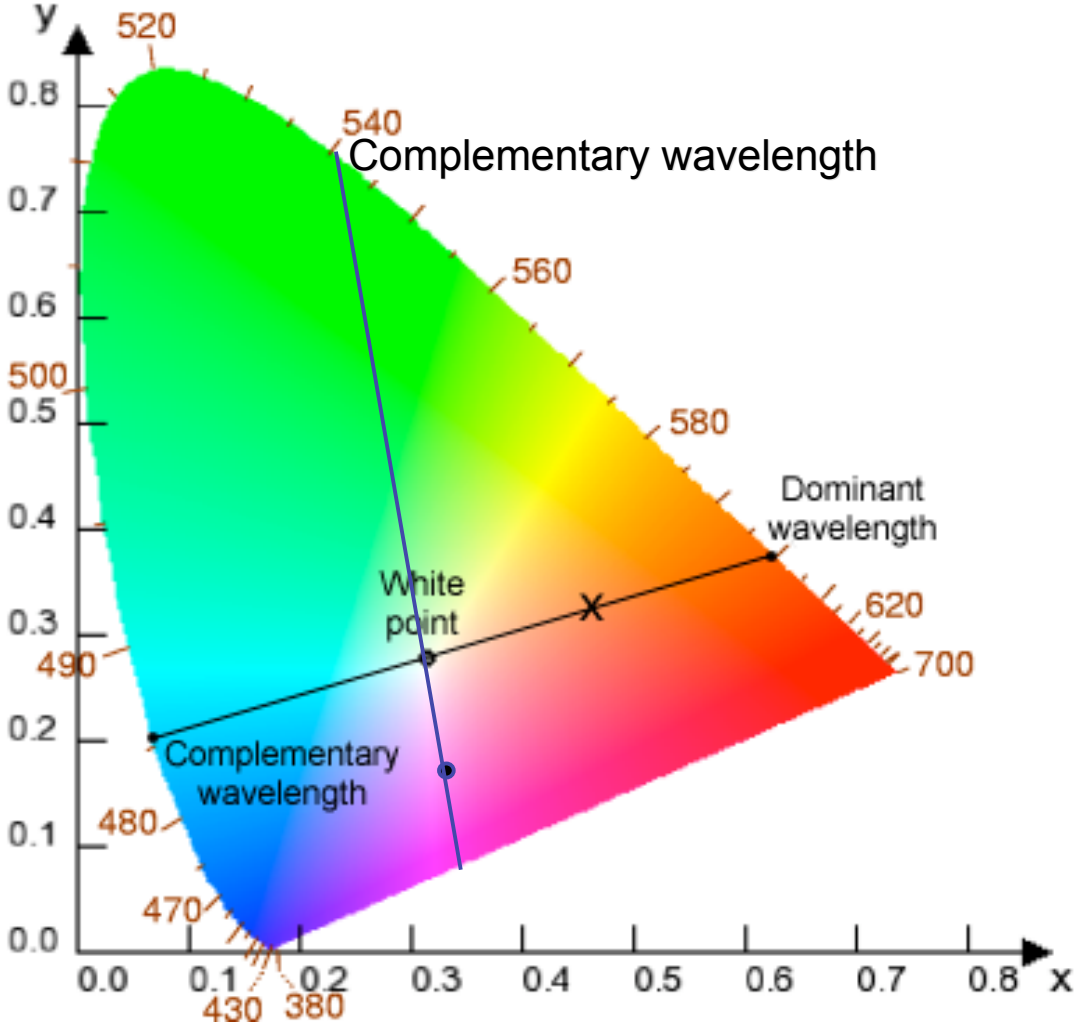
- illumination:
 - candle
2000K
 - A: Light bulb
3000K
 - sunset/
sunrise
3200K
 - D: daylight
6500K
 - overcast
day 7000K
 - lightning
>20,000K



CIE “Horseshoe” Diagram Facts

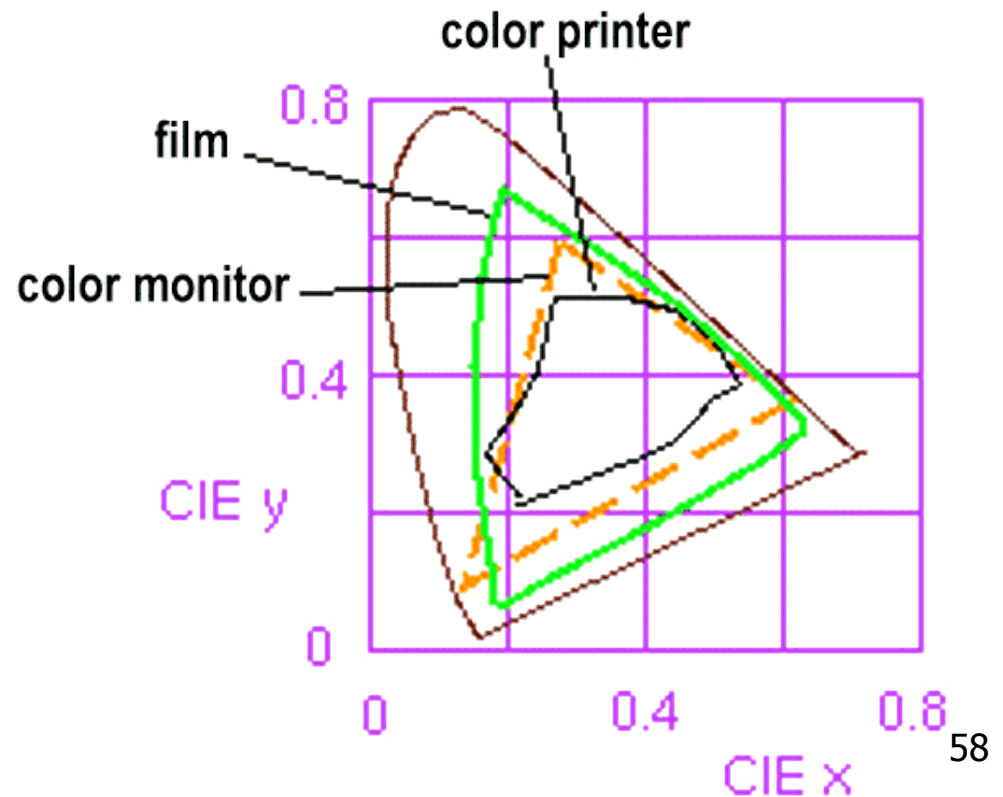
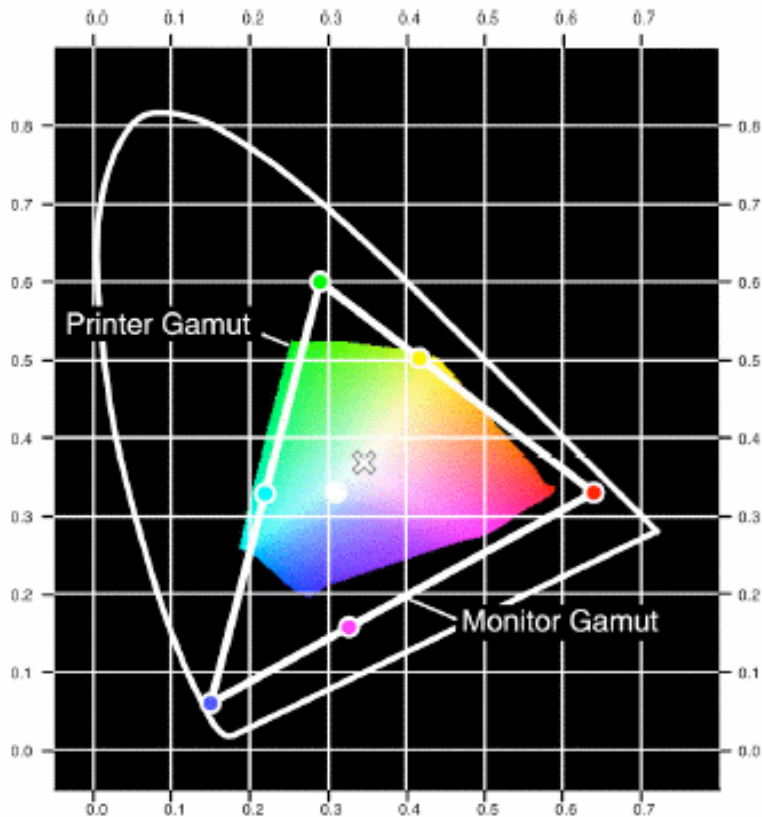
- can choose a point C for a white point
 - corresponds to an illuminant
 - usually on curve swept out by black body radiation spectra for different temperatures
 - two colors are complementary relative to C when are
 - located on opposite sides of line segment through C
 - so C is an affine combination of the two colors
 - find dominant wavelength of a color:
 - extend line from C through color to edge of diagram
 - some colors (i.e. purples) do not have a dominant wavelength, but their complementary color does

Color Interpolation, Dominant & Opponent Wavelength

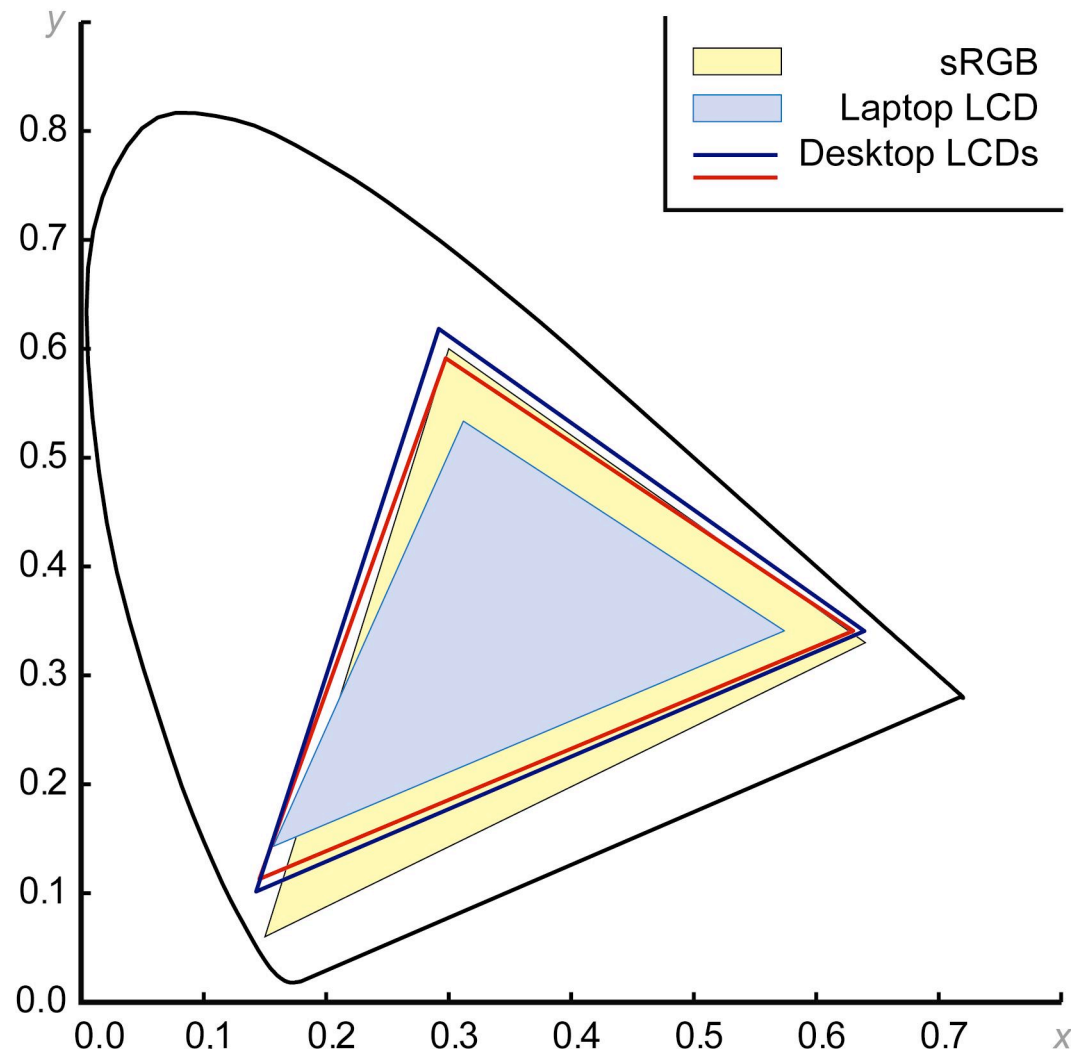


Device Color Gamuts

- gamut is polygon, device primaries at corners
 - defines reproducible color range
 - X, Y, and Z are hypothetical light sources, no device can produce entire gamut

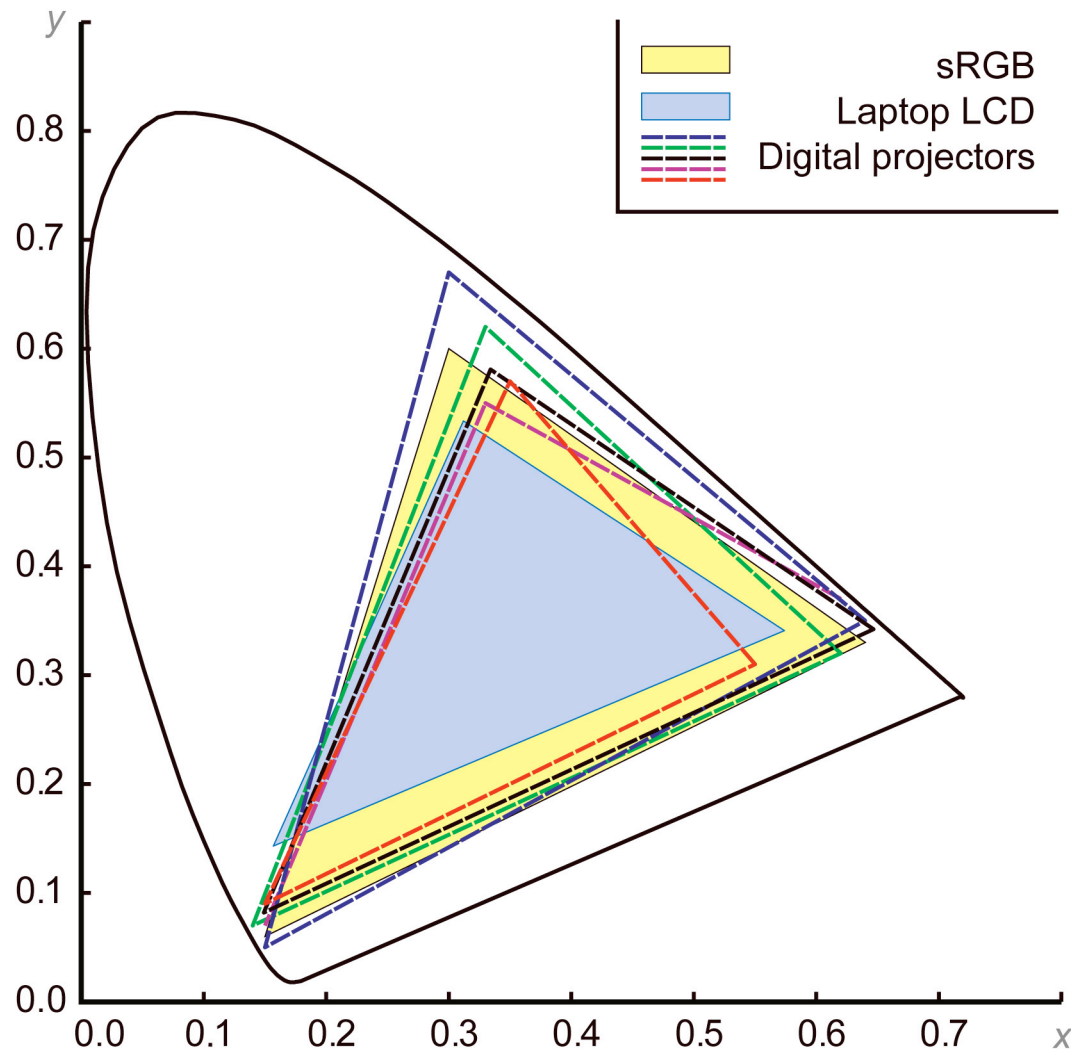


Display Gamuts



From A Field Guide to Digital Color, © A.K. Peters, 2003

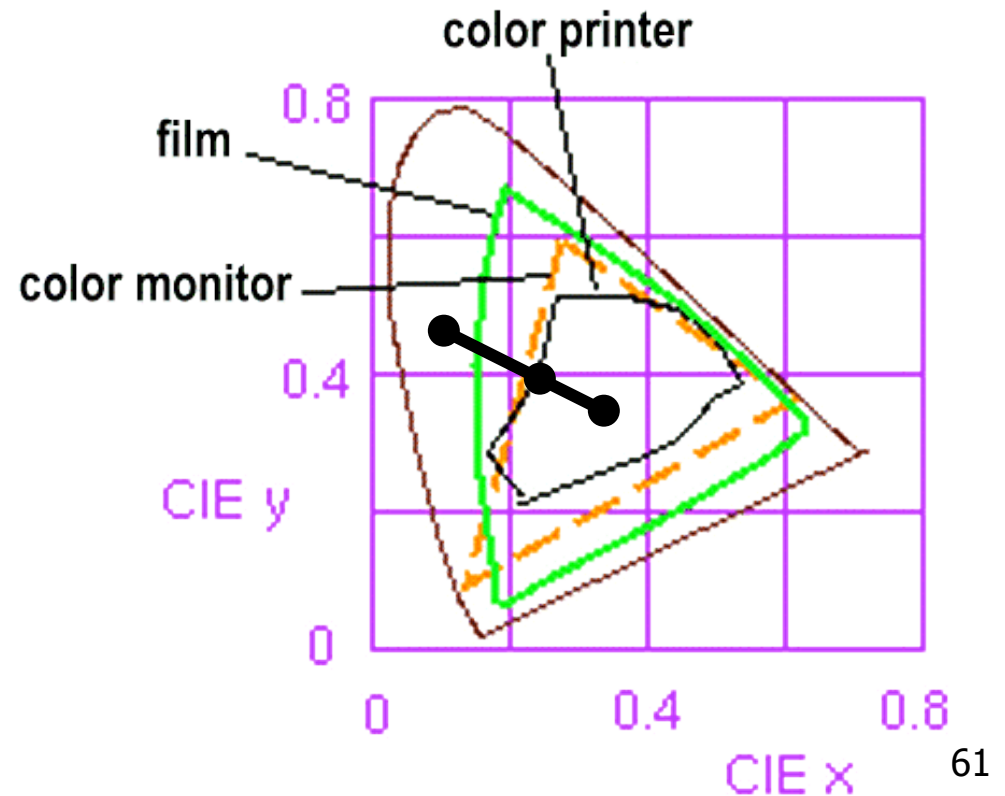
Projector Gamuts



From A Field Guide to Digital Color, © A.K. Peters, 2003

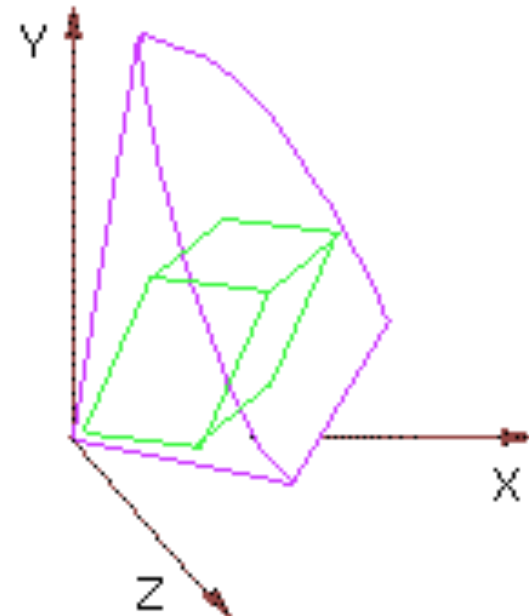
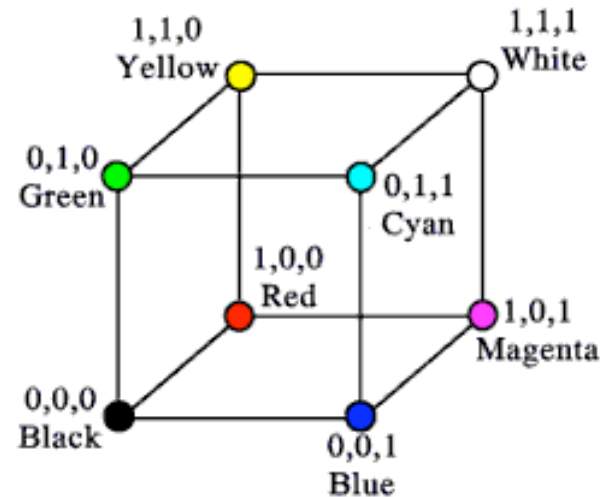
Gamut Mapping

- how to handle colors outside gamut?
 - one way: construct ray to white point, find closest displayable point within gamut



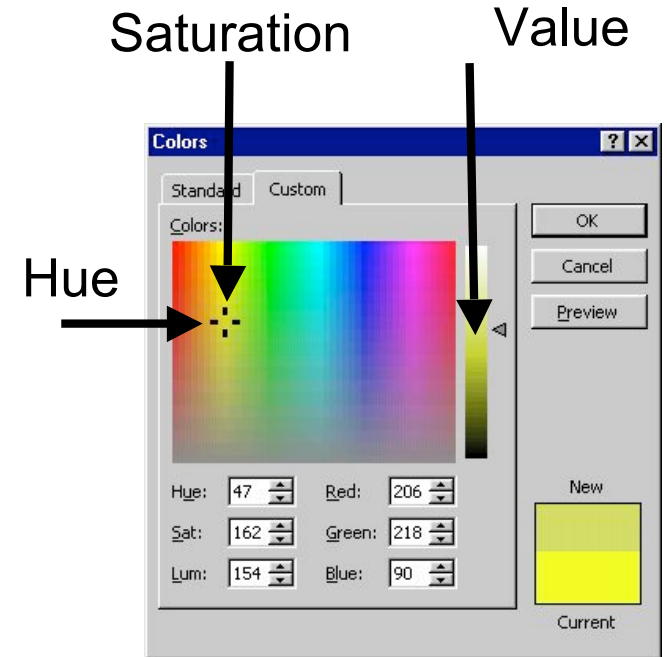
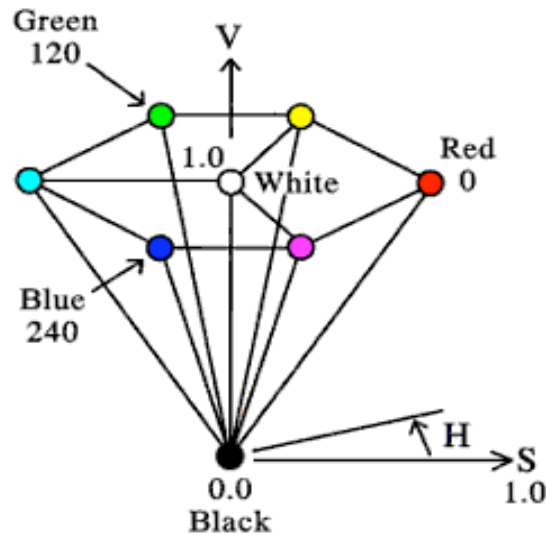
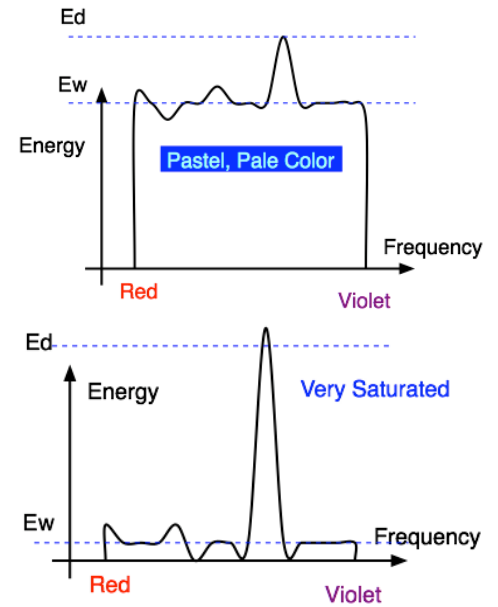
RGB Color Space (Color Cube)

- define colors with (r, g, b) amounts of red, green, and blue
 - used by OpenGL
 - hardware-centric
- RGB color cube sits within CIE color space
 - subset of perceivable colors
 - scale, rotate, shear cube



HSV Color Space

- more intuitive color space for people
 - H = Hue
 - dominant wavelength, “color”
 - S = Saturation
 - how far from grey/white
 - V = Value
 - how far from black/white
 - also: brightness B, intensity I, lightness L



HSI/HSV and RGB

- HSV/HSI conversion from RGB not expressible in matrix
 - H=hue same in both
 - V=value is max, I=intensity is average

$$H = \cos^{-1} \left[\frac{\frac{1}{2} [(R - G) + (R - B)]}{\sqrt{(R - G)^2 + (R - B)(G - B)}} \right] \quad \begin{array}{l} \text{if } (B > G), \\ H = 360 - H \end{array}$$

$$\text{HSI: } S = 1 - \frac{\min(R, G, B)}{I} \quad I = \frac{R + G + B}{3}$$

$$\text{HSV: } S = 1 - \frac{\min(R, G, B)}{V} \quad V = \max(R, G, B)$$