

University of British Columbia **CPSC 314 Computer Graphics** Jan-Apr 2010

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Viewing/Projection VI, Vision/Color

Week 5, Wed Feb 2

http://www.ugrad.cs.ubc.ca/~cs314/Vjan2010

News

- · showing up for your project grading slot is not optional
- · 2% penalty for noshows signing up for your project grading slot is not optional
- 2% penalty for nosignups within two days of due date
- · your responsibility to sign up for slot
 - not ours to hunt you down if you chose to skip class on signup
- we do make best effort to accomodate change requests via email to grader for that project
- take a few minutes to review your code/README to reload vour mental buffers
 - · TA will ask you questions about how you did things

News

- · Homework 2 out
- · due Fri Feb 12 5pm
- Proiect 2 out
- · due Tue Mar 2 5pm
- · moved due date to after break after pleas of prebreak overload with too many assignments due

Review/Clarify: Trackball Rotation

axis of rotation is plane normal: cross product p₁ x p₂

screen plane

· user drags between two points on image plane

find corresponding points on virtual ball

compute rotation angle and axis for ball

p₁ = (x, y, z), p₂ = (a, b, c)

 $\mathbf{p_1} \cdot \mathbf{p_2} = |\mathbf{p_1}| |\mathbf{p_2}| \cos \theta$

• i₁ = (x, y)

 $i_2 = (a, b)$

screen nlane

mouse down at (x, y), mouse up at (a, b)

• amount of rotation θ from angle between lines

- start early, do *not* leave until late in break!!
- · reminder
- extra handouts in lab

Project 2: RCSS

- · solar system
 - planets spin around own axis and sun
 - · moon spins around earth
- two spaceships: mothership and scoutship
 - · one window for each
 - · may see geometry of one spaceship through window of other
- navigation modes
 - · solar system coord (absolute) rotate/translate
 - through the lens flying (relative to camera)
 - · geosynchronous orbit around planet
 - · zoom in/out towards center of planet

Clarify: Trackball Rotation

- · finding location on ball corresponding to click on image
 - ball radius r is 1





Project 2 Hints

- · don't forget to keep viewing and projections in their respective stacks
- try drawing scene graphs to help you figure out how to place multiple cameras
- · especially geosynchronous: camera as child of object in world in the scene graph
- geometric representation of camera vs. what is shown through its window
- · disk for Saturn rings: try scaling sphere by 0
- · OK to reset camera position between absolute/relative navigation modes

· manual ray intersection

· bounding extents

backbuffer coding

 OK to have camera jumpout to different orientation. when new planet picked in geosync mode

Review: Picking Methods

Review/More: Relative Motion

- how to move relative to current camera? what you see in the window
- computation in coordinate system used to draw previous frame is simple:
- · incremental change I to current C
- · each time we just want to premultiply by new matrix
- · but we know that OpenGL only supports postmultiply by new
- p'=Clp
- use OpenGL matrix stack as calculator/storage!
- · dump out modelview matrix from previous frame with glGetDoublev() C = current camera coordinate matrix
- wipe the matrix stack with glldentity()
- · apply incremental update matrix I
- · apply current camera coord matrix C

Review: Select/Hit Picking

- · use small region around cursor for viewport
- · assign per-object integer keys (names)
- · redraw in special mode
- · store hit list of objects in region
- examine hit list
- OpenGL support

Viewport

- small rectangle around cursor
 - · change coord sys so fills viewport





- why rectangle instead of point?
- · people aren't great at positioning mouse
- · Fitts' Law: time to acquire a target is function of the distance to and size of the target
- allow several pixels of slop

Viewport

- · nontrivial to compute
 - · invert viewport matrix, set up new orthogonal projection
- simple utility command
- gluPickMatrix(x,y,w,h,viewport)
 - · x,y: cursor point
 - w,h: sensitivity/slop (in pixels)
- · push old setup first, so can pop it later

Render Modes

- glRenderMode(mode)
- · GL RENDER: normal color buffer default
- · GL_SELECT: selection mode for picking
- (GL FEEDBACK: report objects drawn)

Name Stack

- · again, "names" are just integers glInitNames()
- flat list glLoadName(name)

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- · or hierarchy supported by stack glPushName(name), glPopName
 - · can have multiple names per object

Hierarchical Names Example

for(int i = 0; i < 2; i++) { glPushName(i) for(int j = 0; j < 2; j++) { glPushMatrix(); alPushName(i) glTranslatef(i*10.0,0,j * 10.0); qlPushName(HEAD) glCallList(snowManHeadDL): all padName(BODY) glCallList(snowManBodvDL): glPonName(): glPopName(): glPopMatrix(): glPopName(); http://www.lighthouse3d.com/opengl/picking/

Hit List

- · glSelectBuffer(buffersize, *buffer)
- · where to store hit list data
- · on hit, copy entire contents of name stack to output buffer.
- - · number of names on stack
 - · minimum and minimum depth of object vertices
 - · depth lies in the NDC z range [0.1]
 - · format: multiplied by 2^32 -1 then rounded to nearest int

Integrated vs. Separate Pick Function

- · integrate: use same function to draw and pick
- · simpler to code
- · name stack commands ignored in render mode
- · separate: customize functions for each
 - · potentially more efficient
 - · can avoid drawing unpickable objects

Select/Hit

- advantages
- faster
 - OpenGL support means hardware acceleration
 - · avoid shading overhead
- · flexible precision
- · size of region controllable
- · flexible architecture
 - · custom code possible, e.g. guaranteed frame rate
- disadvantages
- · more complex

Hybrid Picking

- · select/hit approach: fast, coarse
 - · object-level granularity
- · manual ray intersection: slow, precise
 - · exact intersection point
- · hybrid: both speed and precision
- · use select/hit to find object
- · then intersect ray with that object

High-Precision Picking with OpenGL

- qluUnproject
 - transform window coordinates to object coordinates given current projection and modelview matrices
 - · use to create ray into scene from cursor location
 - call gluUnProject twice with same (x,y) mouse location
 - z = near: (x,y,0)
 - z = far: (x,y,1)
 - · subtract near result from far result to get direction vector for ray

Alpha

· use this ray for line/polygon intersection

· fourth component for transparency

Vision/Color

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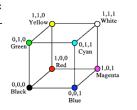
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Reading for Color

- · RB Chap Color
- FCG Sections 3.2-3.3
- · FCG Chap 20 Color
- FCG Chap 21.2.2 Visual Perception (Color)

RGB Color

- · triple (r, g, b) represents colors with amount of red, green, and blue
 - · hardware-centric
- · used by OpenGL



(r,g,b,α)

· more on compositing later

· fraction we can see through

• $c = \alpha c_f + (1-\alpha)c_h$

Additive vs. Subtractive Colors

- · additive: light
- · monitors. LCDs
- RGB model
- · subtractive: pigment
- - printers
 - · CMY model
 - dyes absorb light













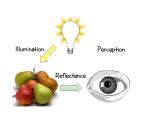
Component Color

· component-wise multiplication of colors • (a0,a1,a2) * (b0,b1,b2) = (a0*b0, a1*b1, a2*b2)



- · why does this work?
- · must dive into light, human vision, color spaces

· elements of color:



Basics Of Color

- physics illumination
 - · electromagnetic spectra
- reflection
 - · material properties
 - · surface geometry and microgeometry

Basics of Color

- polished versus matte versus brushed
- perception
 - · physiology and neurophysiology
 - · perceptual psychology

Light Sources

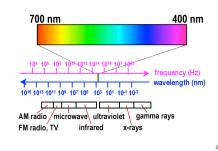
- · common light sources differ in kind of spectrum they emit:
 - · continuous spectrum
 - · energy is emitted at all wavelengths blackbody radiation
 - · tungsten light bulbs certain fluorescent lights
 - sunlight electrical arcs
 - · line spectrum
 - · energy is emitted at certain discrete frequencies

Blackbody Radiation

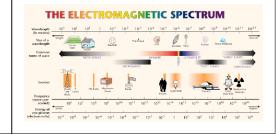
- black body
 - · dark material, so that reflection can be neglected
- spectrum of emitted light changes with temperature
 - · this is the origin of the term "color temperature" e.g. when setting a white point for your monitor
 - · cold: mostly infrared
 - · hot: reddish · very hot: bluish
- demo:

http://www.mhhe.com/physsci/astronomy/applets/Blackbody/frame.html

Electromagnetic Spectrum

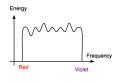


Electromagnetic Spectrum



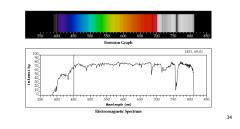
White Light

· sun or light bulbs emit all frequencies within visible range to produce what we perceive as "white light"



Sunlight Spectrum

· spectral distribution: power vs. wavelength



Continuous Spectrum

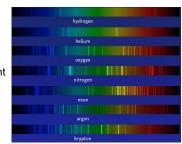
 sunlight various "daylight" lamps

Line Spectrum

· ionized gases

lasers

some fluorescent lamps



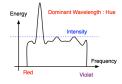
White Light and Color

- · when white light is incident upon an object, some frequencies are reflected and some are absorbed by the object
- · combination of frequencies present in the reflected light that determines what we perceive as the color of the object

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Hue

hue (or simply, "color") is dominant wavelength/frequency



· integration of energy for all visible wavelengths is proportional to intensity of color

Physiology of Vision

Saturation or Purity of Light

- · how washed out or how pure the color of the light
 - contribution of dominant light vs. other frequencies producing white light saturation: how far is color from grey
 - · pink is less saturated than red · sky blue is less saturated than royal blue



Energy

Intensity vs. Brightness

- · intensity : physical term
 - · measured radiant energy emitted per unit of time, per unit solid angle, and per unit projected area of the source (related to the luminance of the source)
- lightness/brightness: perceived intensity of light
 - nonlinear

Perceptual vs. Colorimetric Terms

- Perceptual
 - Hue

 - Saturation
 - · Lightness
 - · reflecting objects
 - Brightness
 - · light sources

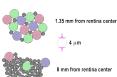
- Colorimetric
 - · Dominant wavelength

 - · Excitation purity
 - Luminance

 - Luminance

Physiology of Vision

- · Center of retina is densely packed region called the fovea.
- · Cones much denser here than the periphery



Foveal Vision

· hold out your thumb at arm's length



Tristimulus Theory of Color Vision

- · Although light sources can have extremely complex spectra, it was empirically determined that colors could be described by only 3 primaries
- · Colors that look the same but have different spectra are called metamers

Trichromacy

three types of cones

· the retina

rods

cones

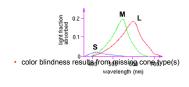
uneven

b/w, edges

 3 types color sensors

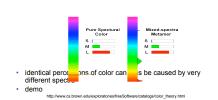
distribution · dense fovea

- · L or R, most sensitive to red light (610 nm)
- M or G, most sensitive to green light (560 nm)
- S or B, most sensitive to blue light (430 nm)



Metamers

· a given perceptual sensation of color derives from the stimulus of all three cone types



Color Spaces

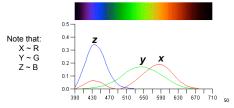
three types of cones suggests color is a 3D quantity. how to define 3D color space?



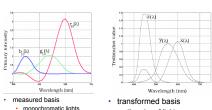
- · idea: perceptually based measurement
- shine given wavelength (λ) on a screen
- · user must control three pure lights producing three other wavelengths
- · used R=700nm, G=546nm, and B=436nm
- adjust intensity of RGB until colors are identical
- · this works because of metamers!
- · experiments performed in 1930s

CIE Color Space

- CIE defined 3 "imaginary" lights X, Y, Z
 - any wavelength λ can be matched perceptually by positive combinations



Measured vs. CIE Color Spaces



physical observations

negative lobes

Blackbody

lightning >20.000K · "imaginary" lights

X.Z no luminance

all positive, unit area

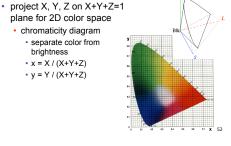
· Y is luminance, no hue

0.2 0.3 0.4 0.5 0.6 0.7 0.8

chromaticity diagram

· X, Y, Z form 3D shape

- plane for 2D color space
- · separate color from
- brightness • x = X / (X+Y+Z)
- y = Y / (X+Y+Z)



CIE "Horseshoe" Diagram Facts

Negative Lobes

· sometimes need to point red light to shine on target

but physically impossible to remove red from CRT phosphors

· equivalent mathematically to "removing red"

· can't generate all other wavelenths with any set of

three positive monochromatic lights!

system to make the job easy

· solution: convert to new synthetic coordinate

in order to match colors

- all visible colors lie inside the horseshoe
- · result from color matching experiments
- · spectral (monochromatic) colors lie around the border
- · straight line between blue and red contains purple tones
- colors combine linearly (i.e. along lines), since the xy-plane is a plane from a linear space

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CIE "Horseshoe" Diagram Facts

- · can choose a point C for a white point
 - · corresponds to an illuminant
 - · usually on curve swept out by black body radiation spectra for different temperatures

Curve illumination: candle A: Light bulb 3000K 0.5 sunset/ sunrise 3200K D: daylight 6500K overcast day 7000K

CIE "Horseshoe" Diagram Facts

CIE and Chromaticity Diagram

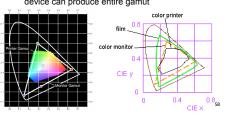
- · can choose a point C for a white point
- · corresponds to an illuminant
- · usually on curve swept out by black body radiation spectra for different temperatures
- · two colors are complementary relative to C when are
 - located on opposite sides of line segment through C
 - so C is an affine combination of the two colors
- · find dominant wavelength of a color:
- · extend line from C through color to edge of diagram
- some colors (i.e. purples) do not have a dominant wavelength, but their complementary color does

Color Interpolation, **Dominant & Opponent Wavelength**

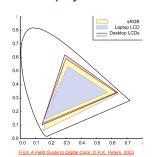


Device Color Gamuts

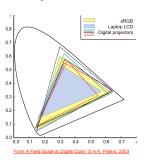
- · gamut is polygon, device primaries at corners
 - · defines reproducible color range
 - · X, Y, and Z are hypothetical light sources, no device can produce entire gamut



Display Gamuts

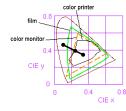


Projector Gamuts



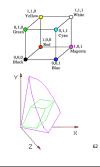
Gamut Mapping

- · how to handle colors outside gamut?
- one way: construct ray to white point, find closest displayable point within gamut



RGB Color Space (Color Cube)

- define colors with (r, g, b) amounts of red, green, and blue · used by OpenGL
- · hardware-centric
- RGB color cube sits within CIE color space
- · subset of perceivable colors
- · scale, rotate, shear cube

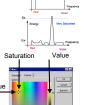


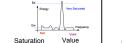
HSV Color Space

- H = Hue dominant wavelength, "color"
- S = Saturation
- · how far from grey/white V = Value
- · how far from black/white · also: brightness B, intensity I, lightness L



more intuitive color space for people





· H=hue same in both · V=value is max, I=intensity is average

$$H = \cos^{-1} \left[\frac{\frac{1}{2} [(R-G) + (R-B)]}{\sqrt{(R-G)^2 + (R-B)(G-B)}} \right] \text{ if } (B > G),$$

$$H = 360 - H$$

HSI/HSV and RGB

HSV/HSI conversion from RGB not expressible in matrix

HSI:
$$S = 1 - \frac{\min(R, G, B)}{I}$$
 $I = \frac{R + G + B}{3}$
 $\min(R, G, B)$ $V = \max(R, G, B)$

HSI:
$$S=1-\frac{\min(R,G,B)}{I}$$
 $I=\frac{R+G+B}{3}$
HSV: $S=1-\frac{\min(R,G,B)}{V}$ $V=\max(R,G,B)$