



# Shadows

**Wolfgang Heidrich**

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## Course News

### **Assignment 3 (project)**

- Due April 1

### **Reading**

- Chapter 11.8

### **Quiz 2**

- Friday
- Topics:
  - *Everything after transformations up to and including this lecture*
  - *Questions on rendering pipeline as a whole*

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## Shadows

### **What are shadows?**

- What distinguishes a point in shadow from a lit point?

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## Shadows

### **Types of light sources**

- Point, directional
- Area lights and generally shaped lights
  - *Not considered here*
  - *Later: ray-tracing for such light sources*

### **Problem statement**

- A shadow algorithm for point and directional lights determines which scene points are
  - *Visible from the light source (i.e. illuminated)*
  - *Invisible from the light source (i.e. in shadow)*
- Thus: shadow casting is a visibility problem!

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## Types of Shadow Algorithms

### Object Space

- Like object space visibility algorithms, the method computes in object space which polygon parts that are illuminated and which are in shadow
  - *Individual parts are then drawn with different intensity*
- Typically slow,  $O(n^2)$ , not for dynamic scenes

### Image Space

- Determine visibility per pixel in the final image
  - *Sort of like depth buffer*
  - *Shadow maps*
  - *Shadow volumes*

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## Credits

- The following shadow mapping slides are taken from Mark Kilgard's OpenGL course at Siggraph 2002.

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# Shadow Mapping Concept (1)



## ***Depth testing from the light's point-of-view***

- Two pass algorithm
- First, render depth buffer from the light's point-of-view
  - The result is a "depth map" or "shadow map"
  - Essentially a 2D function indicating the depth of the closest pixels to the light
- This depth map is used in the second pass

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# Shadow Mapping Concept (2)



## ***Shadow determination with the depth map***

- Second, render scene from the eye's point-of-view
- For each rasterized fragment
  - Determine fragment's XYZ position relative to the light
  - This light position should be setup to match the frustum used to create the depth map
  - Compare the depth value at light position XY in the depth map to fragment's light position Z

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# The Shadow Mapping Concept (3)



## The Shadow Map Comparison

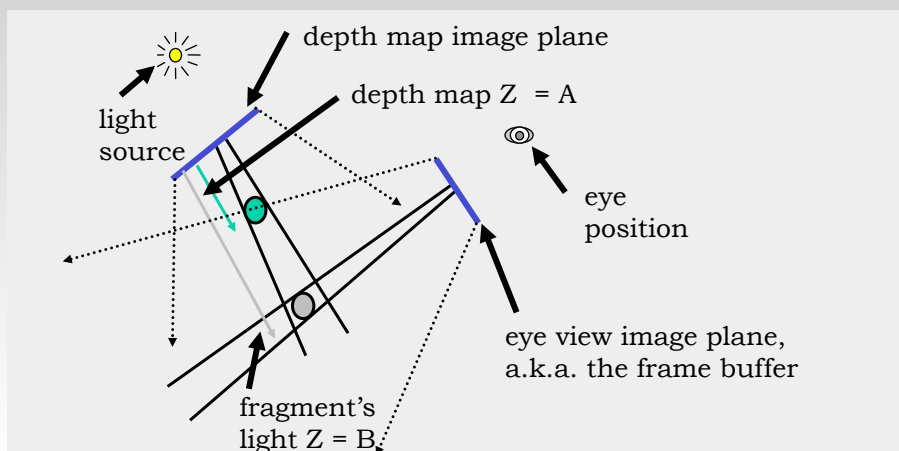
- Two values
  - $A = Z$  value from depth map at fragment's light XY position
  - $B = Z$  value of fragment's XYZ light position
- If  $B$  is greater than  $A$ , then there must be something closer to the light than the fragment
  - Then the fragment is shadowed
- If  $A$  and  $B$  are approximately equal, the fragment is lit

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# Shadow Mapping with a Picture in 2D (1)



## The $A < B$ shadowed fragment case

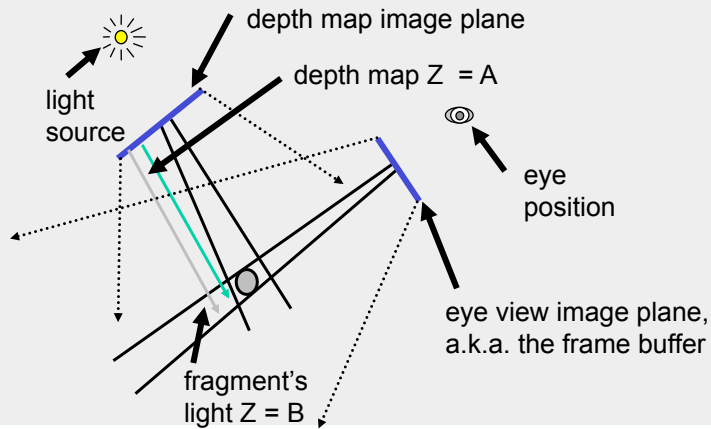


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# Shadow Mapping with a Picture in 2D (2)



The  $A \approx B$  unshadowed fragment case



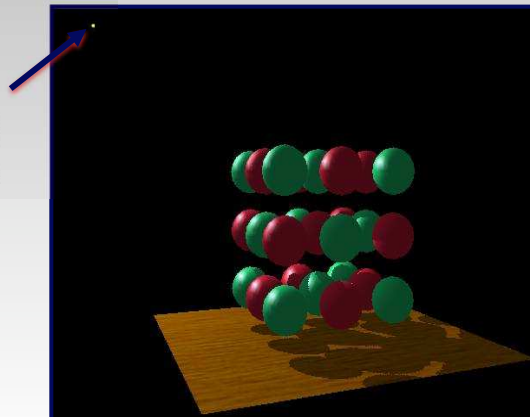
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# Visualizing the Shadow Mapping Technique (1)



*A scene with fairly complex shadows*

*the point light source*

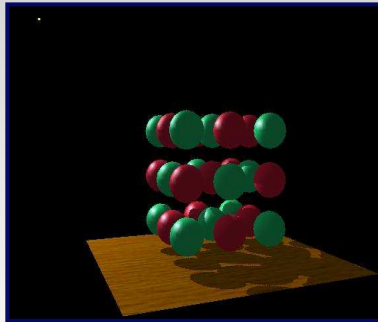


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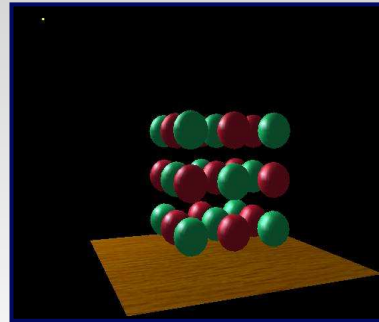
## Visualizing the Shadow Mapping Technique (2)



*Compare with and without shadows*



**with shadows**



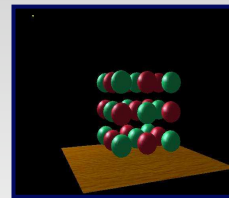
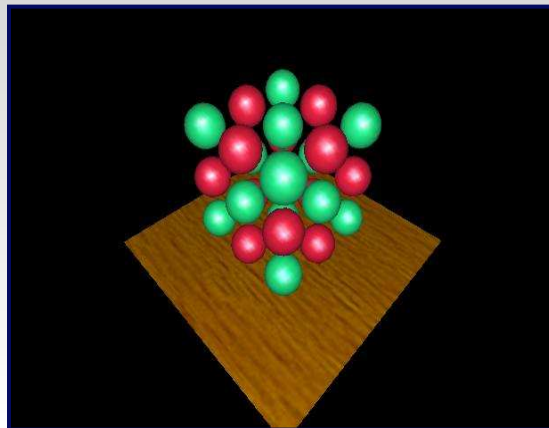
**without shadows**

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## Visualizing the Shadow Mapping Technique (3)



*The scene from the light's point-of-view*



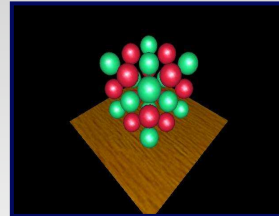
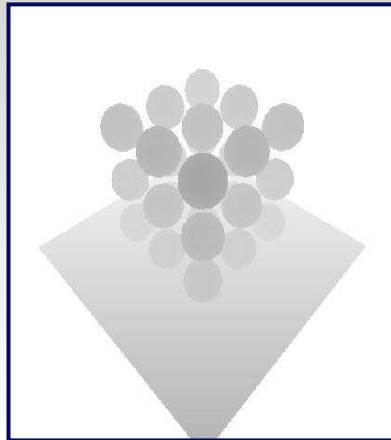
**FYI: from the eye's point-of-view again**

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## Visualizing the Shadow Mapping Technique (4)



**The depth buffer from the light's point-of-view**



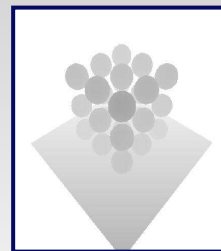
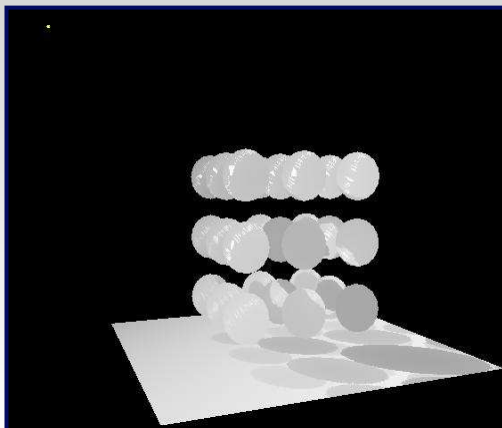
**FYI: from the light's point-of-view again**

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## Visualizing the Shadow Mapping Technique (5)



**Projecting the depth map onto the eye's view**



**FYI: depth map for light's point-of-view again**

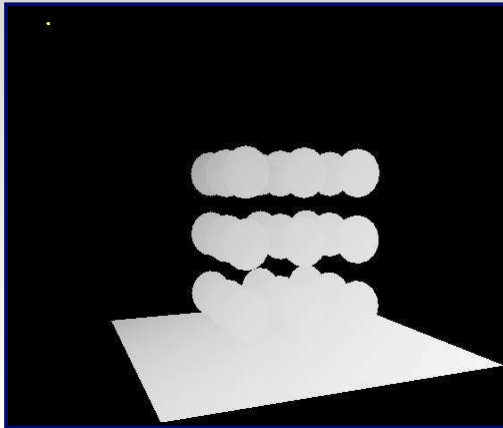
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## Visualizing the Shadow Mapping Technique (6)



*Projecting light's planar distance onto eye's view*



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## Visualizing the Shadow Mapping Technique (6)



*Comparing light distance to light depth map*

*Green is where the light planar distance and the light depth map are approximately equal*



*Non-green is where shadows should be*

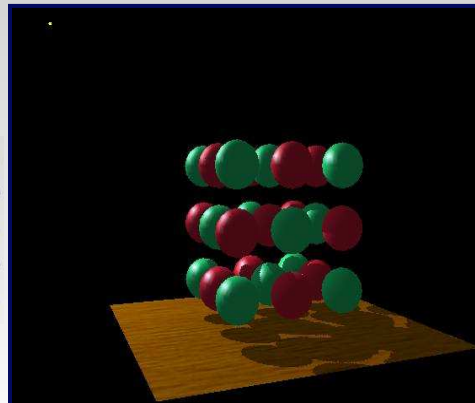
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# Visualizing the Shadow Mapping Technique (7)



## Complete scene with shadows

*Notice how specular highlights never appear in shadows*



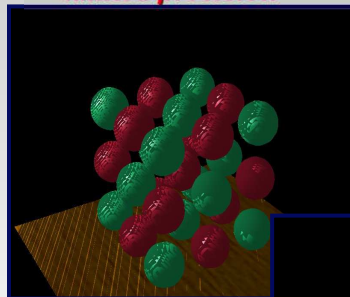
*Notice how curved surfaces cast shadows on each other*

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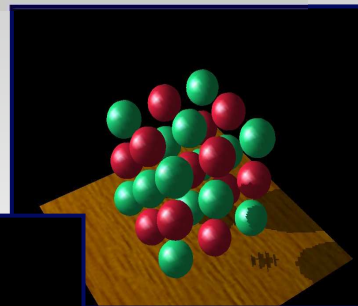
# In Practice: Depth Map Precision Issues



## Have to add a little offset to depth map values to account for limited precision

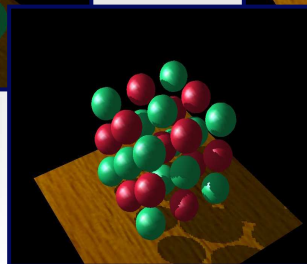


*Too little bias, everything begins to shadow*



*Too much bias, shadow starts too far back*

*Just right*



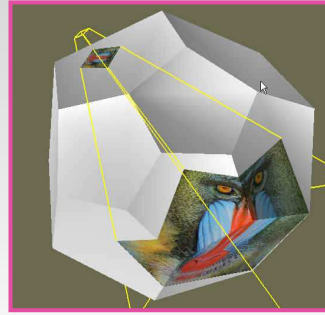
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# What is Projective Texturing?



## *An intuition for projective texturing*

- The slide projector analogy



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# About Projective Texturing (1)



## *First, what is perspective-correct texturing?*

- Normal 2D texture mapping uses  $(s, t)$  coordinates
- 2D perspective-correct texture mapping
  - Means  $(s, t)$  should be interpolated linearly in eye-space
  - So compute per-vertex  $s/w$ ,  $t/w$ , and  $1/w$
  - Linearly interpolated these three parameters over polygon
  - Per-fragment compute  $s' = (s/w) / (1/w)$  and  $t' = (t/w) / (1/w)$
  - Results in per-fragment perspective correct  $(s', t')$

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## About Projective Texturing (2)



### So what is projective texturing?

- Now consider homogeneous texture coordinates
  - $(s, t, r, q) \rightarrow (s/q, t/q, r/q)$
  - Similar to homogeneous clip coordinates where  $(x, y, z, w) = (x/w, y/w, z/w)$
- Idea is to have  $(s/q, t/q, r/q)$  be projected per-fragment

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## Back to the Shadow Mapping Discussion . . .



### Assign light-space texture coordinates to polygon vertices

- Transform eye-space  $(x, y, z, w)$  coordinates to the light's view frustum (match how the light's depth map is generated)
- Further transform these coordinates to map directly into the light view's depth map
  - Expressible as a projective transform
- $(s/q, t/q)$  will map to light's depth map texture

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## Shadow Map Operation

### **Next Step:**

- Compare depth map value to distance of fragment from light source
- Different GPU generations support different means of implementing this
  - *Today's GPUs: pixel shader!*
  - *Earlier: special hardware for implementing this feature (e.g. SGI), or just using alpha blending [Heidrich'99]*

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## Issues with Shadow Mapping (1)

### **Not without its problems**

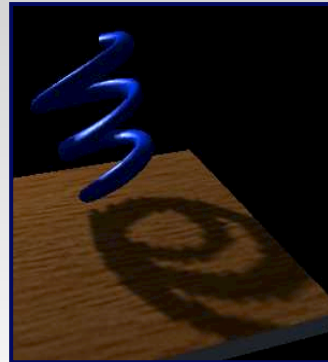
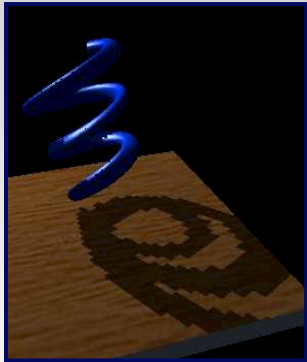
- Prone to aliasing artifacts
  - "percentage closer" filtering helps this
  - normal color filtering does **not** work well
- Depth bias is not completely foolproof
- Requires extra shadow map rendering pass and texture loading
- Higher resolution shadow map reduces blockiness
  - but also increase texture copying expense

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## Hardware Shadow Map Filtering Example



***GL\_NEAREST: blocky***   ***GL\_LINEAR: antialiased edges***



***Low shadow map resolution  
used to heightens filtering artifacts***

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## Issues with Shadow Mapping (2)



### ***Not without its problems***

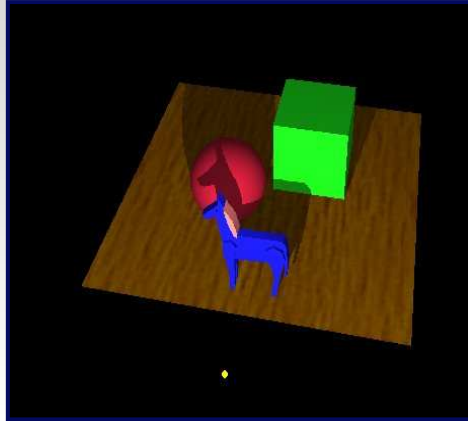
- Shadows are limited to view frustums
  - could use six view frustums for omni-directional light
- Objects outside or crossing the near and far clip planes are not properly accounted for by shadowing
  - move near plane in as close as possible
  - but too close throws away valuable depth map precision when using a projective frustum

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## More Examples

***Complex objects all shadow***

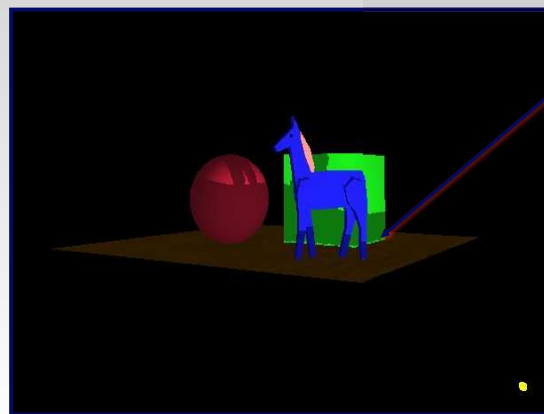


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## More Examples

***Even the floor casts shadow***



***Note shadow leakage due to infinitely thin floor***

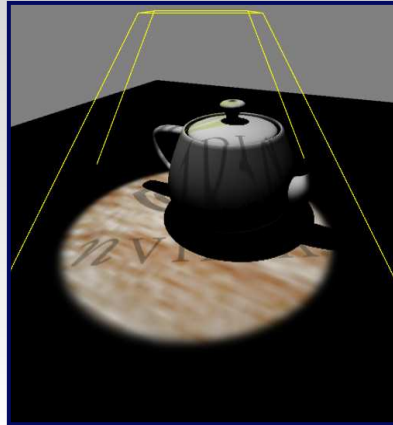
***Could be fixed by giving floor thickness***

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## Combining Projective Texturing for Spotlights



*Use a spotlight-style projected texture to give shadow maps a spotlight falloff*

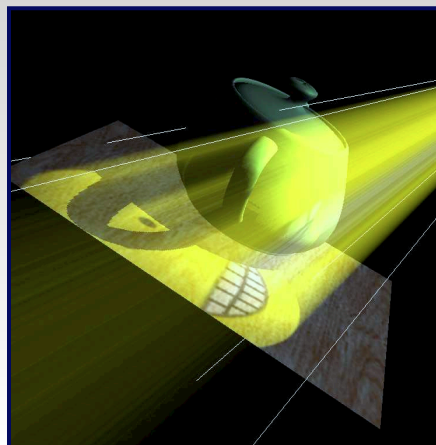


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## Combining Shadows with Atmospherics



*Shadows in a dusty room*



*Simulate atmospheric effects such as suspended dust*

- 1) *Construct shadow map*
- 2) *Draw scene with shadow map*
- 3) *Modulate projected texture image with projected shadow map*
- 4) *Blend back-to-front shadowed slicing planes also modulated by projected texture image*

**Credit: Cass Everitt**

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## Shadow Maps

### **Approach for shadows from point light sources**

- Surface point is in shadow if it is not visible from the light source
- Use depth buffer to test visibility:
  - *Render scene from the point light source*
  - *Store resulting depth buffer as texture map*
  - *For every fragment generated while rendering from the camera position, project the fragment into the depth texture taken from the camera, and check if it passes the depth test.*

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## Shadow Volumes

### **Use new buffer: stencil buffer**

- Just another channel of the framebuffer
- Can count how often a pixel is drawn

### **Algorithm (1):**

- Generate silhouette polygons for all objects
  - *Polygons starting at silhouette edges of object*
  - *Extending away from light source towards infinity*
  - *These can be computed in vertex programs*

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## Shadow Volumes

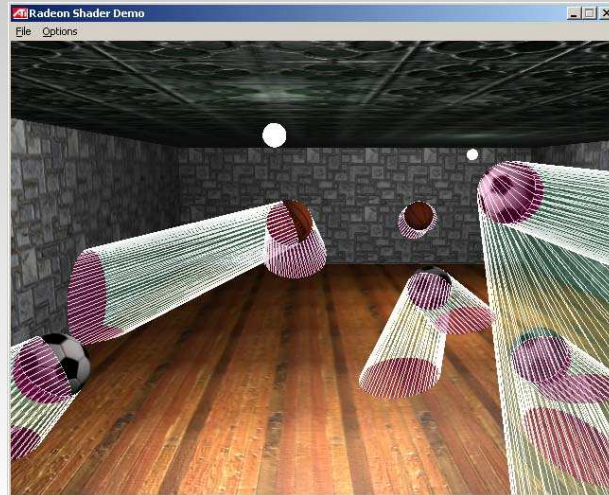


Image by ATI

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## Shadow Volumes

### **Algorithm (2):**

- Render all original geometry into the depth buffer
  - *i.e. do not draw any colors (or only draw ambient illumination term)*
- Render front-facing silhouette polygons while incrementing the stencil buffer for every rendered fragment
- Render back-facing silhouette polygons while decrementing the stencil buffer for every rendered fragment
- Draw illuminated geometry where the stencil buffer is 0, shadow elsewhere

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## Shadow Volumes



Image by ATI

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## Shadow Volumes

### **Discussion:**

- Object space method therefore no precision issues
- Lots of large polygons: can be slow
  - *High geometry count*
  - *Large number of pixels rendered*

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## Coming Up:

### **Friday**

- Quiz 2

### **Monday**

- Color

### **Later next week:**

- Ray-tracing