



Texture Mapping

Wolfgang Heidrich

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Course News

Assignment 2

- Due today

Assignment 3 (project)

- Out last Friday
- Start thinking about a project soon!

Quiz 2 MOVED!

- Friday, March 13 (instead of Wed, March 11)

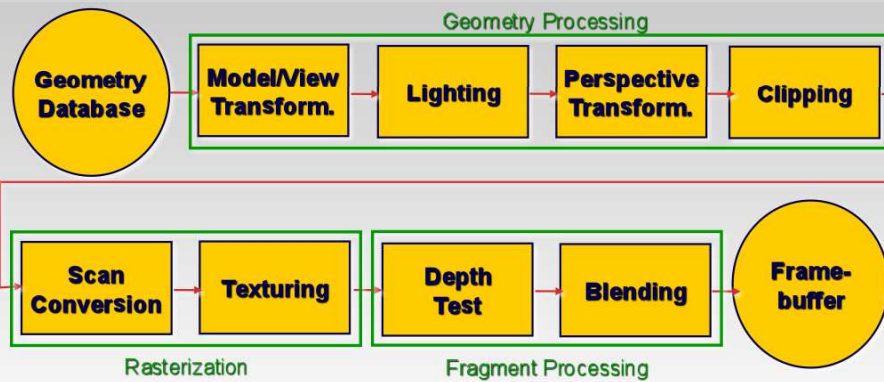
Reading

- Chapter 11 (w/o 11.8)

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The Rendering Pipeline



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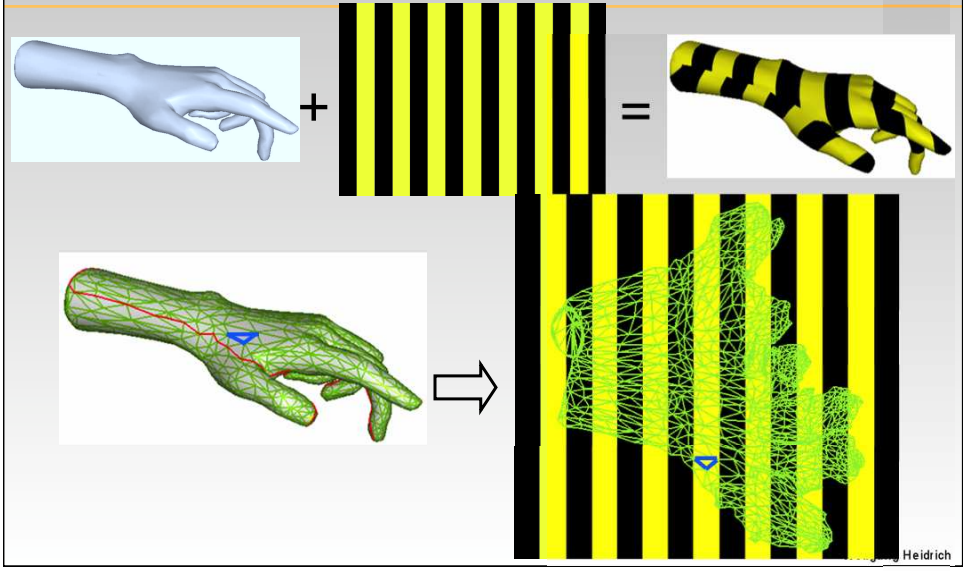
Texture Mapping

- Real life objects have nonuniform colors, normals
- To generate realistic objects, reproduce coloring & normal variations = **texture**
- Can often replace complex geometric details

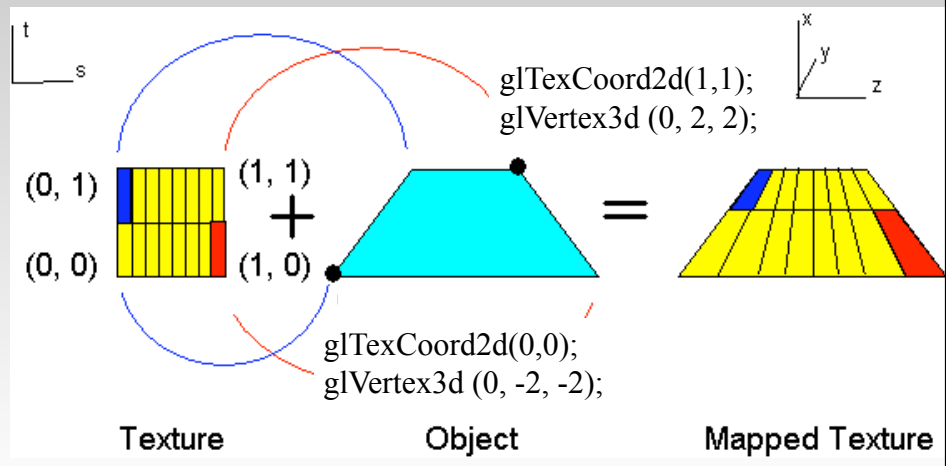


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Texture Mapping Example



Example Texture Map



Texture Lookup: Tiling and Clamping



What if s or t is outside the interval $[0...1]$? Multiple choices

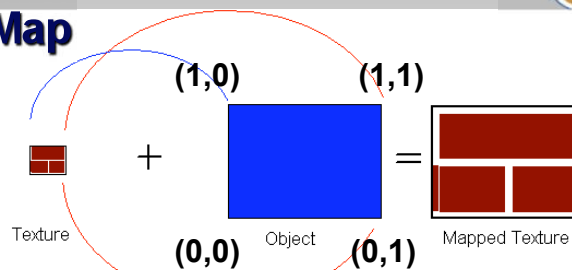
- Use fractional part of texture coordinates
 - Cyclic repetition of texture to tile whole surface
`glTexParameteri(..., GL_TEXTURE_WRAP_S, GL_REPEAT, GL_TEXTURE_WRAP_T, GL_REPEAT, ...)`
- Clamp every component to range $[0...1]$
 - Re-use color values from texture image border
`glTexParameteri(..., GL_TEXTURE_WRAP_S, GL_CLAMP, GL_TEXTURE_WRAP_T, GL_CLAMP, ...)`

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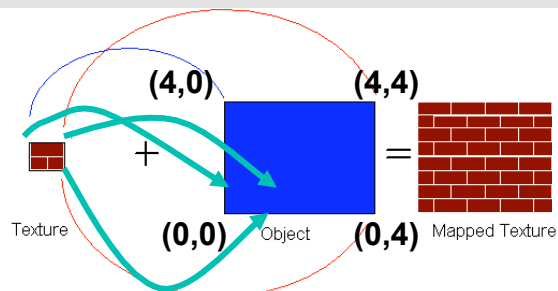
Tiled Texture Map



```
glTexCoord2d(1, 1);  
glVertex3d(x, y, z);
```



```
glTexCoord2d(4, 4);  
glVertex3d(x, y, z);
```



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Texture Coordinate Transformation

Motivation

- Change scale, orientation of texture on an object

Approach

- *Texture matrix stack*
- Transforms specified (or generated) tex coords

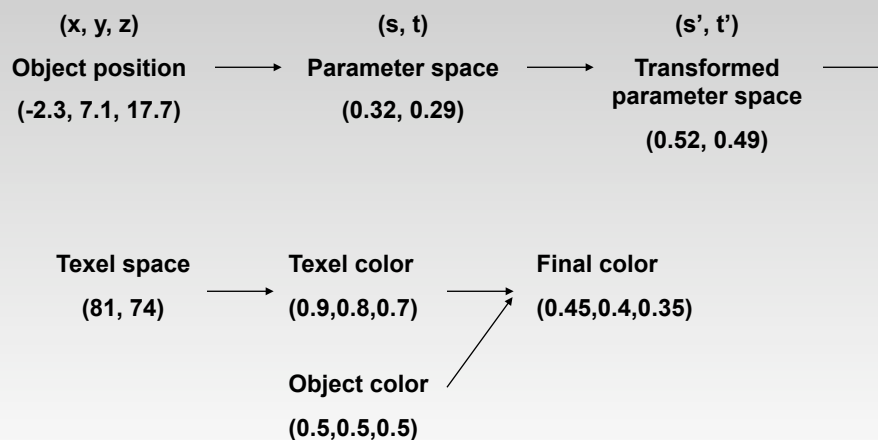
```
glMatrixMode( GL_TEXTURE );  
glLoadIdentity();  
glRotate();  
...
```

- More flexible than changing (s,t) coordinates

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Texture Pipeline



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Low-Level Details

Large range of functions for controlling layout of texture data

- State how the data in your image is arranged
- e.g.: `glPixelStorei(GL_UNPACK_ALIGNMENT, 1)` tells OpenGL not to skip bytes at the end of a row
- You must state how you want the texture to be put in memory: how many bits per “pixel”, which channels,...

Textures must have a size of power of 2

- Common sizes are 32x32, 64x64, 256x256
- But don't need to be square, i.e. 32x64 is fine
- Smaller uses less memory, and there is a finite amount of texture memory on graphics cards

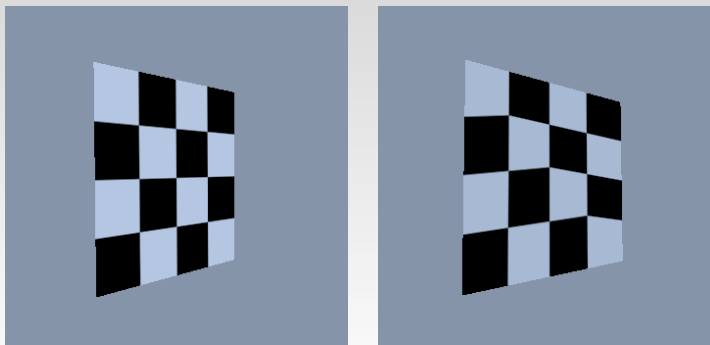
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Texture Mapping

Texture coordinate interpolation

- Perspective foreshortening problem



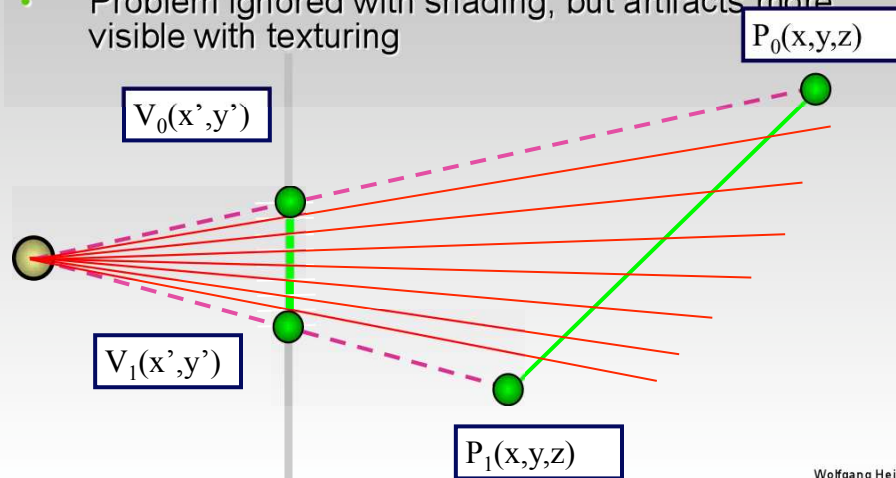
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Interpolation: Screen vs. World Space



Screen space interpolation incorrect

- Problem ignored with shading, but artifacts more visible with texturing



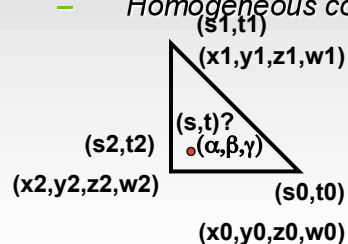
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Texture Coordinate Interpolation



Perspective correct interpolation

- α, β, γ :
 - Barycentric coordinates of a point P in a triangle
- s_0, s_1, s_2 :
 - Texture coordinates of vertices
- w_0, w_1, w_2 :
 - Homogeneous coordinates of vertices



$$s = \frac{\alpha \cdot s_0 / w_0 + \beta \cdot s_1 / w_1 + \gamma \cdot s_2 / w_2}{\alpha / w_0 + \beta / w_1 + \gamma / w_2}$$

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Texture Parameters

In addition to color can control other material/object properties

- Surface normal (bump mapping)
- Reflected color (environment mapping)



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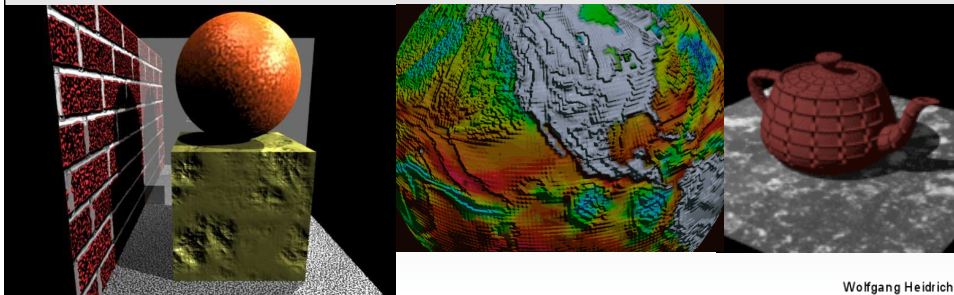


Bump Mapping: Normals As Texture

Object surface often not smooth – to recreate correctly need complex geometry model

Can control shape “effect” by locally perturbing surface normal

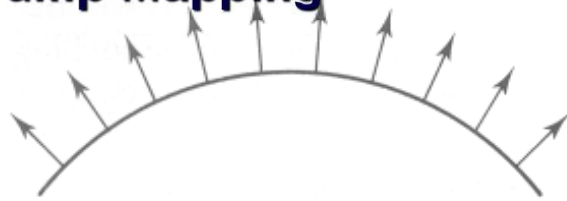
- Random perturbation
- Directional change over region



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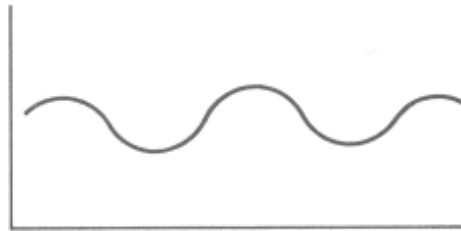


Bump Mapping



$O(u)$

Original surface



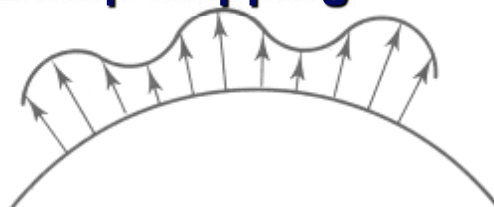
$B(u)$

A bump map

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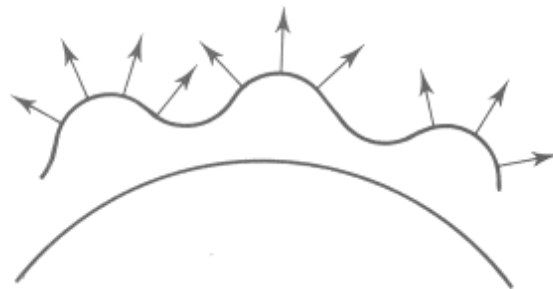


Bump Mapping



$O'(u)$

Lengthening or shortening
 $O(u)$ using $B(u)$



$N'(u)$

The vectors to the
'new' surface

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Displacement Mapping

Bump mapping gets silhouettes wrong

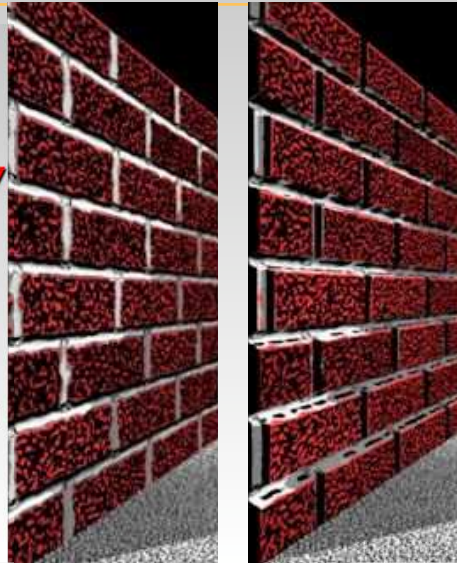
- Shadows wrong too

Change surface geometry instead

- Need to subdivide surface

GPU support

- Bump and displacement mapping not directly supported: require per-pixel lighting
- However: modern GPUs allow for programming both yourself



Environment Mapping

Cheap way to achieve reflective effect

- Generate image of surrounding
- Map to object as texture



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Sphere Mapping

Texture is distorted fish-eye view

- Point camera at mirrored sphere
- Spherical texture mapping creates texture coordinates that correctly index into this texture map

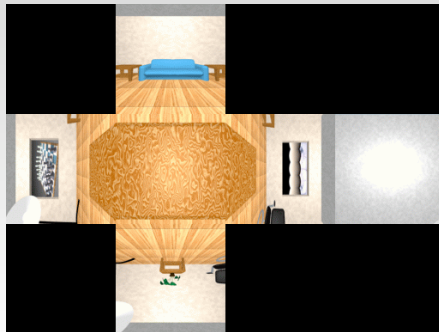


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Cube Mapping

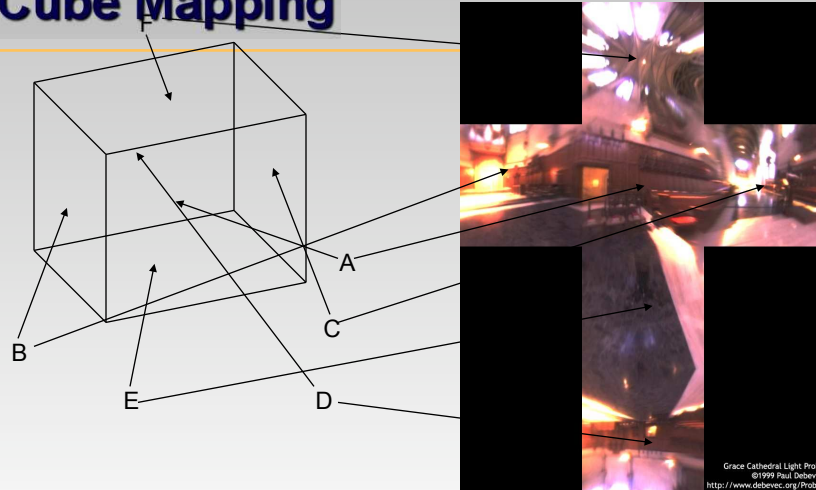
6 planar textures, sides of cube

- Point camera in 6 different directions, facing out from origin



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Cube Mapping



Grace Cathedral Light Probe
©1999 Paul Debevec
<http://www.csberkeley.org/Probes>

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Cube Mapping

Direction of reflection vector r selects the face of the cube to be indexed

- Co-ordinate with largest magnitude
 - e.g., the vector $(-0.2, 0.5, -0.84)$ selects the $-Z$ face
- Remaining two coordinates (normalized by the 3rd coordinate) selects the pixel from the face.
 - E.g., $(-0.2, 0.5)$ gets mapped to $(0.38, 0.80)$.

Difficulty in interpolating across faces

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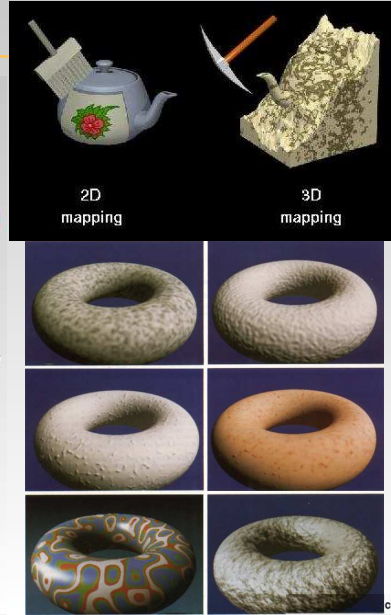
Volumetric (3D) Texture



Define texture pattern over 3D domain - 3D space containing the object

- Texture function can be **sampled**
 - 3D table of texels
- Or **procedural**
 - A function describes the color at each point
 - Implemented in special **shading language**

Common for natural material/irregular textures (stone, wood, etc...)



Procedural Textures



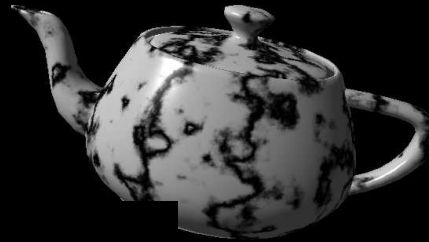
Generate “image” on the fly, instead of loading from disk

- Also called **shader**
- Often saves space
- Allows arbitrary level of detail
 - “magnification” not an issue
 - “minification” less so than for sampled representation
- But can be quite slow for complicated shaders



Volumetric Bump Mapping

Marble



Bump



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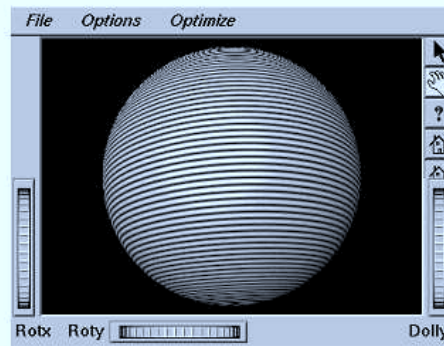
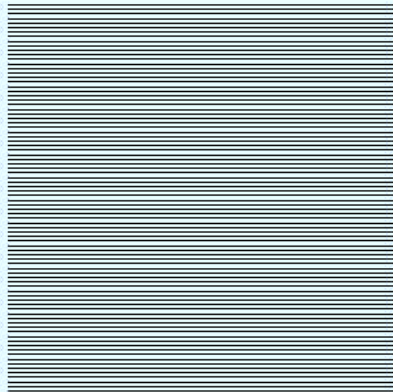
Volumetric Texture Mapping

In Hardware:

- Sampled 3D textures supported very much analogously to 2D textures:
 - `glTexCoord3f`, `glTexImage3f...`
- Procedural textures supported with modern GPUs
 - *More in upcoming lectures*

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Texture Lookup – Sampling & Reconstruction

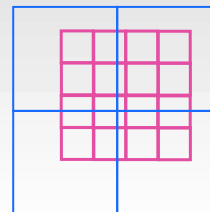
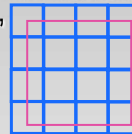


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Texture Lookup – Sampling & Reconstruction



- How to deal with:
 - **Pixels** that are much larger than **texels**?
 - Apply filtering, “averaging”
 - “Minification”
 - **Pixels** that are much smaller than **texels**?
 - Interpolate
 - “Magnification”

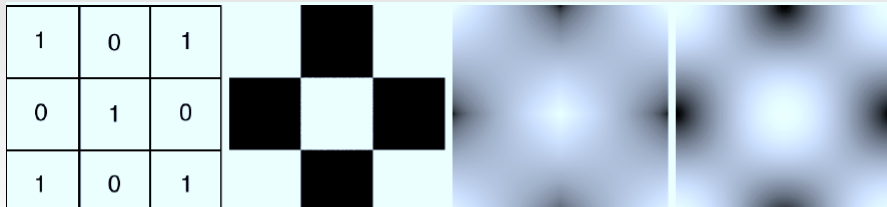


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Magnification: Interpolating Textures



- Nearest neighbor
- Bilinear
- Hermite (cubic)

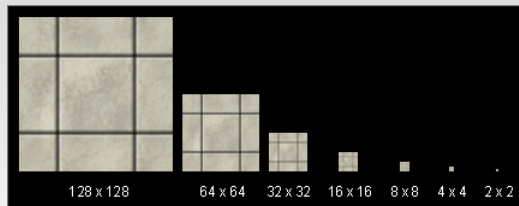


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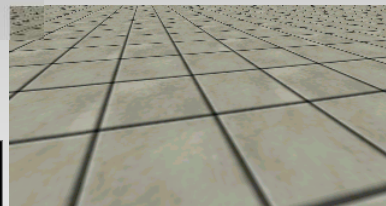
Minification: MIPmapping



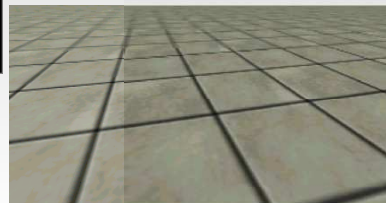
use "image pyramid" to precompute averaged versions of the texture



store whole pyramid in
single block of memory



Without MIP-mapping



With MIP-mapping

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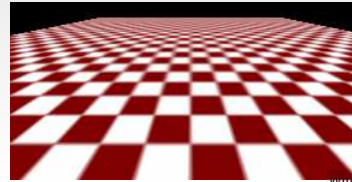
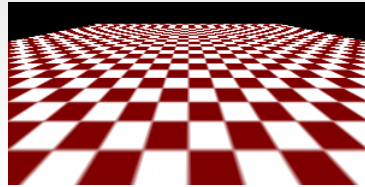
MIPmaps

Multum in parvo -- many things in a small place

- Prespecify a series of prefiltered texture maps of decreasing resolutions
- Requires more texture storage
- Avoid shimmering and flashing as objects move

gluBuild2DMipmaps

- Automatically constructs a family of textures from original texture size down to 1x1



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MIPmap storage

only 1/3 more space required



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Sampling & Reconstruction

CPSC 314

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Samples

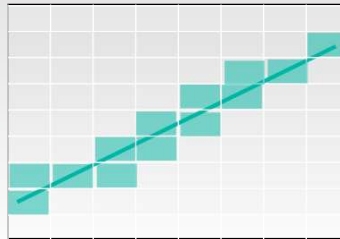
- Most things in the real world are **continuous**
- Everything in a computer is **discrete**
- The process of mapping a continuous function to a discrete one is called **sampling**
- The process of mapping a discrete function to a continuous one is called **reconstruction**
- The process of mapping a continuous variable to a discrete one is called **quantization**
- Rendering an image requires sampling and quantization
- Displaying an image involves reconstruction

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Line Segments

- We tried to sample a line segment so it would map to a 2D raster display
- We quantized the pixel values to 0 or 1
- We saw stair steps, or jaggies

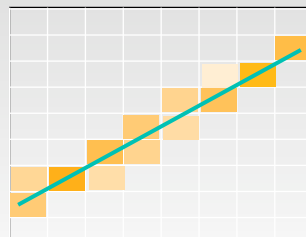


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Line Segments

- Instead, quantize to many shades
- But what sampling algorithm is used?



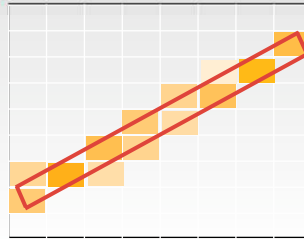
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Unweighted Area Sampling

Shade pixels wrt area covered by thickened line
Equal areas cause equal intensity, regardless of distance from pixel center to area

- Rough approximation formulated by dividing each pixel into a finer grid of pixels

Primitive cannot affect intensity of pixel if it does not intersect the pixel



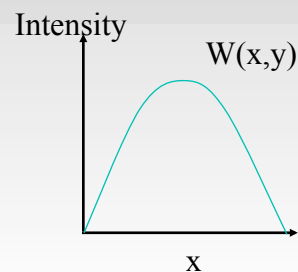
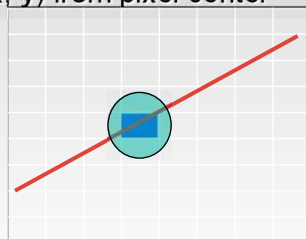
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Weighted Area Sampling

Intuitively, pixel cut through the center should be more heavily weighted than one cut along corner

Weighting function, $W(x,y)$

- Specifies the contribution of primitive passing through the point (x, y) from pixel center



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Images

An image is a 2D function $I(x, y)$

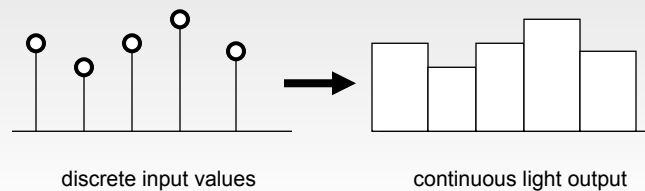
- Specifies intensity for each point (x, y)
- (we consider each color channel independently)



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Image Sampling and Reconstruction

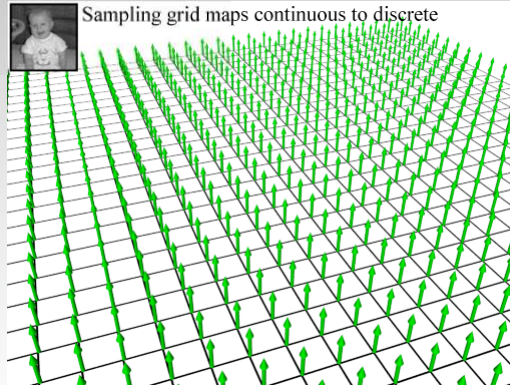
- Convert **continuous** image to **discrete** set of samples
 - Display hardware **reconstructs** samples into continuous image
- *Finite sized source of light for each pixel*



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Point Sampling an Image

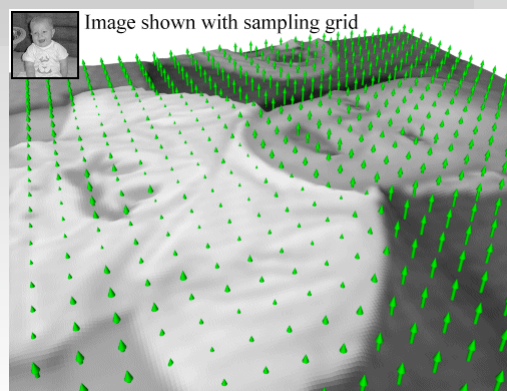
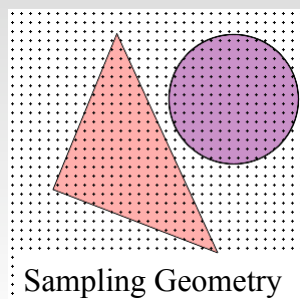
- Simplest sampling is on a grid
- Sample depends solely on value at grid points



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Point Sampling

Multiply sample grid by image intensity to obtain a discrete set of points, or samples.



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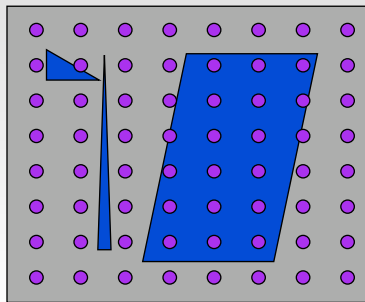


Sampling Errors

Some objects missed entirely, others poorly sampled

- Could try unweighted or weighted area sampling
- But how can we be sure we show everything?

Need to think about entire class of solutions!



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Image As Signal

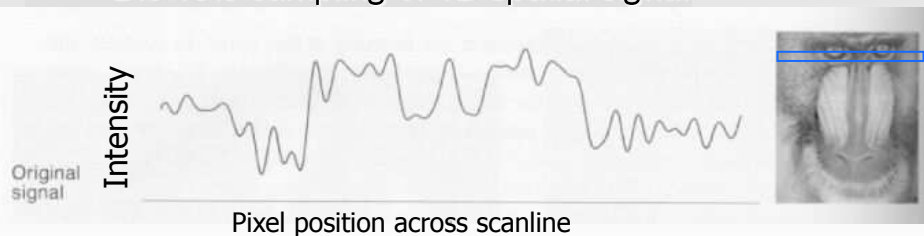
Image as spatial signal

2D raster image

- Discrete sampling of 2D spatial signal

1D slice of raster image

- Discrete sampling of 1D spatial signal



Examples from Foley, van Dam, Feiner, and Hughes

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Sampling Theory

How would we generate a signal like this out of simple building blocks?

Theorem

- Any signal can be represented as an (infinite) sum of sine waves at different frequencies

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Coming Up:

Wednesday / Friday

- More sampling & reconstruction

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