



# Transformation Hierarchies

***Wolfgang Heidrich***

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## Course News

### ***Assignment 1***

- Due February 2

### ***Homework 1***

- Exercise problems for transformations
- Discussed in labs next week

### ***Reading (this week)***

- Chapter 5

### ***Reading (next week)***

- Chapter 6

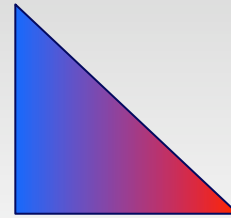
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## Recap: Rendering Geometry in OpenGL



### **Example:**

```
glBegin( GL_TRIANGLES );  
    glColor3f( 1.0, 0.0, 0.0 );  
    glVertex3f( 1.0, 0.0, 0.0 );  
    glColor3f( 0.0, 0.0, 1.0 );  
    glVertex3f( 0.0, 1.0, 0.0 );  
    glVertex3f( 0.0, 0.0, 0.0 );  
glEnd();
```



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## Recap: Rendering Geometry in OpenGL



### **Additional attributes**

- glColor3f: RGB color value (0...1 per component)
- glNormal3f: normal vector
- glTexCoord2f: texture coordinate (explained later)

### **OpenGL is state machine:**

- Every vertex gets color, normal etc. that corresponds to last specified value

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# Recap: Interpreting Composite OpenGL Transformations



## Example for earlier lectures:

- Rotation around arbitrary center
- In OpenGL:

```
// initialization of matrix
glMatrixMode( GL_MODELVIEW );
glLoadIdentity();

glTranslatef( 4, 3 );
glRotatef( 30, 0.0, 0.0, 1.0 );
glTranslatef( -4, -3 );

glBegin( GL_TRIANGLES );
// specify object geometry...
```

Top-to-bottom:  
transf. of  
coordinate frame

Bottom-to-top:  
transf. of  
object

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# Transformation Hierarchies

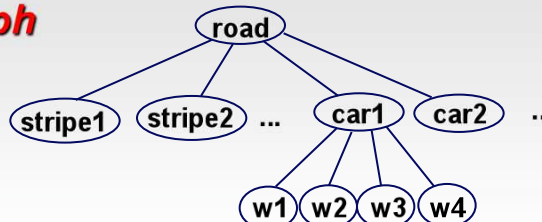


## Scene may have a hierarchy of coordinate systems

- Stores matrix at each level with incremental transform from parent's coordinate system



## Scene graph

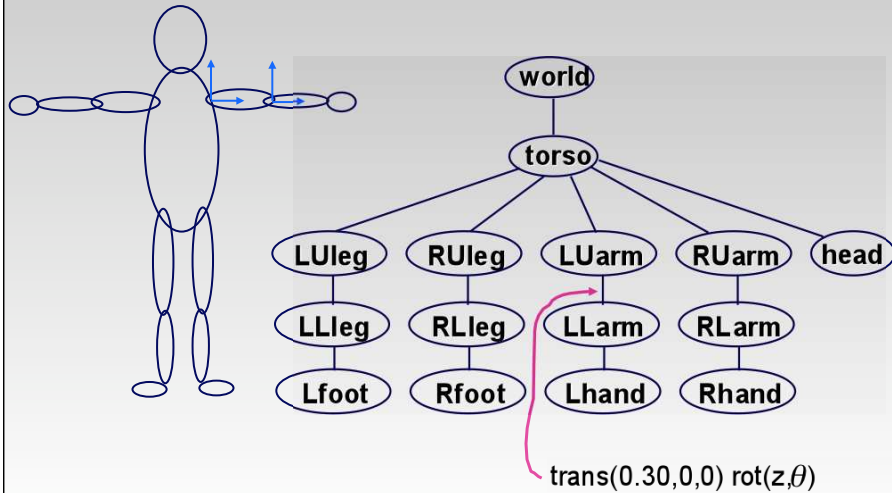


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# Transformation Hierarchy Example



1

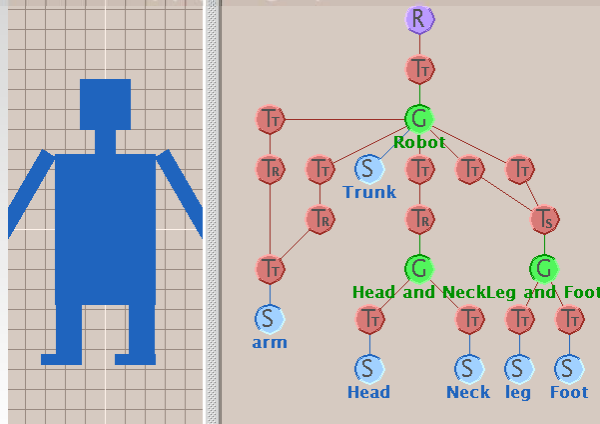


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# Transformation Hierarchies



- Hierarchies don't fall apart when changed
- transforms apply to graph nodes beneath



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## Brown Applets

<http://www.cs.brown.edu/exploratories/freeSoftware/catalogs/scenegraphs.html>



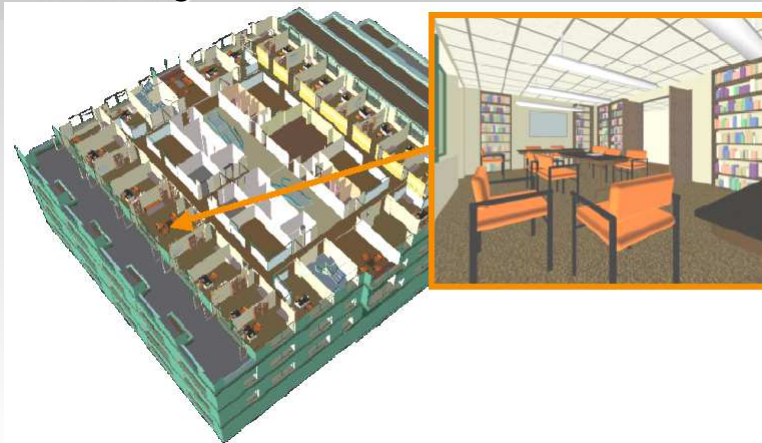
- Have a look later

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## Transformation Hierarchy Example 2

- Draw same 3D data with different transformations: instancing



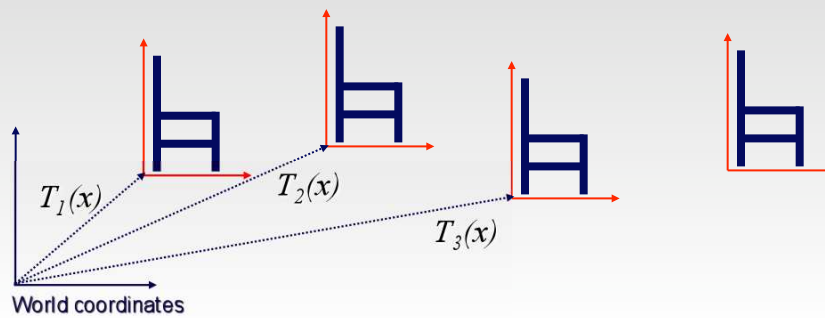
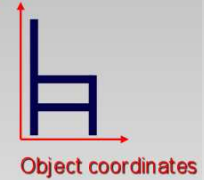
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# Matrix Stacks

## Challenge of avoiding unnecessary computation

- Using inverse to return to origin
- Computing incremental  $T_1 \rightarrow T_2$



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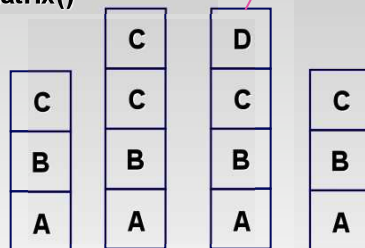


# Matrix Stacks

`glPushMatrix()`

`glPopMatrix()`

`D = C scale(2,2,2) trans(1,0,0)`



```

DrawSquare()
glPushMatrix()
glScale3f(2,2,2)
glTranslate3f(1,0,0)
DrawSquare()
glPopMatrix()

```

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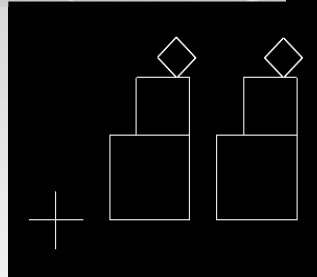


## Modularization

### Drawing a scaled square

- Push/pop ensures no coord system change

```
void drawBlock(float k) {  
    glPushMatrix();  
  
    glScalef(k,k,k);  
    glBegin(GL_LINE_LOOP);  
    glVertex3f(0,0,0);  
    glVertex3f(1,0,0);  
    glVertex3f(1,1,0);  
    glVertex3f(0,1,0);  
    glEnd();  
  
    glPopMatrix();  
}
```



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## Matrix Stacks

### Advantages

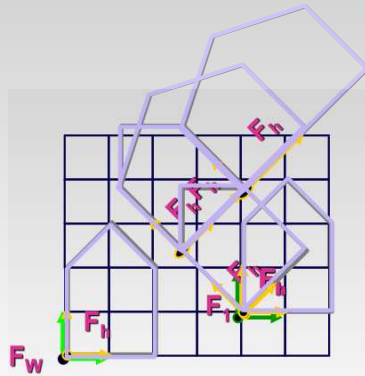
- No need to compute inverse matrices all the time
- Modularize changes to pipeline state
- Avoids incremental changes to coordinate systems
  - Accumulation of numerical errors

### Practical issues

- In graphics hardware, depth of matrix stacks is limited
  - (typically 16 for model/view and about 4 for projective matrix)

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## Transformation Hierarchy Example 3

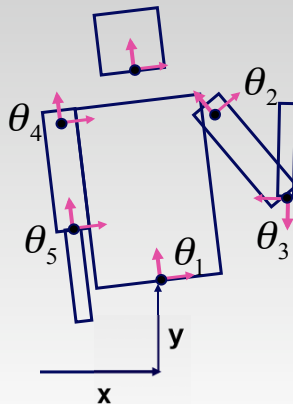
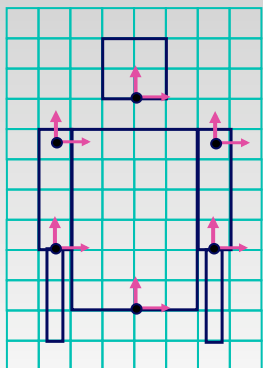


```

glLoadIdentity();
glTranslatef(4,1,0);
glPushMatrix();
glRotatef(45,0,0,1);
glTranslatef(0,2,0);
glScalef(2,1,1);
glTranslate(1,0,0);
glPopMatrix();
    
```

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## Transformation Hierarchy Example 4



```

glTranslate3f(x,y,0);
glRotatef(theta_1,0,0,1);
DrawBody();
glPushMatrix();
glTranslate3f(0,7,0);
DrawHead();
glPopMatrix();
glPushMatrix();
glTranslate(2.5,5.5,0);
glRotatef(theta_2,0,0,1);
DrawUArm();
glTranslate(0,-3.5,0);
glRotatef(theta_3,0,0,1);
DrawLArm();
glPopMatrix();
... (draw other arm)
    
```

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## Hierarchical Modeling

### Advantages

- Define object once, instantiate multiple copies
- Transformation parameters often good control knobs
- Maintain structural constraints if well-designed

### Limitations

- Expressivity: not always the best controls
- Can't do closed kinematic chains
  - *Keep hand on hip*

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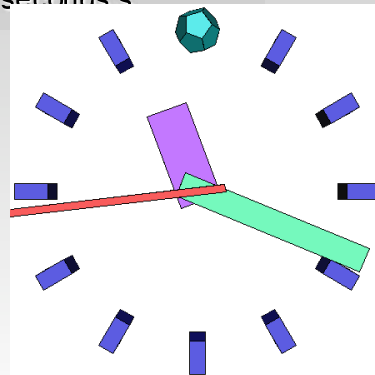


## Single Parameter: simple

### Parameters as functions of other params

- Clock: control all hands with seconds  $s$

$$\begin{aligned}m &= s/60, h=m/60, \\ \text{theta}_s &= (2 \pi s) / 60, \\ \text{theta}_m &= (2 \pi m) / 60, \\ \text{theta}_h &= (2 \pi h) / 60\end{aligned}$$



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## Single Parameter: complex

***Mechanisms not easily expressible with affine transforms***



<http://www.flying-pig.co.uk>

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## Representing Complex Geometry

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## Display Lists

### Concept:

- If multiple copies of an object are required, it can be compiled into a display list:

```
glNewList( listId, GL_COMPILE );
```

```
glBegin( ... );
```

```
... // geometry goes here
```

```
glEndList();
```

```
// render two copies of geometry offset by 1 in z-direction:
```

```
glCallList( listId );
```

```
glTranslatef( 0.0, 0.0, 1.0 );
```

```
glCallList( listId );
```

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## Display Lists

### Advantages:

- More efficient than individual function calls for every vertex/attribute
- Can be cached on the graphics board (bandwidth!)
- Display lists exist across multiple frames
  - *Represent static objects in an interactive application*

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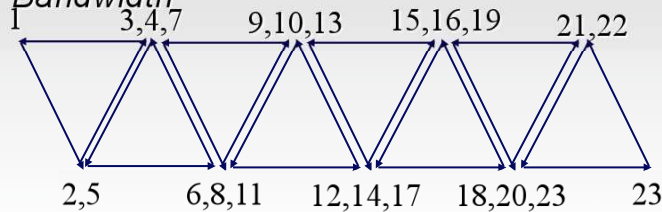
## Shared Vertices

### Triangle Meshes

- Multiple triangles share vertices
- If individual triangles are sent to graphics board, every vertex is sent and transformed multiple times!

— *Computational expense*

— *Bandwidth*



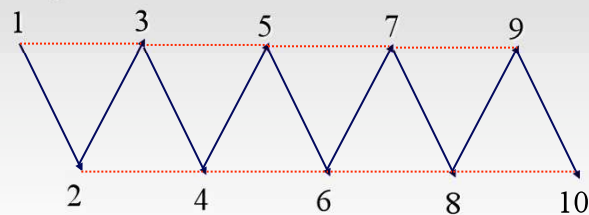
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## Triangle Strips

### Idea:

- Encode neighboring triangles that share vertices
- Use an encoding that requires only a constant-sized part of the whole geometry to determine a single triangle
- $N$  triangles need  $n+2$  vertices



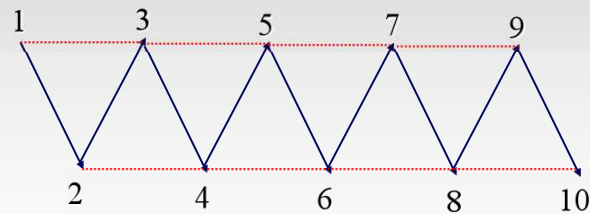
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## Triangle Strips

### **Orientation:**

- Strip starts with a counter-clockwise triangle
- Then alternates between clockwise and counter-clockwise



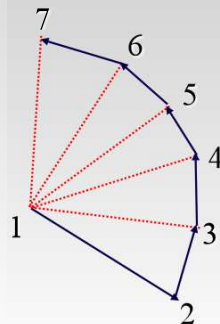
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## Triangle Fans

### **Similar concept:**

- All triangles share on center vertex
- All other vertices are specified in CCW order



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## Triangle Strips and Fans

### Transformations:

- $n+2$  for  $n$  triangles
- Only requires 3 vertices to be stored according to simple access scheme
- Ideal for pipeline (local knowledge)

### Generation

- E.g. from directed edge data structure
- Optimize for longest strips/fans



Strippification by Dana Sharon

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## Vertex Arrays

### Concept:

- Store array of vertex data for meshes with arbitrary connectivity (topology)

```
GLfloat *points[3*nvertices];
```

```
GLfloat *colors[3*nvertices];
```

```
GLuint *tris[numtris]=
```

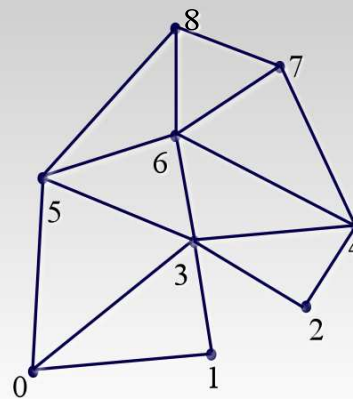
```
    {0,1,3, 3,2,4, ...};
```

```
glVertexPointer( ..., points );
```

```
glColorPointer( ..., colors );
```

```
glDrawElements(
```

```
    GL_TRIANGLES, ..., tris );
```



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## Vertex Arrays

### Benefits:

- Ideally, vertex array fits into memory on GPU
- Then all vertices are transformed exactly once

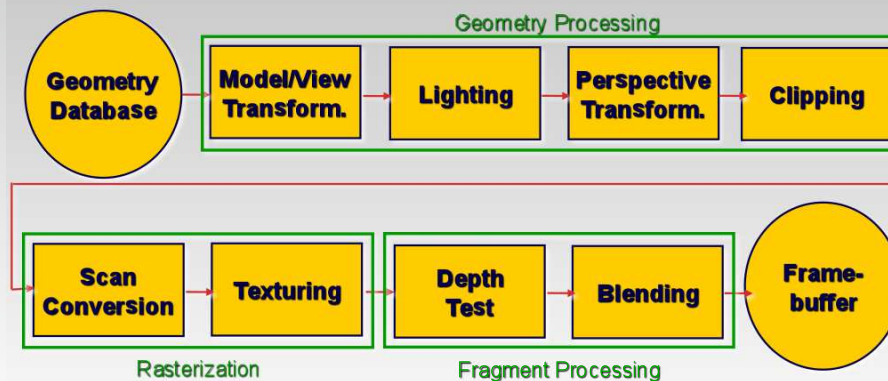
### In practice:

- Graphics memory may not be sufficient to hold model
- Then either:
  - Cache only parts of the vertex array on board (may lead to cache trashing!)
  - Transform everything in software and just send results for individual triangles (bandwidth problem: multiple transfers of same vertex!)

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## The Rendering Pipeline



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## Coming Up:

### **Next Week:**

- Perspective projection
- Lighting/shading