

#### Motion Capture



Data Acquisition

- mechanical
  - joint angles
- electromagnetic
   6 DOF sensors



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## **Data Acquisition (cont)**



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- active optical systems
  - self-identifying markers
- passive optical systems





# Data Acquisition (cont)



- building a skeleton
  - joint locations, limb lengths
- from marker positions to joint angles
- data cleanup

## **Editing Mocap Data**



- map onto a new character
  - e.g., character that is larger than actor
- change the motion
  - e.g, walk with larger steps, higher jump
- take physics into account?
- maintaining constraints
  - footskate cleanup
- mirroring and transplanting limbs

#### **Using Mocap Data**

- continuous motion spaces
  *e.g., walk(speed, turning rate)*
- discrete motion spaces
  - e.g., motion graphs from motion capture soup
  - e.g., designed motion trees for games
  - when can we transition btwn two motions?
  - what should the blend time be?
  - which motions to add?



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## Using Mocap Data (cont)



- planning in discrete and continous motion spaces
- · UIs for using discrete and continous motion spaces
- abstracting motion style

Limitations of mocap

- can never have enough motion data !
- complex interactions with the environment, e.g, tripping over a box; colliding football players
- motion done in the context of an environment and this context is not captured e.g., objects, other people
- motions can be composed e.g., can walk and scratch one's head
- motion can have huge variation and expressiveness e.g., acting, dancing, particular walk e.g., facial animation
- not a predictive model