



University of British Columbia  
 CPSC 314 Computer Graphics  
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**Interpolation**  
**Clipping**

**Week 7, Mon Feb 21**

<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2005>

## News

- grades for p1, h2 posted

2

## Interpolation

3

## Scan Conversion

- done
- how to determine pixels covered by a primitive
- next
  - how to assign pixel colors
    - interpolation of colors across triangles
    - interpolation of other properties

4

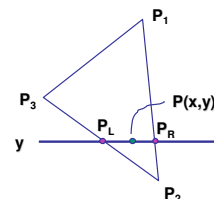
## Interpolation During Scan Conversion

- interpolate values between vertices
  - z values
  - r,g,b colour components
    - use for Gouraud shading
  - u,v texture coordinates
  - $N_x, N_y, N_z$  surface normals
- equivalent methods (for triangles)
  - bilinear interpolation
  - barycentric coordinates

5

## Bilinear Interpolation

- interpolate quantity along  $L$  and  $R$  edges, as a function of  $y$ 
  - then interpolate quantity as a function of  $x$



6

### Barycentric Coordinates

- weighted combination of vertices

$$\begin{cases} P = \alpha \cdot P_1 + \beta \cdot P_2 + \gamma \cdot P_3 \\ \alpha + \beta + \gamma = 1 \\ 0 \leq \alpha, \beta, \gamma \leq 1 \end{cases}$$

"convex combination of points"

7

### Computing Barycentric Coordinates

- for point P on scanline

$$\begin{aligned} P_L &= P_2 + \frac{d_1}{d_1+d_2} (P_3 - P_2) \\ &= (1 - \frac{d_1}{d_1+d_2}) P_2 + \frac{d_1}{d_1+d_2} P_3 = \\ &= \frac{d_2}{d_1+d_2} P_2 + \frac{d_1}{d_1+d_2} P_3 \end{aligned}$$

8

### Computing Barycentric Coordinates

- similarly

$$\begin{aligned} P_R &= P_2 + \frac{b_1}{b_1+b_2} (P_1 - P_2) \\ &= (1 - \frac{b_1}{b_1+b_2}) P_2 + \frac{b_1}{b_1+b_2} P_1 = \\ &= \frac{b_2}{b_1+b_2} P_2 + \frac{b_1}{b_1+b_2} P_1 \end{aligned}$$

9

### Computing Barycentric Coordinates

- combining

$$\begin{aligned} P &= \frac{c_2}{c_1+c_2} \cdot P_L + \frac{c_1}{c_1+c_2} \cdot P_R \\ P_L &= \frac{d_2}{d_1+d_2} P_2 + \frac{d_1}{d_1+d_2} P_3 \\ P_R &= \frac{b_2}{b_1+b_2} P_2 + \frac{b_1}{b_1+b_2} P_1 \end{aligned}$$

- gives  $P_2$

$$P = \frac{c_2}{c_1+c_2} \left( \frac{d_2}{d_1+d_2} P_2 + \frac{d_1}{d_1+d_2} P_3 \right) + \frac{c_1}{c_1+c_2} \left( \frac{b_2}{b_1+b_2} P_2 + \frac{b_1}{b_1+b_2} P_1 \right)$$

10

### Computing Barycentric Coordinates

$$P = \frac{c_2}{c_1+c_2} \left( \frac{d_2}{d_1+d_2} P_2 + \frac{d_1}{d_1+d_2} P_3 \right) + \frac{c_1}{c_1+c_2} \left( \frac{b_2}{b_1+b_2} P_2 + \frac{b_1}{b_1+b_2} P_1 \right)$$

- thus  $P = a_1 \cdot P_1 + a_2 \cdot P_2 + a_3 \cdot P_3$

with

$$\begin{aligned} a_1 &= \frac{c_1}{c_1+c_2} \frac{b_1}{b_1+b_2} \\ a_2 &= \frac{c_2}{c_1+c_2} \frac{d_2}{d_1+d_2} + \frac{c_1}{c_1+c_2} \frac{b_2}{b_1+b_2} \\ a_3 &= \frac{c_2}{c_1+c_2} \frac{d_1}{d_1+d_2} \end{aligned}$$

11

### Computing Barycentric Coordinates

- can verify barycentric properties

$$\begin{aligned} a_1 + a_2 + a_3 &= 1 \\ 0 \leq a_1, a_2, a_3 &\leq 1 \end{aligned}$$

$$\begin{aligned} a_1 &= \frac{c_1}{c_1+c_2} \frac{b_1}{b_1+b_2} \\ a_2 &= \frac{c_2}{c_1+c_2} \frac{d_2}{d_1+d_2} + \frac{c_1}{c_1+c_2} \frac{b_2}{b_1+b_2} \\ a_3 &= \frac{c_2}{c_1+c_2} \frac{d_1}{d_1+d_2} \end{aligned}$$

12

## Clipping

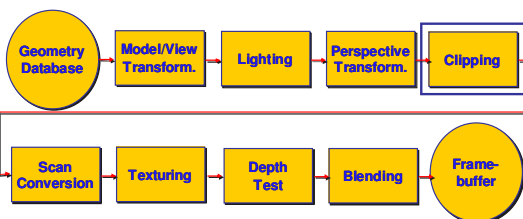
13

## Reading

- FCG Chapter 11
  - pp 209-214 only: clipping

14

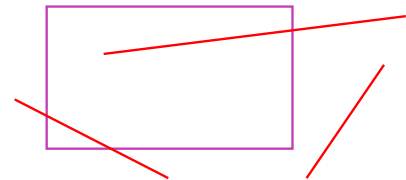
## Rendering Pipeline



15

## Next Topic: Clipping

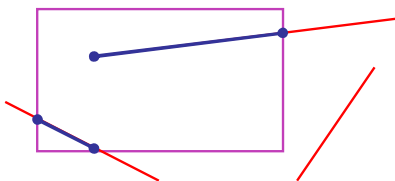
- we've been assuming that all primitives (lines, triangles, polygons) lie entirely within the *viewport*
  - in general, this assumption will not hold:



16

## Clipping

- analytically calculating the portions of primitives within the viewport



17

## Why Clip?

- bad idea to rasterize outside of framebuffer bounds
- also, don't waste time scan converting pixels outside window
  - could be billions of pixels for very close objects!

18

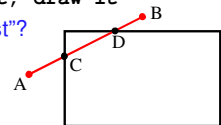
## Line Clipping

- 2D
  - determine portion of line inside an axis-aligned rectangle (screen or window)
- 3D
  - determine portion of line inside axis-aligned parallelepiped (viewing frustum in NDC)
  - simple extension to 2D algorithms

19

## Clipping

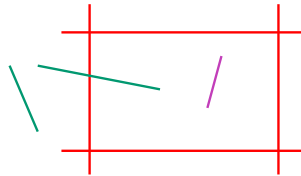
- naïve approach to clipping lines:
  - for each line segment
  - for each edge of viewport
  - find intersection point
  - pick "nearest" point
  - if anything is left, draw it
- what do we mean by "nearest"?
- how can we optimize this?



20

## Trivial Accepts

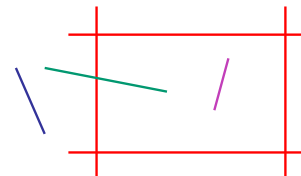
- big optimization: trivial accept/rejects
  - Q: how can we quickly determine whether a line segment is entirely inside the viewport?
  - A: test both endpoints



21

## Trivial Rejects

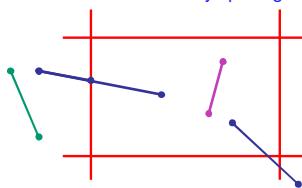
- Q: how can we know a line is outside viewport?
- A: if both endpoints on wrong side of same edge, can trivially reject line



22

## Clipping Lines To Viewport

- combining trivial accepts/rejects
  - trivially accept lines with both endpoints inside all edges of the viewport
  - trivially reject lines with both endpoints outside the same edge of the viewport
  - otherwise, reduce to trivial cases by splitting into two segments

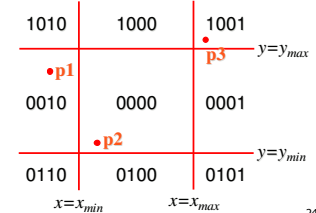


23

## Cohen-Sutherland Line Clipping

- outcodes
  - 4 flags encoding position of a point relative to top, bottom, left, and right boundary

- $OC(p1)=0010$
- $OC(p2)=0000$
- $OC(p3)=1001$



24

## Cohen-Sutherland Line Clipping

- assign outcode to each vertex of line to test
  - line segment:  $(p1, p2)$
- trivial cases
  - $OC(p1) == 0$  &&  $OC(p2) == 0$ 
    - both points inside window, thus line segment completely visible (trivial accept)
  - $(OC(p1) \& OC(p2)) != 0$ 
    - there is (at least) one boundary for which both points are outside (same flag set in both outcodes)
    - thus line segment completely outside window (trivial reject)

25

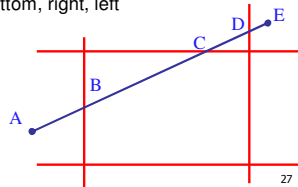
## Cohen-Sutherland Line Clipping

- if line cannot be trivially accepted or rejected, subdivide so that one or both segments can be discarded
  - pick an edge that the line crosses (*how?*)
  - intersect line with edge (*how?*)
  - discard portion on wrong side of edge and assign outcode to new vertex
  - apply trivial accept/reject tests; repeat if necessary

26

## Cohen-Sutherland Line Clipping

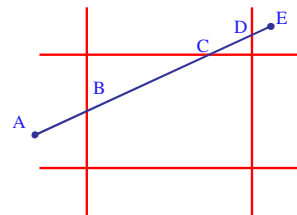
- if line cannot be trivially accepted or rejected, subdivide so that one or both segments can be discarded
  - pick an edge that the line crosses
    - check against edges in same order each time
      - for example: top, bottom, right, left



27

## Cohen-Sutherland Line Clipping

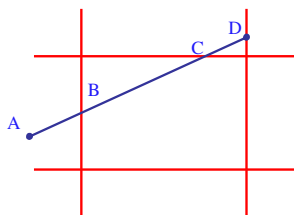
- intersect line with edge (*how?*)



28

## Cohen-Sutherland Line Clipping

- discard portion on wrong side of edge and assign outcode to new vertex

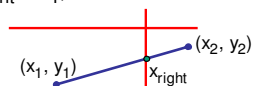


- apply trivial accept/reject tests and repeat if necessary

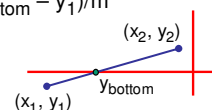
29

## Viewport Intersection Code

- $(x_1, y_1), (x_2, y_2)$  intersect vertical edge at  $x_{right}$ 
  - $y_{intersect} = y_1 + m(x_{right} - x_1)$
  - $m = (y_2 - y_1) / (x_2 - x_1)$



- $(x_1, y_1), (x_2, y_2)$  intersect horiz edge at  $y_{bottom}$ 
  - $x_{intersect} = x_1 + (y_{bottom} - y_1) / m$
  - $m = (y_2 - y_1) / (x_2 - x_1)$



30

### Cohen-Sutherland Discussion

- use opcodes to quickly eliminate/include lines
  - best algorithm when trivial accepts/rejects are common
- must compute viewport clipping of remaining lines
  - non-trivial clipping cost
  - redundant clipping of some lines
- more efficient algorithms exist

31

### Line Clipping in 3D

- approach
  - clip against parallelepiped in NDC
    - after perspective transform
  - means that clipping volume always the same
    - $x_{min}=y_{min}=-1, x_{max}=y_{max}=1$  in OpenGL
- boundary lines become boundary planes
  - but outcodes still work the same way
  - additional front and back clipping plane
    - $z_{min} = -1, z_{max} = 1$  in OpenGL

32

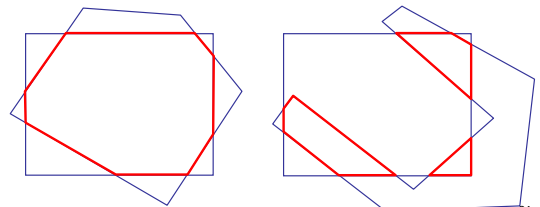
### Polygon Clipping

- objective
  - 2D: clip polygon against rectangular window
    - or general convex polygons
    - extensions for non-convex or general polygons
  - 3D: clip polygon against parallelepiped

33

### Polygon Clipping

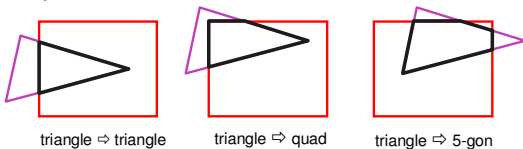
- not just clipping all boundary lines
  - may have to introduce new line segments



34

### Why Is Clipping Hard?

- what happens to a triangle during clipping?
- possible outcomes:

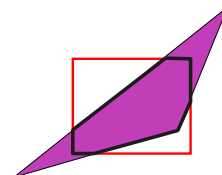


- how many sides can a clipped triangle have?

35

### How Many Sides?

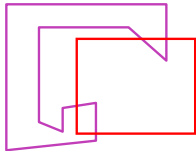
- seven...



36

### Why Is Clipping Hard?

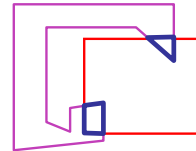
- a really tough case:



37

### Why Is Clipping Hard?

- a really tough case:



concave polygon  $\Rightarrow$  multiple polygons

38

### Polygon Clipping

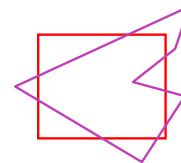
- classes of polygons
  - triangles
  - convex
  - concave
  - holes and self-intersection



39

### Sutherland-Hodgeman Clipping

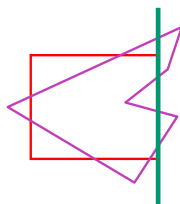
- basic idea:
  - consider each edge of the viewport individually
  - clip the polygon against the edge equation
  - after doing all edges, the polygon is fully clipped



40

### Sutherland-Hodgeman Clipping

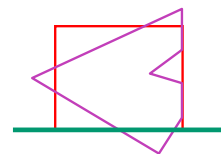
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41

### Sutherland-Hodgeman Clipping

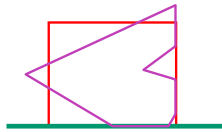
- basic idea:
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42

### Sutherland-Hodgeman Clipping

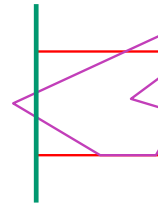
- basic idea:
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  - after doing all edges, the polygon is fully clipped



43

### Sutherland-Hodgeman Clipping

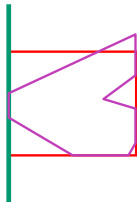
- basic idea:
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  - after doing all edges, the polygon is fully clipped



44

### Sutherland-Hodgeman Clipping

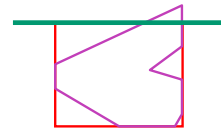
- basic idea:
  - consider each edge of the viewport individually
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  - after doing all edges, the polygon is fully clipped



45

### Sutherland-Hodgeman Clipping

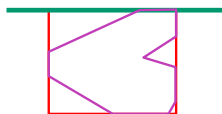
- basic idea:
  - consider each edge of the viewport individually
  - clip the polygon against the edge equation
  - after doing all edges, the polygon is fully clipped



46

### Sutherland-Hodgeman Clipping

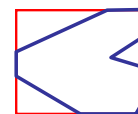
- basic idea:
  - consider each edge of the viewport individually
  - clip the polygon against the edge equation
  - after doing all edges, the polygon is fully clipped



47

### Sutherland-Hodgeman Clipping

- basic idea:
  - consider each edge of the viewport individually
  - clip the polygon against the edge equation
  - after doing all edges, the polygon is fully clipped



48

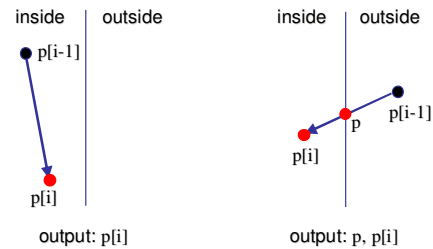
## Sutherland-Hodgeman Algorithm

- input/output for algorithm
  - input: list of polygon vertices in order
  - output: list of clipped polygon vertices consisting of old vertices (maybe) and new vertices (maybe)
- basic routine
  - go around polygon one vertex at a time
  - decide what to do based on 4 possibilities
    - is vertex inside or outside?
    - is previous vertex inside or outside?

49

## Clipping Against One Edge

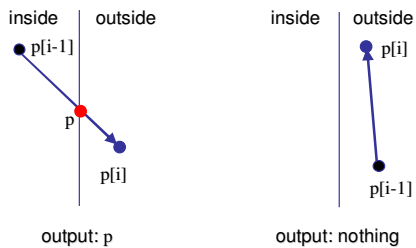
- $p[i]$  inside: 2 cases



50

## Clipping Against One Edge

- $p[i]$  outside: 2 cases



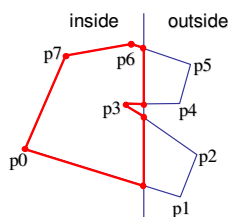
51

## Clipping Against One Edge

```
clipPolygonToEdge( p[n], edge ) {
  for( i= 0 ; i< n ; i++ ) {
    if( p[i] inside edge ) {
      if( p[i-1] inside edge ) output p[i]; // p[-1]= p[n-1]
      else {
        p= intersect( p[i-1], p[i], edge ); output p, p[i];
      }
    } else { // p[i] is outside edge
      if( p[i-1] inside edge ) {
        p= intersect( p[i-1], p[i], edge ); output p;
      }
    }
  }
}
```

52

## Sutherland-Hodgeman Example



53

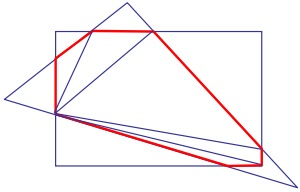
## Sutherland-Hodgeman Discussion

- similar to Cohen/Sutherland line clipping
  - inside/outside tests: outcodes
  - intersection of line segment with edge: window-edge coordinates
- clipping against individual edges independent
  - great for hardware (pipelining)
  - all vertices required in memory at same time
    - not so good, but unavoidable
    - another reason for using triangles only in hardware rendering

54

### Sutherland/Hodgeman Discussion

- for rendering pipeline:
  - re-triangulate resulting polygon  
(can be done for every individual clipping edge)



55