

Computer Animation

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(preview of CPSC 426)

cs533d-winter-2005 1

Computer Animation

- ◆ Offline: generate a film, play it back later
- ◆ We long ago reached the point of being able to render anything an artist could model
- ◆ The problem is: how to model?
 - Tools/UI for directly specifying model+motion (the traditional technique)
 - Procedural modeling (e.g. particle systems)
 - Data-driven modeling (e.g. motion capture)
 - Physics-based modeling (e.g. fluid simulation)

cs533d-winter-2005 2

Real-Time Animation

- ◆ For example, games
- ◆ Rendering limited, modeling even more limited
- ◆ “Traditional” technique - replay scripted motions
 - But scalability/realism are becoming a problem
 - Need to generate more new motion on the fly

cs533d-winter-2005 3

Traditional CG animation

- ◆ Grew out of traditional animation
- ◆ [Pixar]
- ◆ Every detail of every model is parameterized
 - E.g. position and orientation of base of lamp, joint angles, lengths, light intensity, control points for spline curve of power cord, ...
- ◆ Associate a “motion curve” with each parameter - how it changes in time
- ◆ Animating == designing motion curves

cs533d-winter-2005 4

Motion Curves

- ◆ Keyframe approach:
 - Artist sets extreme values at important frames
 - Computer fills in the rest with splines
 - Artist adjusts spline controls, slopes, adds more points, adjusts, readjusts, re-readjusts, ...
- ◆ Straight-ahead approach:
 - Artist simply sets parameters in each successive frame
- ◆ Layering approach:
 - Design the basic motion curves first, layer detail on afterwards

cs533d-winter-2005 5

Motion Curve Tools

- ◆ Retiming: keep the shape of the trajectory, but change how fast we go along it
 - Add a new abstract motion curve controlling distance traveled along trajectory
- ◆ Inverse Kinematics (IK):
 - Given a skeleton (specified by joint angles)
 - Artist directly controls where parts of the skeleton go, computer solves for the angles that achieve that

cs533d-winter-2005 6

Procedural Modeling

- ◆ Write programs to automatically generate models and motion
- ◆ For example, “flocking behaviour”
- ◆ Build a flock of birds by specifying simple rules of motion:
 - Accelerate to avoid collisions
 - Accelerate to fly at preferred distance to nearby birds
 - Accelerate to fly at same velocity as nearby birds
 - Accelerate to follow “migratory” impulse
- ◆ Let it go, hope the results look good

cs533d-winter-2005 7

Data-Driven Modeling

- ◆ Measure the real world, use that data to synthesize models
 - Laser scanners
 - Camera systems for measuring reflectance properties
 - Image-Based Rendering - e.g. Spiderman
 - ...

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Data-Driven Motion

- ◆ Record real motion (motion capture = mocap)
- ◆ Then play it back
- ◆ But life is never that simple
 - Real motion is hard to measure
 - Measurements are noisy
 - Won't quite fit what you needed
 - Not obviously adaptable to new environments, interactive control, etc.

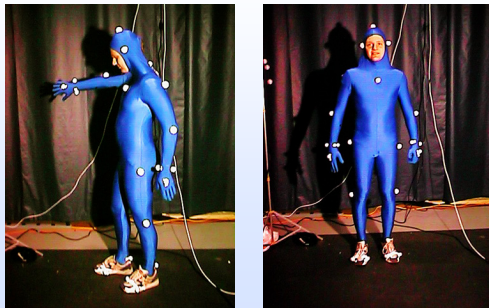
cs533d-winter-2005 9

Marker-based mocap

- ◆ Stick performer in a tight black suit, stick markers on body, limbs, ...
- ◆ Film motion with an infrared strobe light and multiple calibrated cameras
- ◆ Reconstruct 3D trajectories of markers, filling in gaps and eliminating noise
- ◆ Infer motion of abstract skeleton
- ◆ Clean up data
- ◆ Drive CG skeleton with recorded motion curves

cs533d-winter-2005 10

What it looks like...



(from Zoran Popovic's website)

cs533d-winter-2005 11

Footskate and Clean Up

- ◆ Most common problem: footskate
 - Feet that in reality were stuck to floor hover and slip around
- ◆ Fix using IK: determine target footplants, automatically adjust joint angles to keep feet planted
 - Often OK to even adjust limb lengths...

cs533d-winter-2005 12

Motion Control

- ◆ How do you adapt mocap data to new purposes?
 - Motion graphs (remixing)
 - Motion parameterization (adjust mocap data)
 - Motion texturing (add mocap details to traditional animation)

cs533d-winter-2005 13

Motion Graphs

- ◆ Chop up recorded data into tiny clips
 - Aim to cut at common poses
- ◆ Build graph on clips: connect two clips if the end pose of one is similar to the start pose of another
- ◆ Then walk the graph
 - Figure out smooth transitions from clip to clip
 - Navigate a small finite graph instead of infinite space of all possible motions

cs533d-winter-2005 14

Physics-based modeling

- ◆ Like procedural modeling, only based on laws of physics
- ◆ If you want realistic motion, simulate reality
- ◆ Human motion:
 - Specify muscle forces (joint torques), simulate actual motion
 - Has to conserve momentum etc.
 - Can handle the unexpected (e.g. a tackle)
 - But need to write motion controllers
- ◆ Passive motion:
 - Figure out physical laws behind natural phenomena
 - Simulate (close cousin of scientific computing)

cs533d-winter-2005 15

Example: particle dynamics

- ◆ Newton's law: $F=ma$
 - Rewrite as $\frac{dv}{dt} = a = \frac{F}{m}$, $\frac{dx}{dt} = v$
 - Simplest good solver: symplectic Euler

$$v^{new} = v + \Delta t \frac{F(x,v)}{m}$$
$$x^{new} = x + \Delta t v^{new}$$

cs533d-winter-2005 16

Particle forces

- ◆ For next animation, damped spring between nearby particles
 - Elastic force pushes/pulls between two nearby particles to make them preferred distance apart
 - Damping force slows down relative motion
 - Cut off to zero for particles too far away from each other
- ◆ Also collision forces
 - If particles penetrate container, push them out

cs533d-winter-2005 17

More advanced physics

- ◆ Rigid bodies
 - Include orientation and rotation
- ◆ Constrained dynamics
 - E.g. jointed skeletons
- ◆ Solid mechanics
 - Generalize springs to multiple dimensions
- ◆ Fluid mechanics
 - Pressure and viscosity forces

cs533d-winter-2005 18