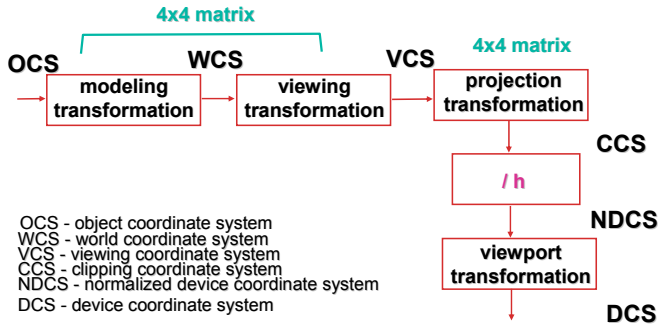




Projective Rendering Pipeline



Lines and Curves

Explicit

line $y = mx + b$
 $y = \frac{(y_2 - y_1)}{(x_2 - x_1)}(x - x_1) + y_1$

circle $y = \pm\sqrt{r^2 - x^2}$

plane $z = E_x + F_y + G$

sphere $z = \pm\sqrt{r^2 - x^2 - y^2}$



Lines and Curves

Parametric

line $x(t) = x_0 + t(x_1 - x_0)$
 $y(t) = y_0 + t(y_1 - y_0)$
 $t \in [0, 1]$
 $P(t) = P_0 + t(P_1 - P_0)$
 $P(t) = (1-t)P_0 + tP_1$

circle $x(\theta) = r \cos(\theta)$
 $y(\theta) = r \sin(\theta)$

plane $P(s, t) = P_0 + s(P_1 - P_0) + t(P_2 - P_0)$

*not unique!
 e.g. could replace
 t by 5t*



Lines and Curves

Implicit

line $F(x, y) = (x - x_0)dy - (y - y_0)dx$
 $F(x, y) = 0$ (x,y) is on line
 $F(x, y) > 0$ (x,y) is below line
 $F(x, y) < 0$ (x,y) is above line

circle $F(x, y) = x^2 + y^2 - r^2$
 $F(x, y) = 0$ (x,y) is on circle
 $F(x, y) > 0$ (x,y) is outside
 $F(x, y) < 0$ (x,y) is inside

*not unique:
 e.g. could replace
 F(x,y) by k·F(x,y)*

*plane $F(x,y,z) = Ax + By + Cz + D$
 $= \langle A, B, C \rangle \cdot P + D$
 $= \vec{N} \cdot P + D$
 normal to plane*



Polygons

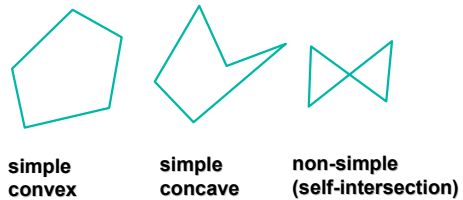
Interactive graphics uses Polygons

- Can represent any surface with arbitrary accuracy
 - Splines, mathematical functions, ...
- simple, regular rendering algorithms
 - embed well in hardware



Polygons

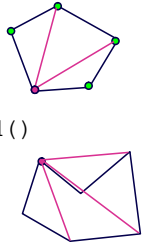
Basic Types





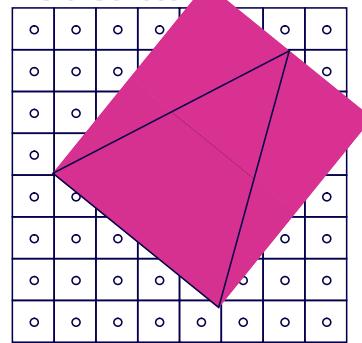
From Polygons to Triangles

- why? triangles are planar and convex
- simple convex polygons
 - break into triangles, trivial
 - glBegin(GL_POLYGON) ... glEnd()
- concave or non-simple polygons
 - break into triangles, more effort
 - gluNewTess(), gluTessCallback(), ...

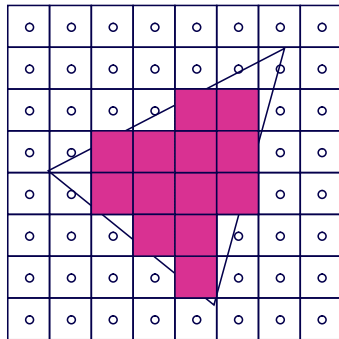


What is Scan Conversion? (a.k.a. Rasterization)

screen is discrete



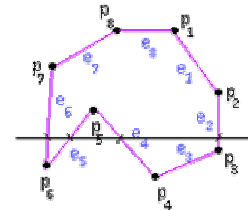
one possible scan conversion



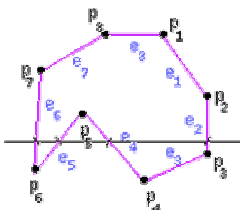
Scan Conversion

A General Algorithm

- intersect each scanline with all edges
- sort intersections in x
- calculate parity to determine in/out
- fill the 'in' pixels



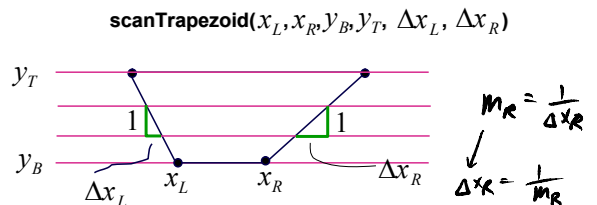
- works for arbitrary polygons
- efficiency improvement:
 - exploit row-to-row coherence using "edge table"



Edge Walking

past graphics hardware

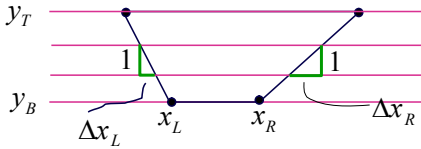
- exploit continuous L and R edges on trapezoid



```

for (y=yB; y<=yT; y++) {
  for (x=xL; x<=xR; x++)
    setPixel(x,y);
  xL += DxL;
  xR += DxR;
}

```

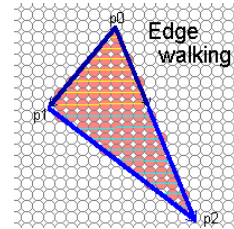
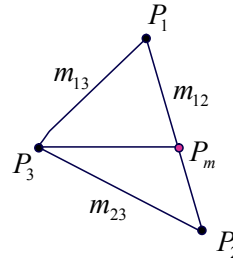


Edge Walking Triangles

- split triangles into two regions with continuous left and right edges

$$\text{scanTrapezoid}(x_3, x_m, y_3, y_b, \frac{1}{m_{13}}, \frac{1}{m_{12}})$$

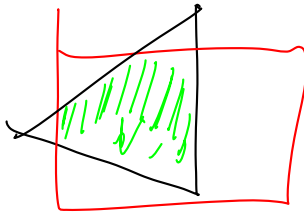
$$\text{scanTrapezoid}(x_2, x_2, y_2, y_3, \frac{1}{m_{23}}, \frac{1}{m_{12}})$$



Edge Walking Triangles

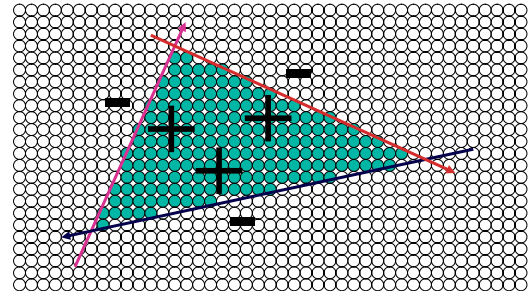
Issues

- many applications have small triangles
 - setup cost is non-trivial
- clipping triangles produces non-triangles

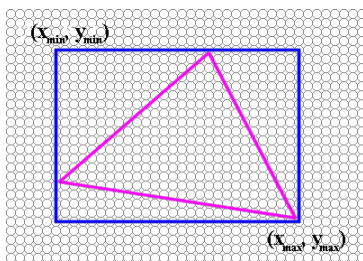


Modern Rasterization

Define a triangle as follows:

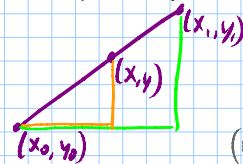


Using Edge Equations



→ clip to window by clipping the bbox to the window

Implicit Equation for a 2D line



general form: $Ax + By + C = 0$

$$\frac{y_1 - y_0}{x_1 - x_0} = \frac{y - y_0}{x - x_0}$$

$$(y_1 - y_0)(x - x_0) = (y - y_0)(x_1 - x_0)$$

$$x(y_1 - y_0) - x_0(y_1 - y_0) + y(y_0 - x_1) - y_0(x_0 - x_1) = 0$$

$$x(y_1 - y_0) + y(y_0 - x_1) - x_0 y_1 + x_0 y_0 - x_1 y_0 + x_1 y_0 = 0$$

$$\Rightarrow F(x, y) = Ax + By + C$$

$$A = y_1 - y_0$$

$$B = y_0 - x_1$$

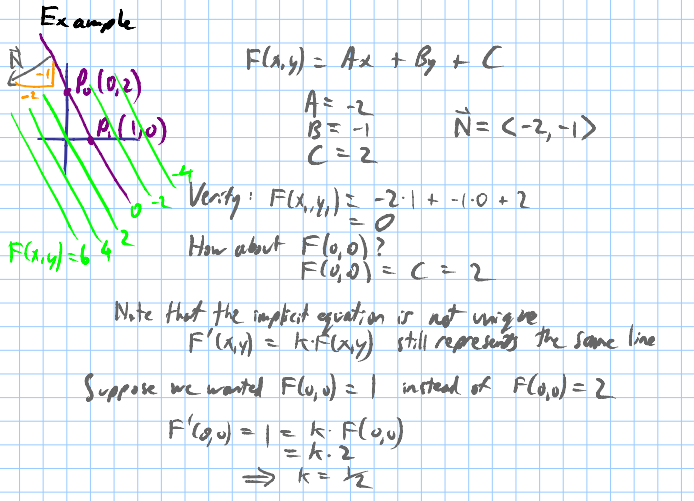
$$C = x_0 y_0 - x_0 y_1$$

Note: can think of $\langle A, B \rangle$ as a normal \vec{N} to the line

Edge Equations

- So...we can find edge equation from two verts.
- Given P_0, P_1, P_2 , what are our three edges?
How do we make sure the half-spaces defined by the edge equations all share the same sign on the interior of the triangle?
- A: Be consistent (Ex: $[P_0 P_1], [P_1 P_2], [P_2 P_0]$)
How do we make sure that sign is positive?
- A: Test, and flip if needed (~~$A = -A, B = -B, C = -C$~~)
Consistently walking clockwise around the Δ and using $F(x,y)$ as developed previously will result in the Δ interior being positive for all 3 line equations

Example



$F(x,y) = Ax + By + C$

$A = -2$
 $B = -1$
 $C = 2$

$\vec{N} = \langle -2, -1 \rangle$

Verify: $F(x,y) = -2 \cdot 1 + -1 \cdot 0 + 2 = 0$

How about $F(0,0)$?
 $F(0,0) = C = 2$

Note that the implicit equation is not unique
 $F'(x,y) = k \cdot F(x,y)$ still represents the same line

Suppose we wanted $F(0,0) = 1$ instead of $F(0,0) = 2$

$F'(0,0) = 1 = k \cdot F(0,0)$
 $= k \cdot 2$
 $\Rightarrow k = \frac{1}{2}$

Edge Equations: Code



Basic structure of code:

- Setup: compute edge equations, bounding box
- (Outer loop) For each scanline in bounding box...
- (Inner loop) ...check each pixel on scanline, evaluating edge equations and drawing the pixel if all three are positive

Edge Equations: Code



```
findBoundingBox(&xmin, &xmax, &ymin, &ymax);
setupEdges (&a0, &b0, &c0, &a1, &b1, &c1, &a2, &b2, &c2);

for (int y = yMin; y <= yMax; y++) {
    for (int x = xMin; x <= xMax; x++) {
        float e0 = a0*x + b0*y + c0;
        float e1 = a1*x + b1*y + c1;
        float e2 = a2*x + b2*y + c2;
        if (e0 > 0 && e1 > 0 && e2 > 0)
            Image[x][y] = TriangleColor;
    }
}
```

Edge Equations: Code



```
// more efficient inner loop
for (int y = yMin; y <= yMax; y++) {
    float e0 = a0*xMin + b0*y + c0;
    float e1 = a1*xMin + b1*y + c1;
    float e2 = a2*xMin + b2*y + c2;
    for (int x = xMin; x <= xMax; x++) {
        if (e0 > 0 && e1 > 0 && e2 > 0)
            Image[x][y] = TriangleColor;
        e0 += a0; e1 += a1; e2 += a2;
    }
}
```

Can pull much of this out of loop for further efficiency

Triangle Rasterization Issues



Exactly which pixels should be lit?

A: Those pixels inside the triangle edges

What about pixels exactly on the edge?

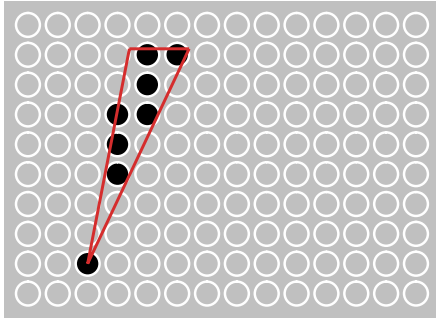
- Draw them: order of triangles matters (it shouldn't)
- Don't draw them: gaps possible between triangles

We need a consistent (if arbitrary) rule

- Example: draw pixels on left or top edge, but not on right or bottom edge

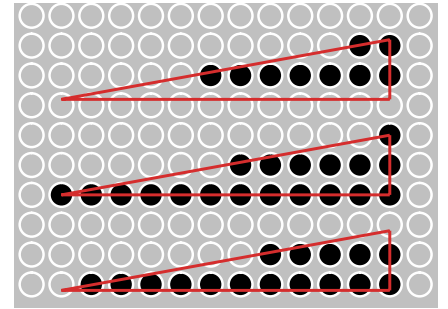
Triangle Rasterization Issues

Sliver



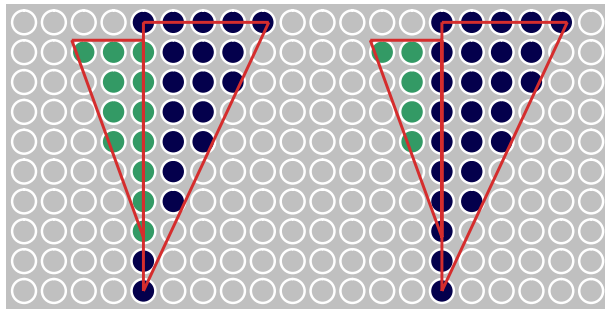
Triangle Rasterization Issues

Moving Slivers



Triangle Rasterization Issues

Shared Edge Ordering

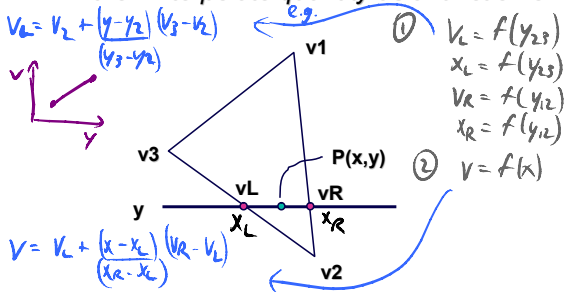


Interpolation During Scan Conversion

- interpolate between vertices: (demo)
 - z
 - r, g, b colour components
 - u, v texture coordinates
 - N_x, N_y, N_z surface normals
- three equivalent methods (for triangles)
 - bilinear interpolation
 - plane equation
 - barycentric coordinates

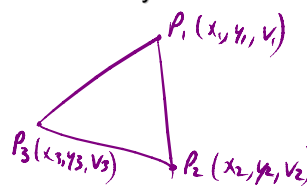
1. Bilinear Interpolation

- interpolate quantity along LH and RH edges, as a function of y
 - then interpolate quantity as a function of x



2. Plane Equation

- $v = Ax + By + C$



Plane eq'n: $Ax + By + Cz + D = 0$
 $\Rightarrow Ax + By + Cv + 0 = 0$
 $V = -\frac{A}{C}x - \frac{B}{C}y - \frac{D}{C}$

Computing A, B, C:
 $\vec{N} = \langle A, B, C \rangle = (P_2 - P_1) \times (P_3 - P_1)$
 $N \cdot P + D = 0$
 $D = -N \cdot P$
 choose any P:
 $D = -N \cdot P_1$

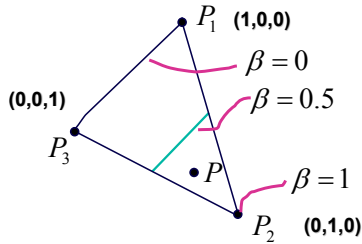


3. Barycentric Coordinates

•weighted combination of vertices

$$\begin{cases} P = \alpha \cdot P_1 + \beta \cdot P_2 + \gamma \cdot P_3 \\ \alpha + \beta + \gamma = 1 \\ 0 \leq \alpha, \beta, \gamma \leq 1 \end{cases}$$

"convex combination of points"



Barycentric Coordinates

- once computed, use to interpolate any # of parameters from their vertex values

$$\begin{aligned} z &= \alpha \cdot z_1 + \beta \cdot z_2 + \gamma \cdot z_3 \\ r &= \alpha \cdot r_1 + \beta \cdot r_2 + \gamma \cdot r_3 \\ g &= \alpha \cdot g_1 + \beta \cdot g_2 + \gamma \cdot g_3 \end{aligned}$$

etc.

Computing Barycentric Coordinates

$$P = \alpha P_1 + \beta P_2 + \gamma P_3$$

① Compute implicit line eqn for P_1P_2
 $F(x,y) = Ax + By + C$

② Compute $F'(x,y) = kF(x,y)$ such that
 $F'(P_1) = 1$
 $1 = k \cdot F(P_1)$
 $\Rightarrow k = 1/F(P_1)$

$$\alpha = F'(x,y) = A'x + B'y + C'$$

where $A' = kA$
 $B' = kB$
 $C' = kC$

Similarly for β, γ

Note that we could use α, β, γ for the in/out test for scan conversion.