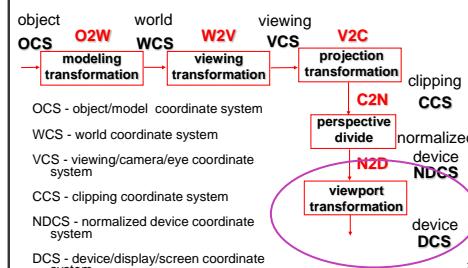


Tamara Munzner

Viewing 4

<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2016>

Projective Rendering Pipeline



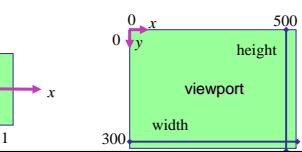
NDC to Device Transformation

- map from NDC to pixel coordinates on display
 - NDC range is $x = -1 \dots 1$, $y = -1 \dots 1$, $z = -1 \dots 1$
 - typical display range: $x = 0 \dots 500$, $y = 0 \dots 300$
 - maximum is size of actual screen
 - z range max and default is $(0, 1)$, use later for visibility
 - gl.viewport(0,0,w,h);
gl.depthRange(0,1); // depth = 1 by default

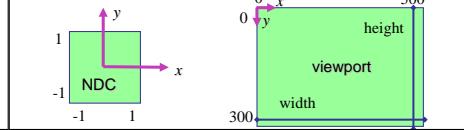
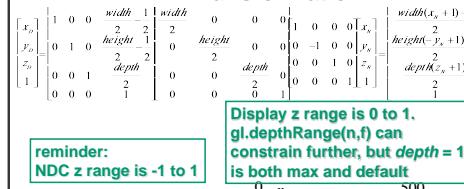


N2D Transformation

- general formulation
- reflect in y for upper vs. lower left origin
- scale by width, height, depth
- translate by width/2, height/2, depth/2
 - FCG includes additional translation for pixel centers at $(.5, .5)$ instead of $(0,0)$

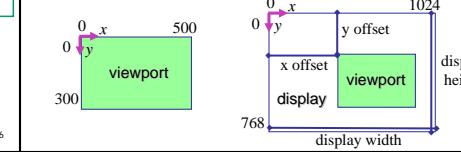


N2D Transformation



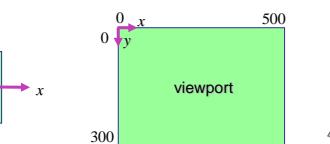
Device vs. Screen Coordinates

- viewport/window location wrt actual display not available within GL
 - usually don't care
 - use relative information when handling mouse events, not absolute coordinates
 - could get actual display height/width, window offsets from OS
- loose use of terms: device, display, window, screen...



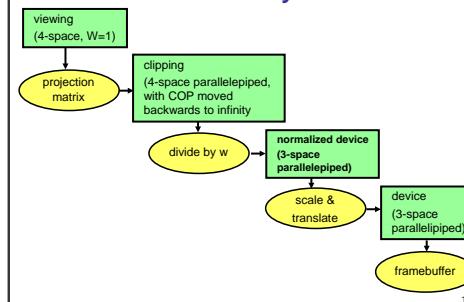
Origin Location

- yet more (possibly confusing) conventions
 - GL origin: lower left
 - most window systems origin: upper left
- then must reflect in y
- when interpreting mouse position, have to flip your y coordinates



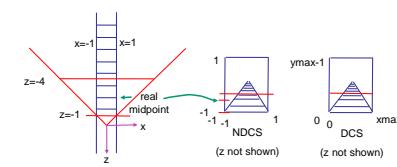
Questions?

Coordinate Systems



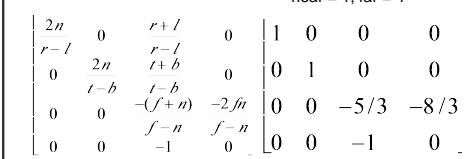
Perspective Example

tracks in VCS:
left $x=-1$, $y=-1$
right $x=1$, $y=-1$
bottom $x=-1$, $y=1$
top $x=1$, $y=1$
near = 1, far = 4

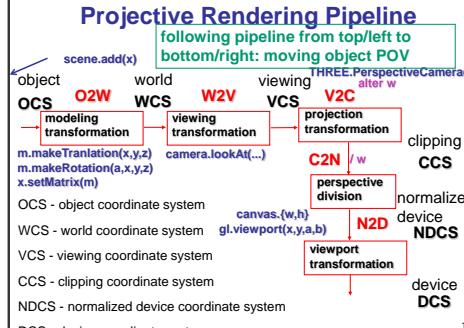
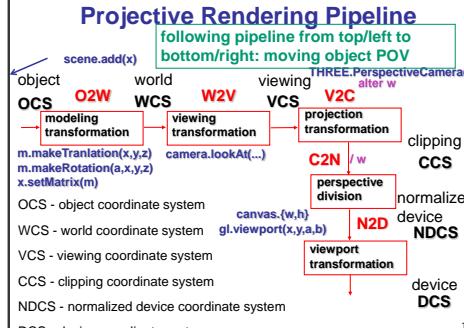


Perspective Example

view volume
• left = -1, right = 1
• bot = -1, top = 1
• near = 1, far = 4



Perspective Example



OpenGL Example

go back from end of pipeline to beginning: coord frame POV!

object OCS	modeling transformation	world WCS	viewing V2V	clipping CCS
m.makeTranslation(x,y,z)	m.makeRotation(a,x,y,z)	camera.lookAt(...)		
x.setMatrix(m)				

CCS: gl.viewport(0,0,w,h);

VCS: THREE.PerspectiveCamera(view angle, aspect, near, far)

WCS: u_xformMatrix = Identity();
gl.uniformMatrix4fv(u_xformMatrix, false, xformMatrix);

OCS1: torsoGeometry.applyMatrix(u_xformMatrix);
var torso = new THREE.Mesh(torsoGeometry, normalMaterial);
scene.add(torso);

Coord Sys: Frame vs Point

read down: transforming points between coordinate frames, from frame A to frame B	read up: transforming points, up from frame B coords to frame A coords
OpenGL command order	
DCS display gl.viewport(x,y,a,b)	N2D
D2N NDCS normalized device	V2N
N2V THREE.PerspectiveCamera(...)	W2V
V2W viewing camera.lookAt(...)	W2O
WCS world m.makeRotationX(...)	O2W
OCS object scene.add(object)	

pipeline interpretation

Questions?