

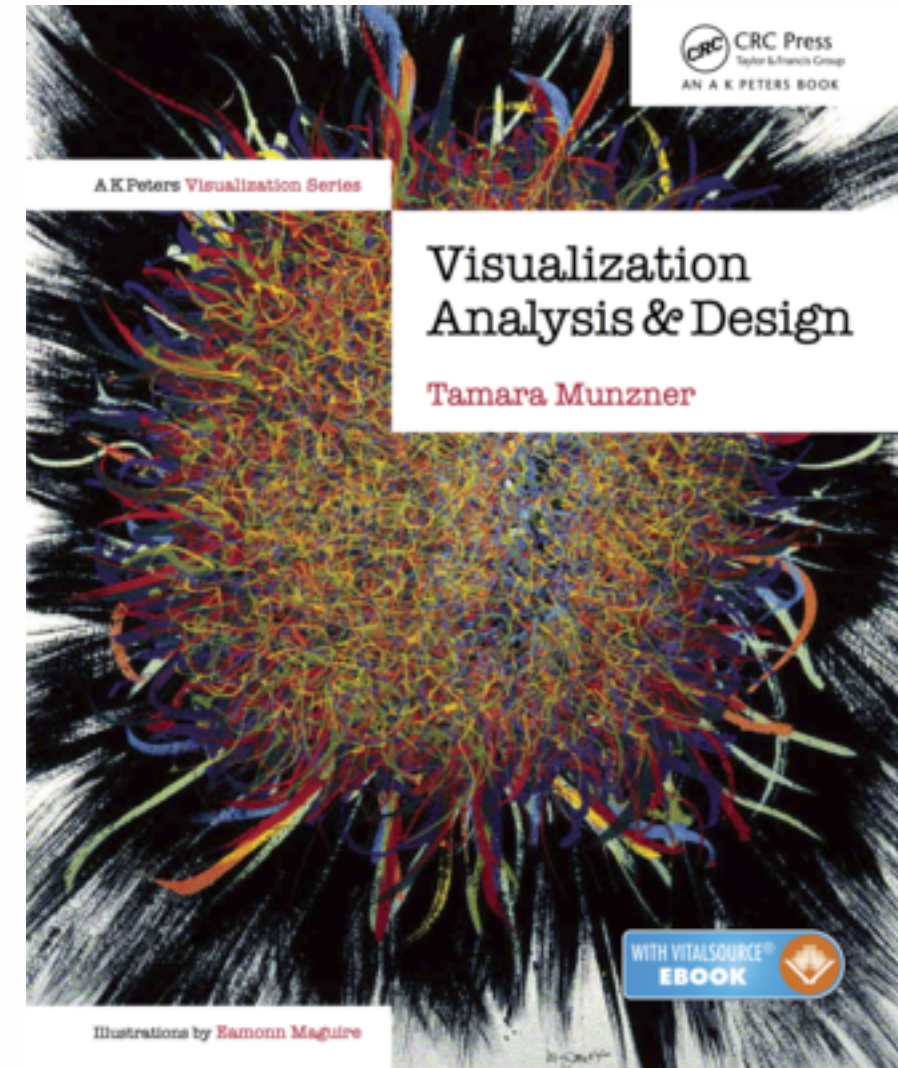
# Visualization

**Tamara Munzner**

Department of Computer Science  
University of British Columbia

*UBC 314 Computer Graphics, Jan-Apr 2016*

**<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2016>**



# Defining visualization (vis)

**Computer-based visualization systems provide visual representations of datasets designed to help people carry out tasks more effectively.**

Why?...

# Why have a human in the loop?

**Computer-based visualization systems provide visual representations of datasets designed to help people carry out tasks more effectively.**

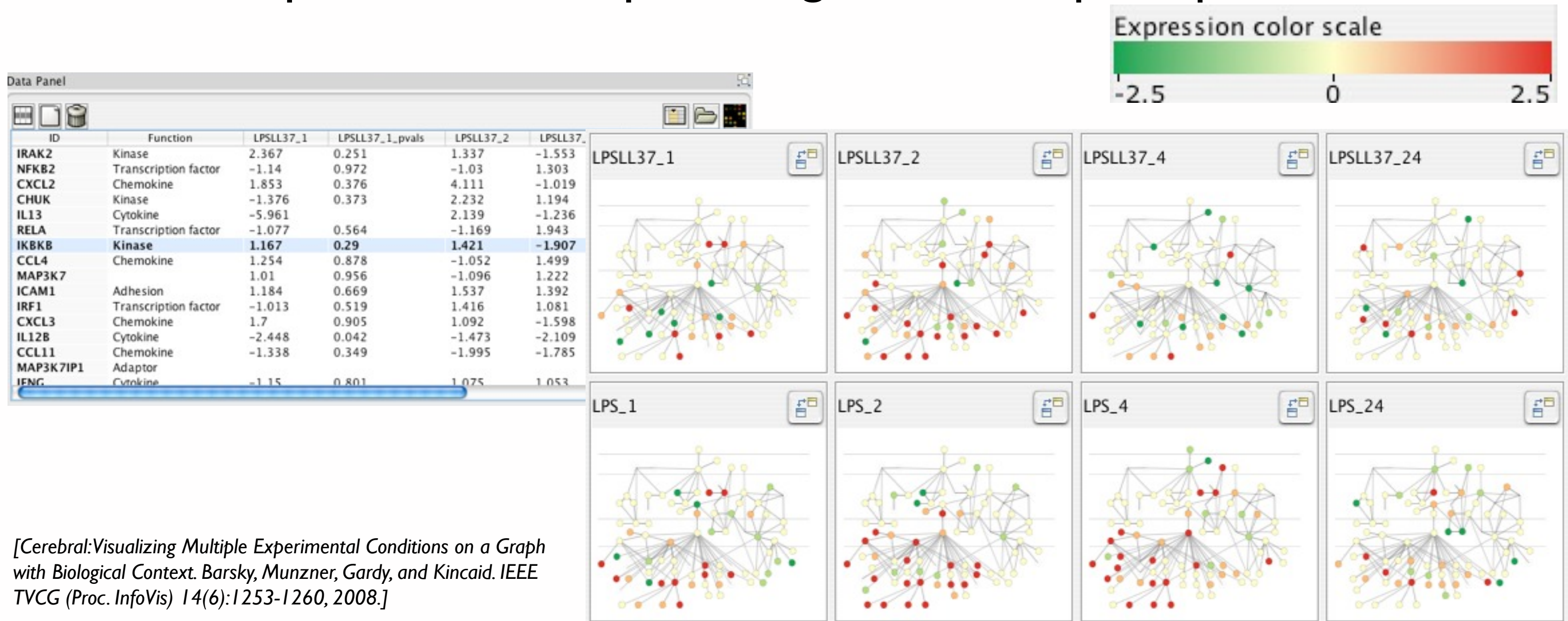
**Visualization is suitable when there is a need to augment human capabilities rather than replace people with computational decision-making methods.**

- don't need vis when fully automatic solution exists and is trusted
- many analysis problems ill-specified
  - don't know exactly what questions to ask in advance
- possibilities
  - long-term use for end users (e.g. exploratory analysis of scientific data)
  - presentation of known results
  - stepping stone to better understanding of requirements before developing models
  - help developers of automatic solution refine/debug, determine parameters
  - help end users of automatic solutions verify, build trust

# Why use an external representation?

Computer-based visualization systems provide **visual representations** of datasets designed to help people carry out tasks more effectively.

- external representation: replace cognition with perception



[Cerebral: Visualizing Multiple Experimental Conditions on a Graph with Biological Context. Barsky, Munzner, Gardy, and Kincaid. IEEE TVCG (Proc. InfoVis) 14(6):1253-1260, 2008.]

# Why represent all the data?

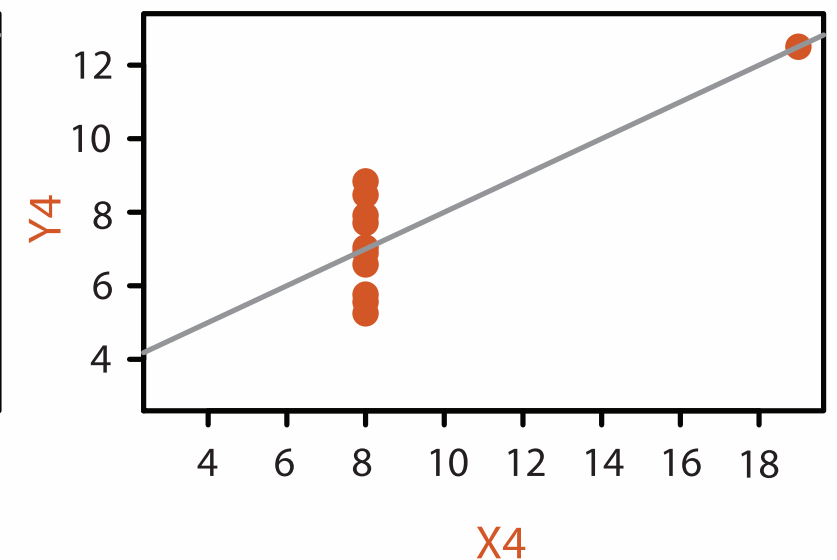
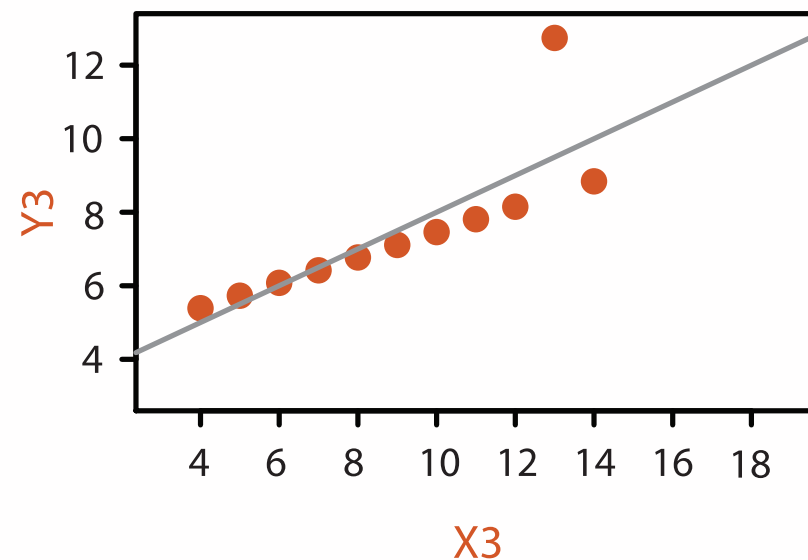
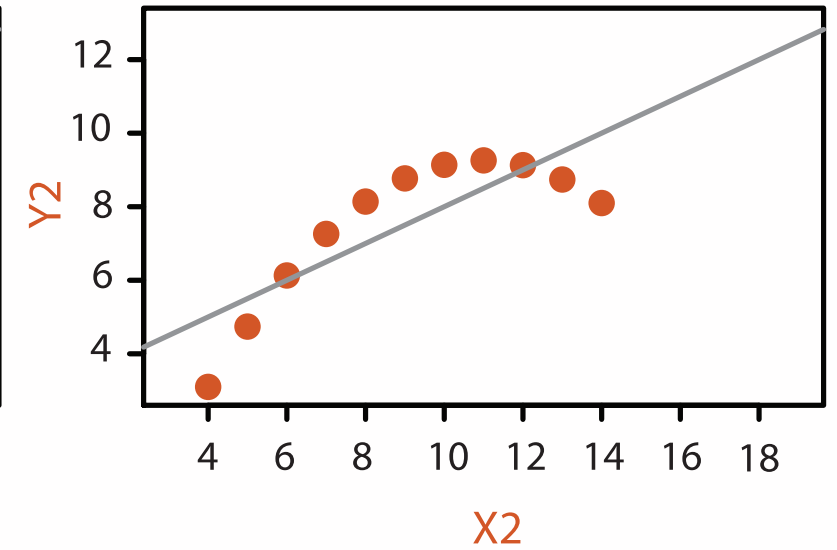
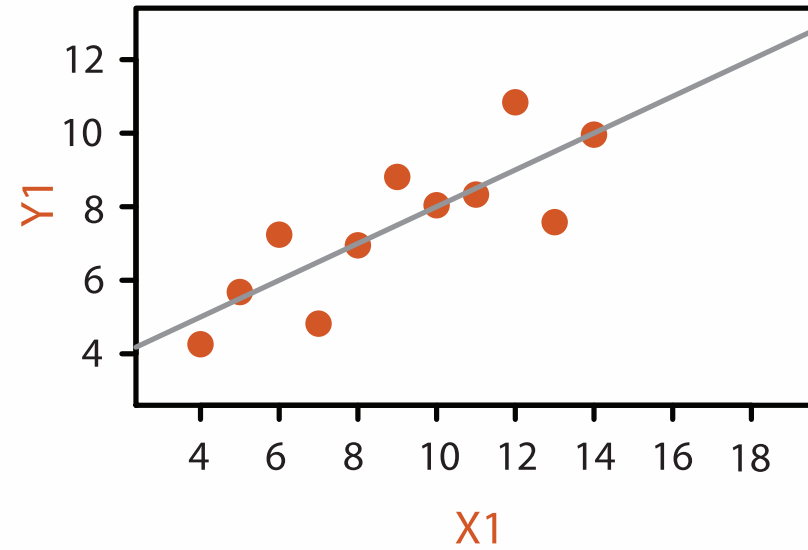
Computer-based visualization systems provide visual representations of datasets designed to help people carry out tasks more effectively.

- summaries lose information, details matter
  - confirm expected and find unexpected patterns
  - assess validity of statistical model

## Anscombe's Quartet

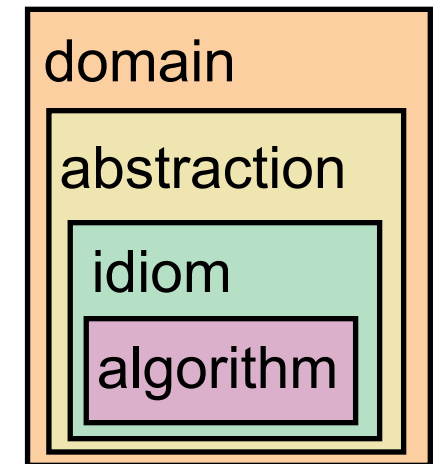
### Identical statistics

x mean	9
x variance	10
y mean	8
y variance	4
x/y correlation	1

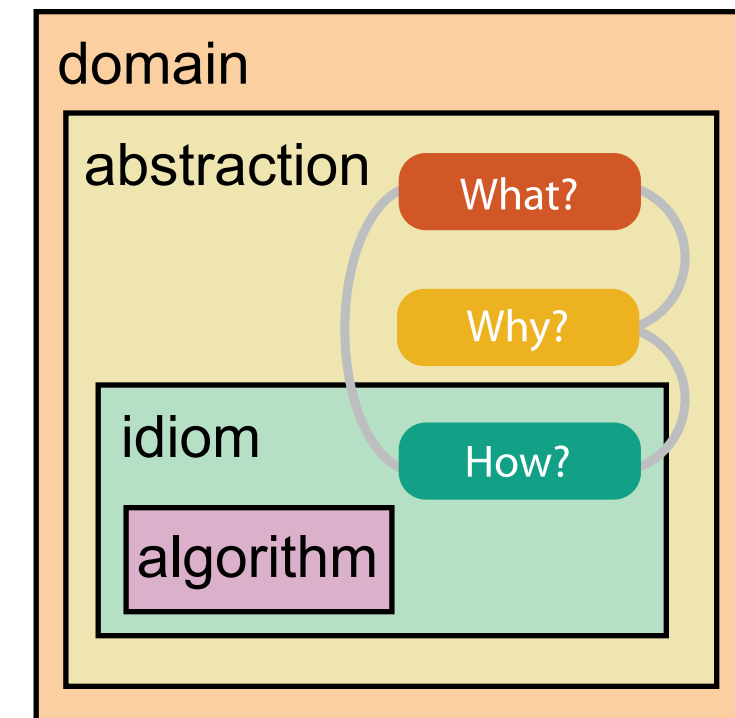


# Analysis framework: Four levels, three questions

- *domain* situation
  - who are the target users?
- *abstraction*
  - translate from specifics of domain to vocabulary of vis
- **what** is shown? **data abstraction**
  - often don't just draw what you're given: transform to new form
- **why** is the user looking at it? **task abstraction**
- *idiom*
  - **how** is it shown?
    - **visual encoding idiom**: how to draw
    - **interaction idiom**: how to manipulate
- *algorithm*
  - efficient computation



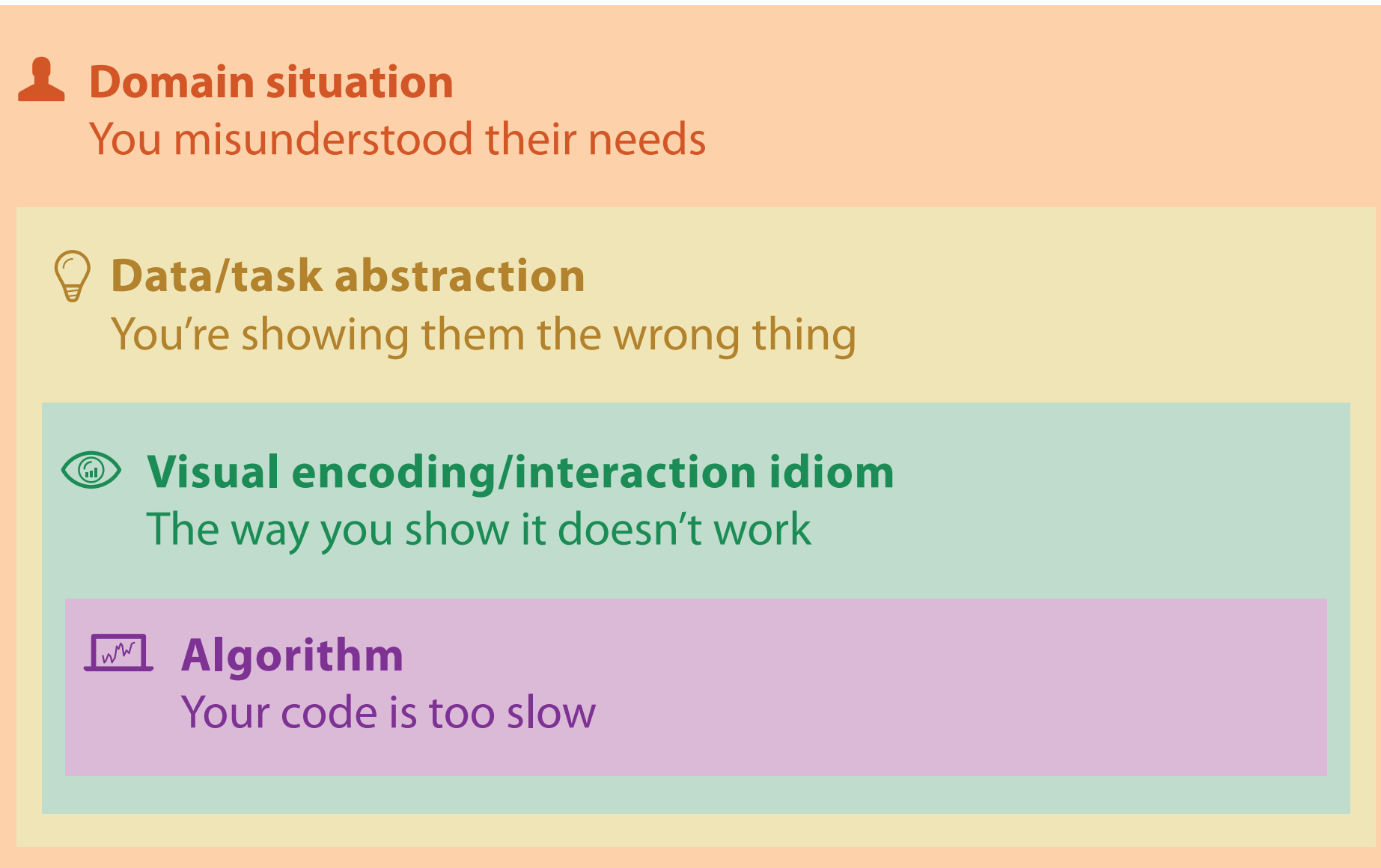
[A Nested Model of Visualization Design and Validation.  
Munzner. *IEEE TVCG* 15(6):921-928, 2009 (Proc. InfoVis 2009).]



[A Multi-Level Typology of Abstract Visualization Tasks  
Brehmer and Munzner. *IEEE TVCG* 19(12):2376-2385, 2013 (Proc. InfoVis 2013).]

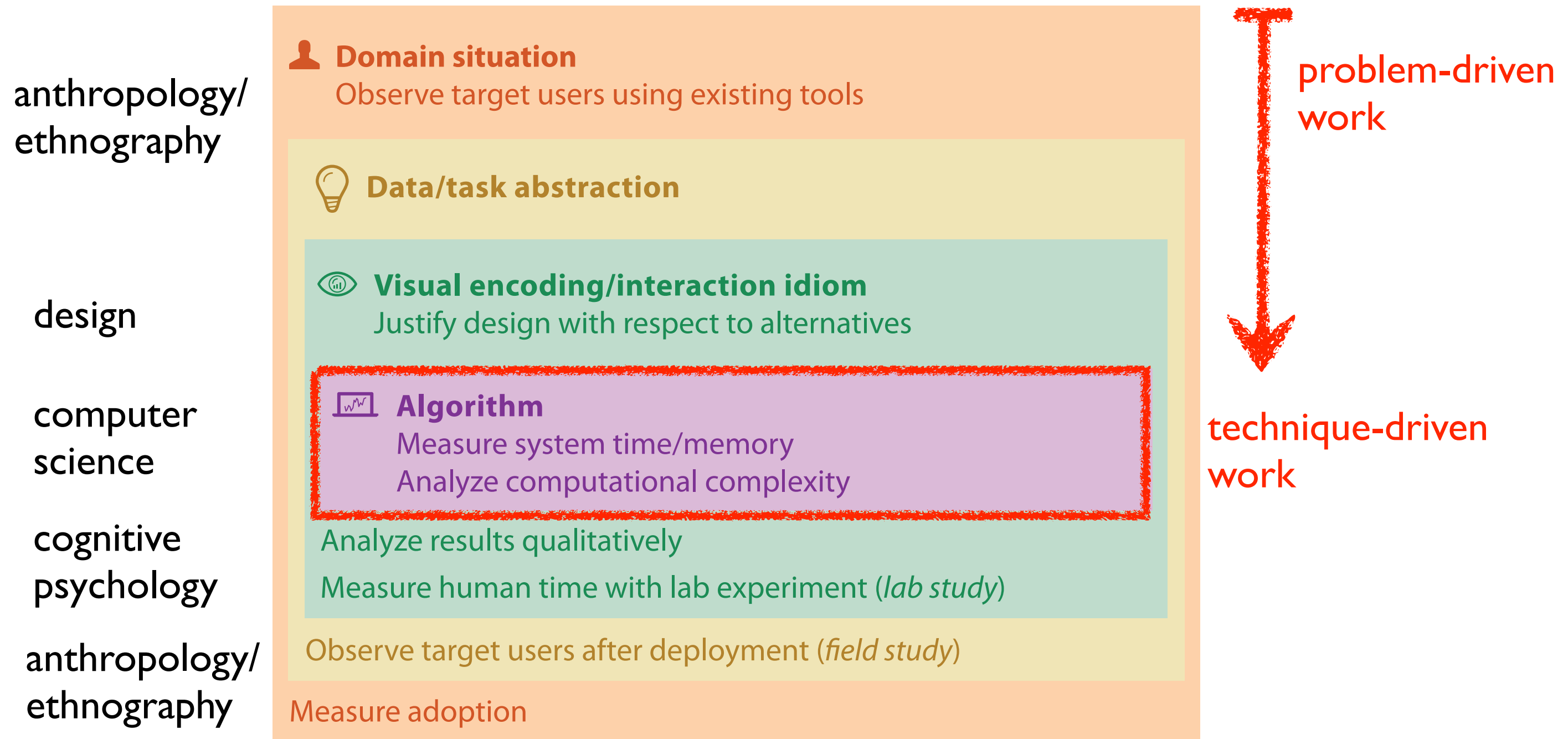
# Why is validation difficult?

- different ways to get it wrong at each level

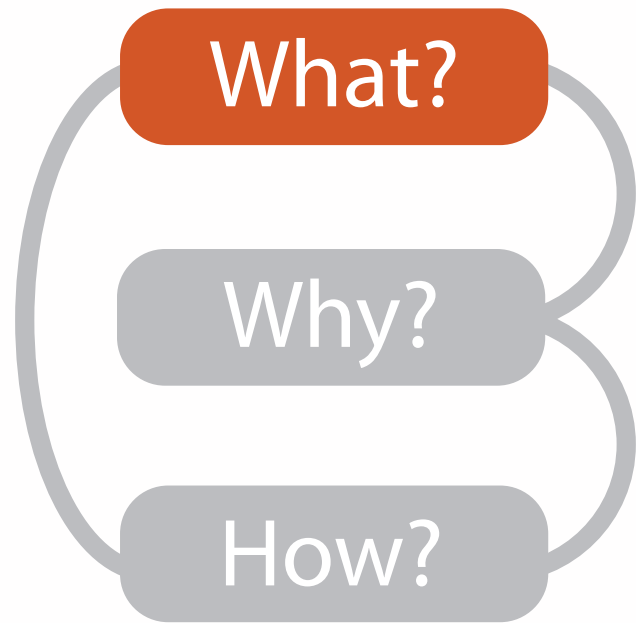


# Why is validation difficult?

- solution: use methods from different fields at each level







# What?

## Datasets

## Attributes

### → Data Types

- Items
- Attributes
- Links
- Positions
- Grids

### → Data and Dataset Types

Tables	Networks & Trees	Fields	Geometry	Clusters, Sets, Lists
Items	Items (nodes)	Grids	Items	Items
Attributes	Links	Positions	Positions	
	Attributes	Attributes		

### → Attribute Types

- Categorical



- Ordered

- Ordinal

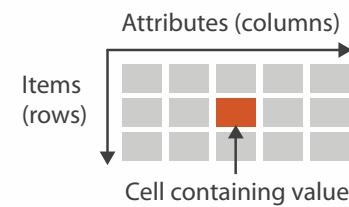


- Quantitative

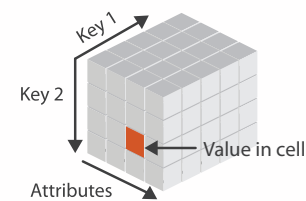


### → Dataset Types

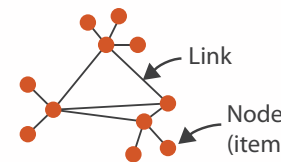
- Tables



- Multidimensional Table



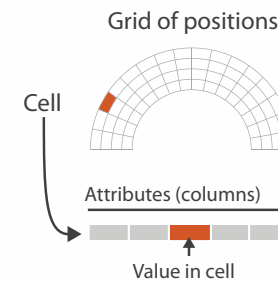
- Networks



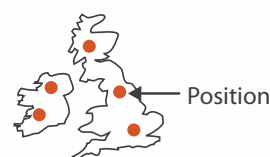
- Trees



- Fields (Continuous)



- Geometry (Spatial)



### → Ordering Direction

- Sequential



- Diverging



- Cyclic



### → Dataset Availability

- Static



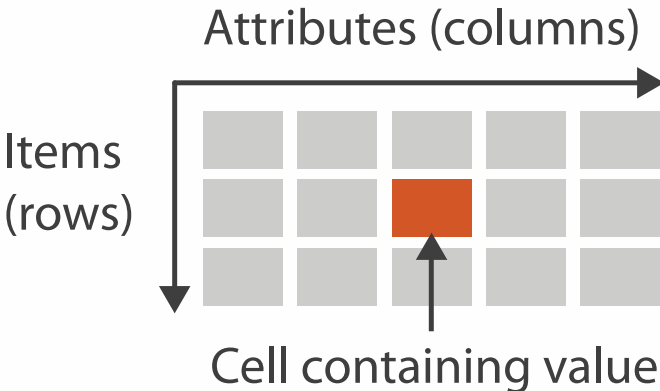
- Dynamic



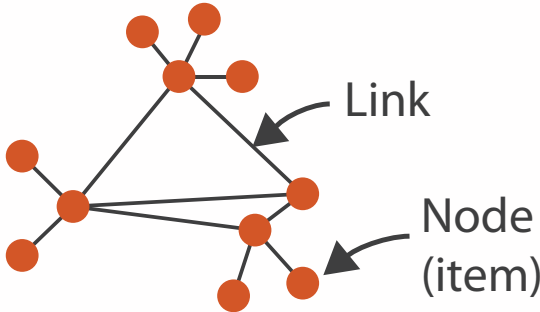
# Types: Datasets and data

## → Dataset Types

→ Tables

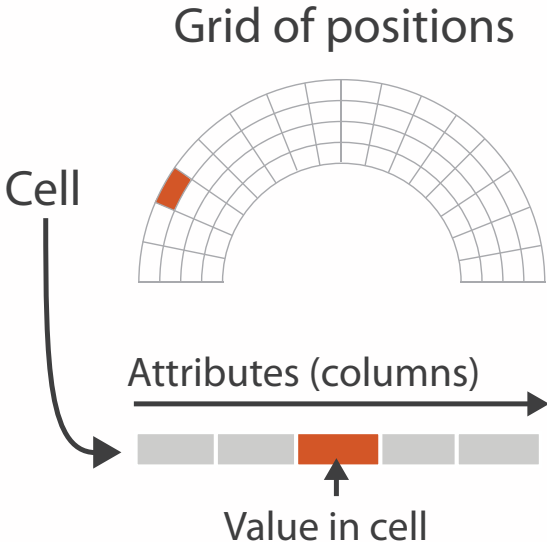


→ Networks

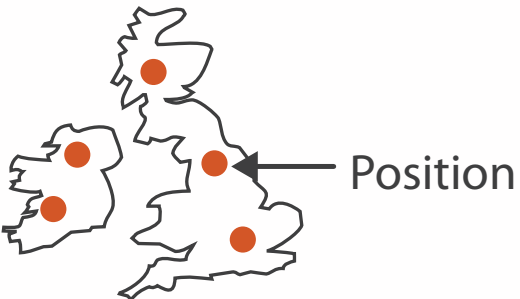


→ Spatial

→ Fields (Continuous)



→ Geometry (Spatial)



## → Attribute Types

→ Categorical

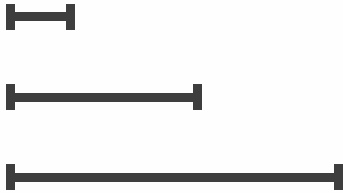


→ Ordered

→ Ordinal



→ Quantitative









# Why?




## 👉 Actions

## 🎯 Targets




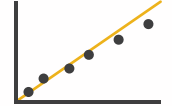
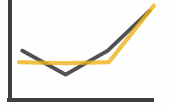
➔ **Analyze**

- ➔ Consume
  - ➔ Discover 
  - ➔ Present 
  - ➔ Enjoy 
- ➔ Produce
  - ➔ Annotate 
  - ➔ Record 
  - ➔ Derive 





➔ **All Data**

- ➔ Trends 
- ➔ Outliers 
- ➔ Features 


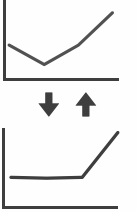

➔ **Attributes**

- ➔ One
  - ➔ Distribution 
  - ➔ Extremes 
- ➔ Many
  - ➔ Dependency 
  - ➔ Correlation 
  - ➔ Similarity 

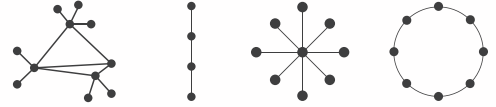

➔ **Search**

	Target known	Target unknown
Location known	 <i>Lookup</i>	 <i>Browse</i>
Location unknown	 <i>Locate</i>	 <i>Explore</i>


➔ **Query**

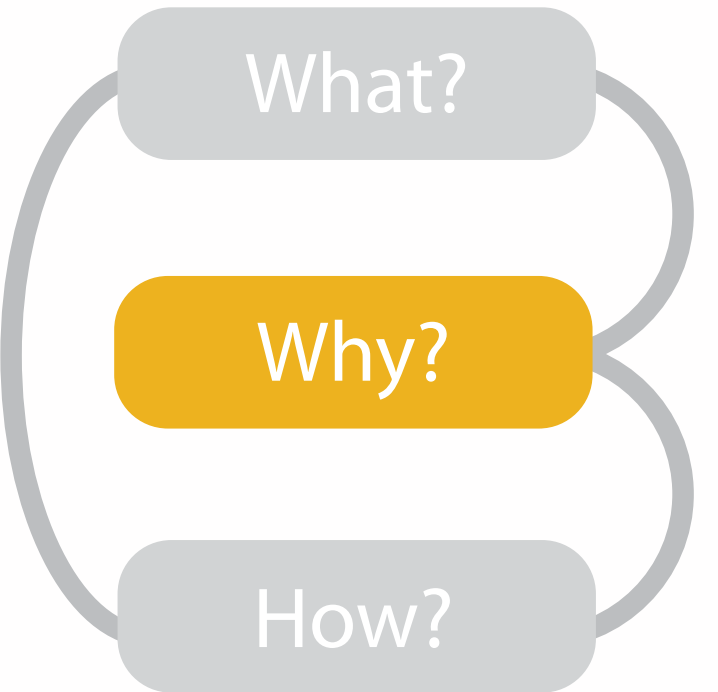
- ➔ Identify 
- ➔ Compare 
- ➔ Summarize 

➔ **Network Data**

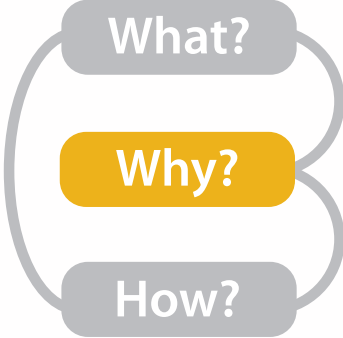
- ➔ Topology 
- ➔ Paths 

➔ **Spatial Data**

- ➔ Shape 



- {action, target} pairs
  - discover distribution
  - compare trends
  - locate outliers
  - browse topology



# Actions: Analyze

- consume
  - discover vs present
    - classic split
    - aka explore vs explain
  - enjoy
- produce
  - newcomer
  - aka casual, social
- produce
  - annotate, record
  - derive
    - crucial design choice

## → Analyze

### → Consume

→ Discover



→ Present

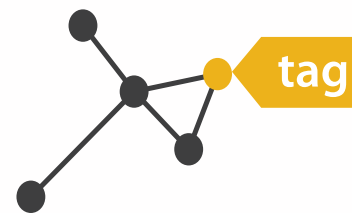


→ Enjoy



### → Produce

→ Annotate



→ Record

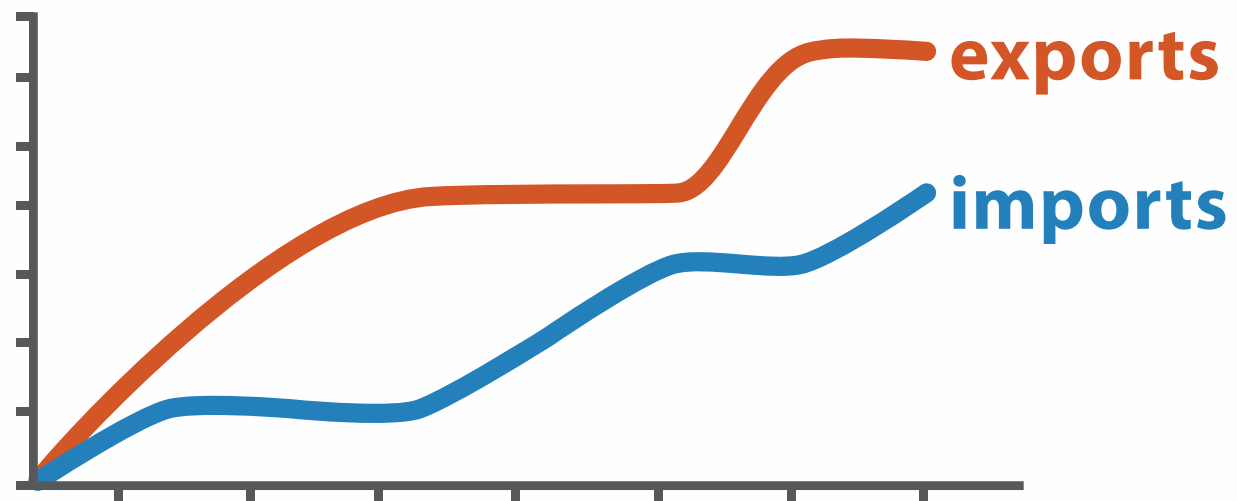


→ Derive

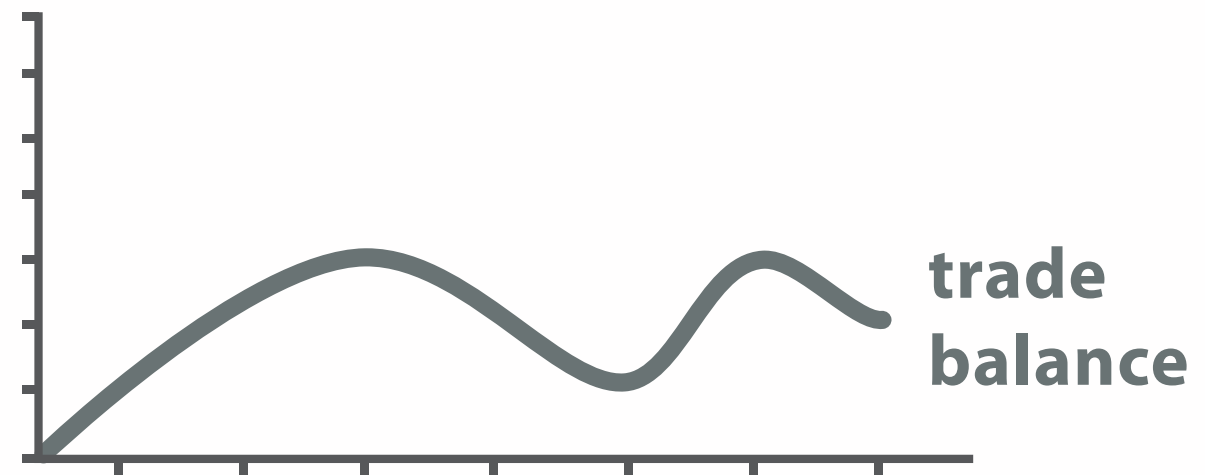


# Derive

- don't just draw what you're given!
  - decide what the right thing to show is
  - create it with a series of transformations from the original dataset
  - draw that
- one of the four major strategies for handling complexity



Original Data



$$\text{trade balance} = \text{exports} - \text{imports}$$

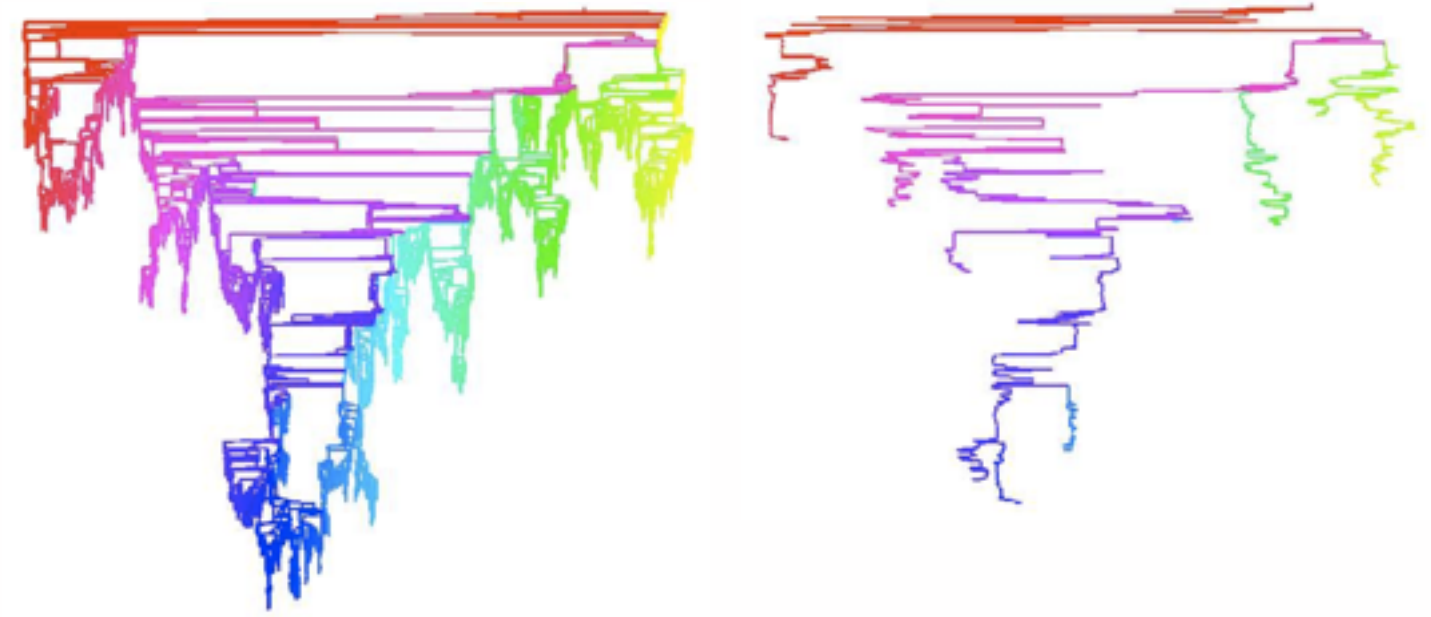
Derived Data

# Analysis example: Derive one attribute

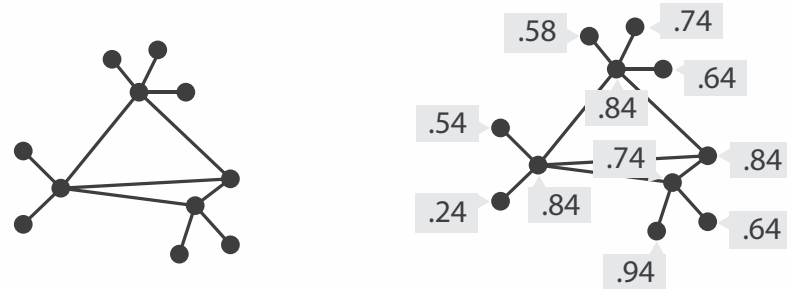
- Strahler number

- centrality metric for trees/networks
- derived quantitative attribute
- draw top 5K of 500K for good skeleton

*[Using Strahler numbers for real time visual exploration of huge graphs. Auber. Proc. Intl. Conf. Computer Vision and Graphics, pp. 56–69, 2002.]*



## Task 1



**In**  
Tree

➔

**Out**  
Quantitative  
attribute on nodes

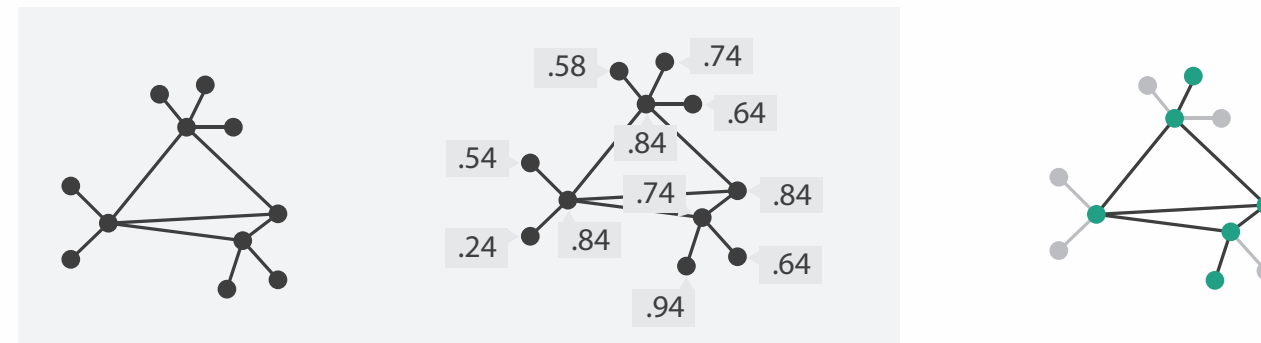
### What?

- ➔ In Tree
- ➔ Out Quantitative attribute on nodes

### Why?

- ➔ Derive

## Task 2



**In**  
Tree

+

**In**  
Quantitative  
attribute on nodes

➔

**Out**  
Filtered Tree  
Removed  
unimportant parts

### What?

- ➔ In Tree
- ➔ In Quantitative attribute on nodes
- ➔ Out Filtered Tree

### Why?

- ➔ Summarize
- ➔ Topology





### How?

- ➔ Reduce
- ➔ Filter

# Actions: Search, query

- what does user know?
  - target, location
- how much of the data matters?
  - one, some, all

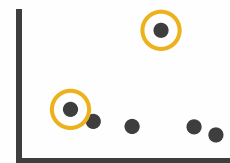
## ➔ Search

	Target known	Target unknown
Location known	 <i>Lookup</i>	 <i>Browse</i>
Location unknown	 <i>Locate</i>	 <i>Explore</i>

- independent choices for each of these three levels
  - analyze, search, query
  - mix and match

## ➔ Query

➔ Identify



➔ Compare



↓ ↑



➔ Summarize



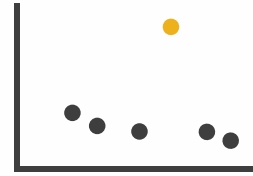
# Targets

## → All Data

→ Trends



→ Outliers



→ Features



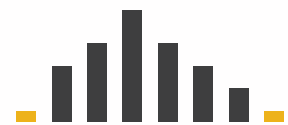
## → Attributes

→ One

→ *Distribution*

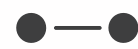


→ *Extremes*

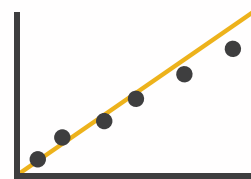


→ Many

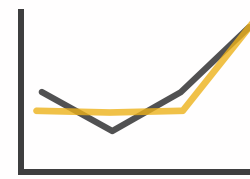
→ *Dependency*



→ *Correlation*

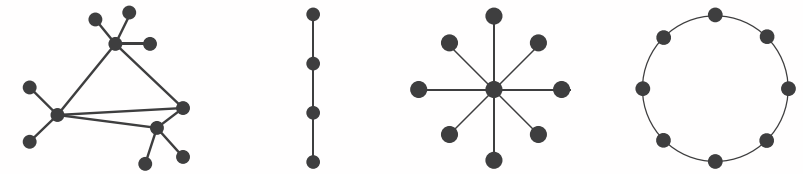


→ *Similarity*

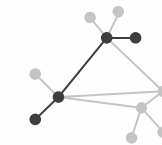


## → Network Data

→ Topology

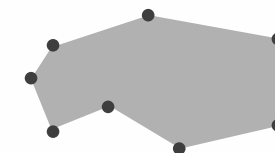


→ *Paths*



## → Spatial Data

→ Shape





# How?

## Encode

### → Arrange

→ Express



→ Separate



→ Order



→ Align



→ Use



### → Map

from **categorical** and **ordered** attributes

→ Color

→ Hue



→ Saturation



→ Luminance



→ Size, Angle, Curvature, ...



→ Shape



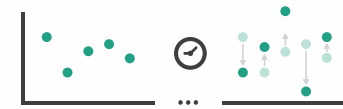
→ Motion

*Direction, Rate, Frequency, ...*



## Manipulate

### → Change



### → Select



### → Navigate

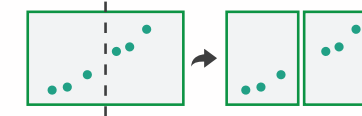


## Facet

### → Juxtapose



### → Partition



### → Superimpose



## Reduce

### → Filter



### → Aggregate



### → Embed



What?

Why?

How?

# How to encode: Arrange space, map channels

## Encode

### ➔ Arrange

➔ Express



➔ Order



➔ Use



➔ Separate



➔ Align



### ➔ Map

from **categorical** and **ordered** attributes

➔ Color

➔ Hue



➔ Saturation



➔ Luminance



➔ Size, Angle, Curvature, ...

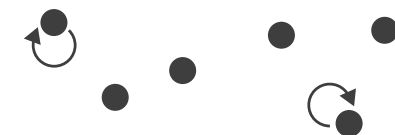


➔ Shape



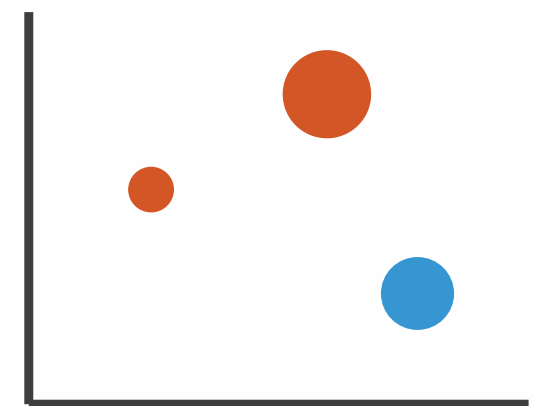
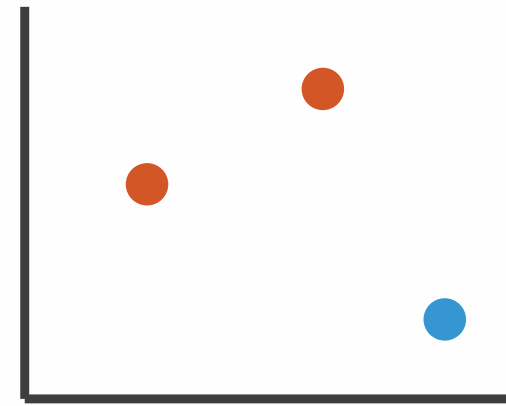
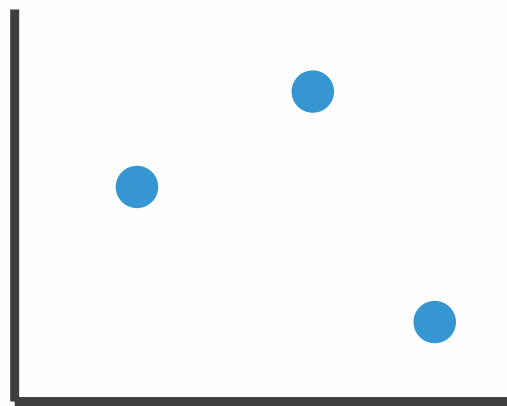
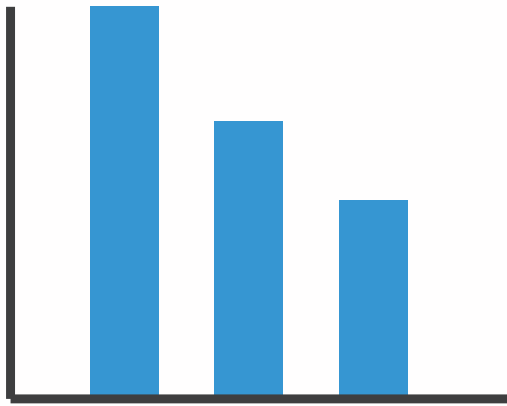
➔ Motion

*Direction, Rate, Frequency, ...*



# Encoding visually

- analyze idiom structure



# Definitions: Marks and channels

- marks

– geometric primitives

→ Points



→ Lines



→ Areas



- channels

– control appearance of marks

→ Position

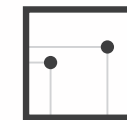
→ Horizontal



→ Vertical



→ Both



→ Color



→ Shape



→ Tilt



→ Size

→ Length



→ Area

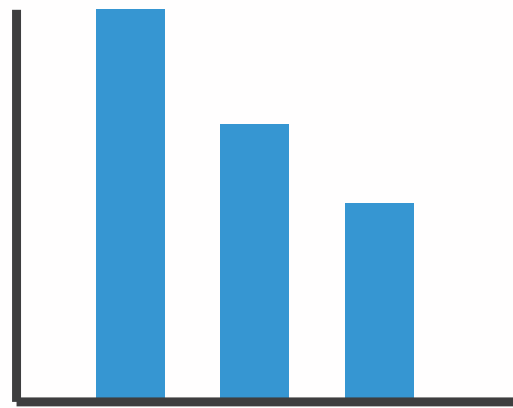


→ Volume



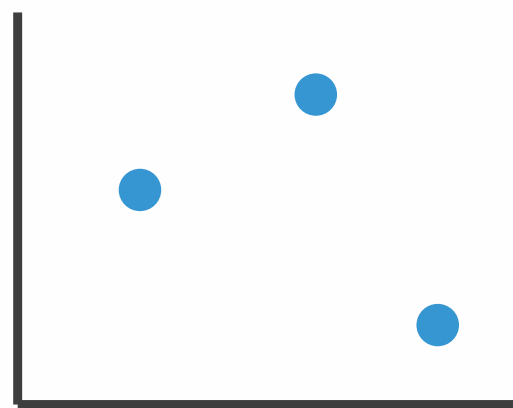
# Encoding visually with marks and channels

- analyze idiom structure
  - as combination of marks and channels



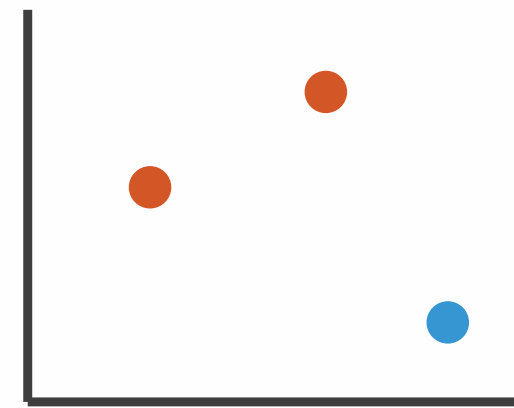
1:  
vertical position

mark: line



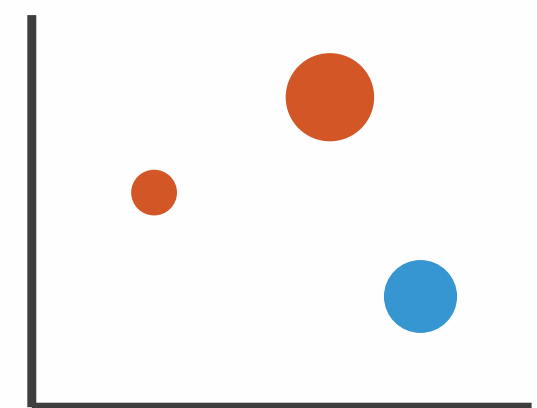
2:  
vertical position  
horizontal position

mark: point



3:  
vertical position  
horizontal position  
color hue

mark: point



4:  
vertical position  
horizontal position  
color hue  
size (area)

mark: point

# Channels

Position on common scale



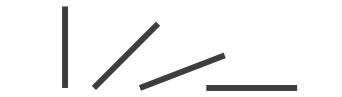
Position on unaligned scale



Length (1D size)



Tilt/angle



Area (2D size)



Depth (3D position)



Color luminance



Color saturation



Curvature



Volume (3D size)



Same

Spatial region



Color hue



Motion



Shape



# Channels: Matching Types

## ➔ Magnitude Channels: Ordered Attributes

Position on common scale 

Position on unaligned scale 

Length (1D size) 

Tilt/angle 

Area (2D size) 

Depth (3D position) 

Color luminance 

Color saturation 

Curvature 

Volume (3D size) 

Same  
Same

## ➔ Identity Channels: Categorical Attributes

Spatial region 

Color hue 

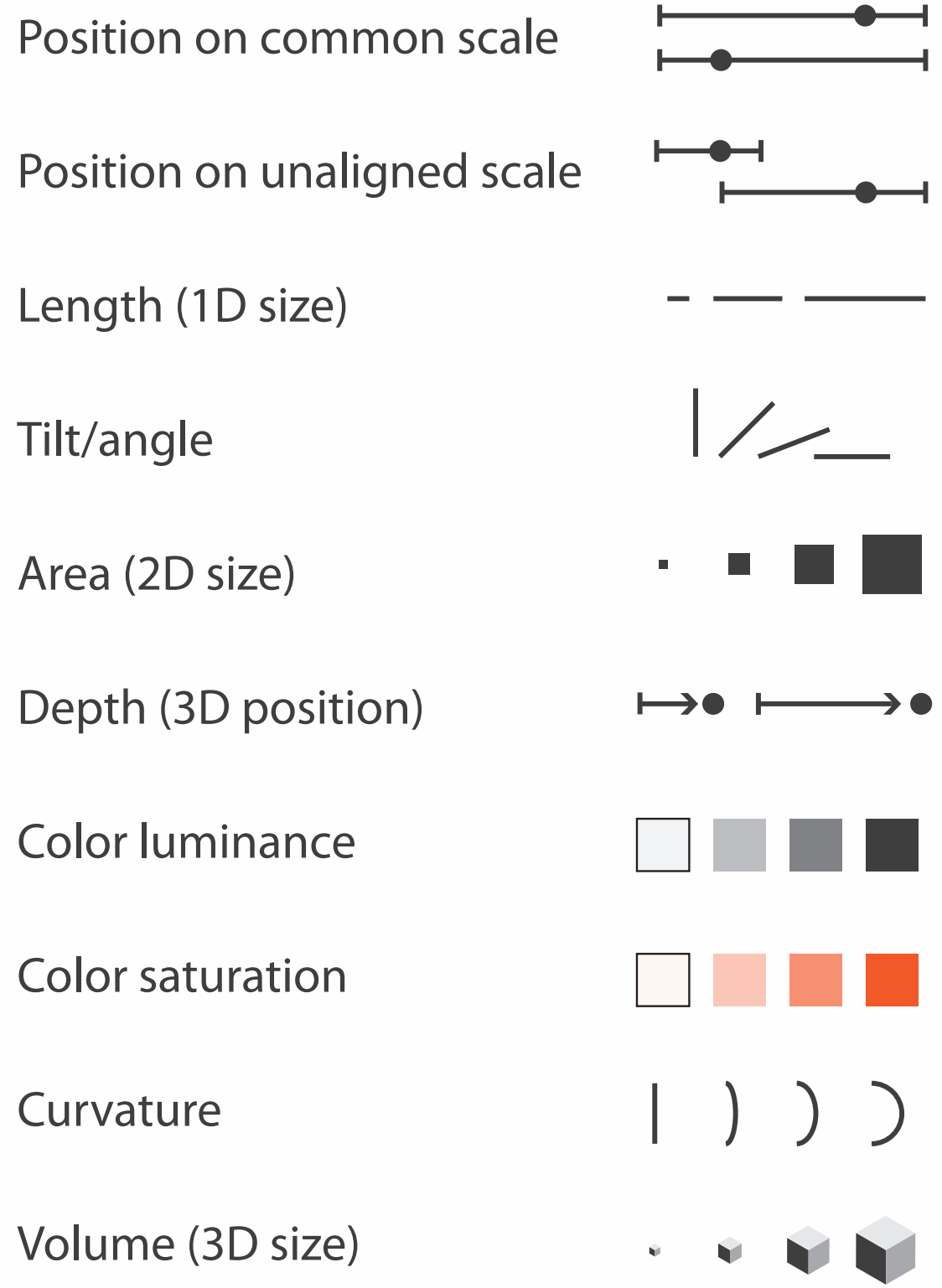
Motion 

Shape 

- **expressiveness principle**
  - match channel and data characteristics

# Channels: Rankings

## ➔ Magnitude Channels: Ordered Attributes



## ➔ Identity Channels: Categorical Attributes



Best

Effectiveness

Least

Same

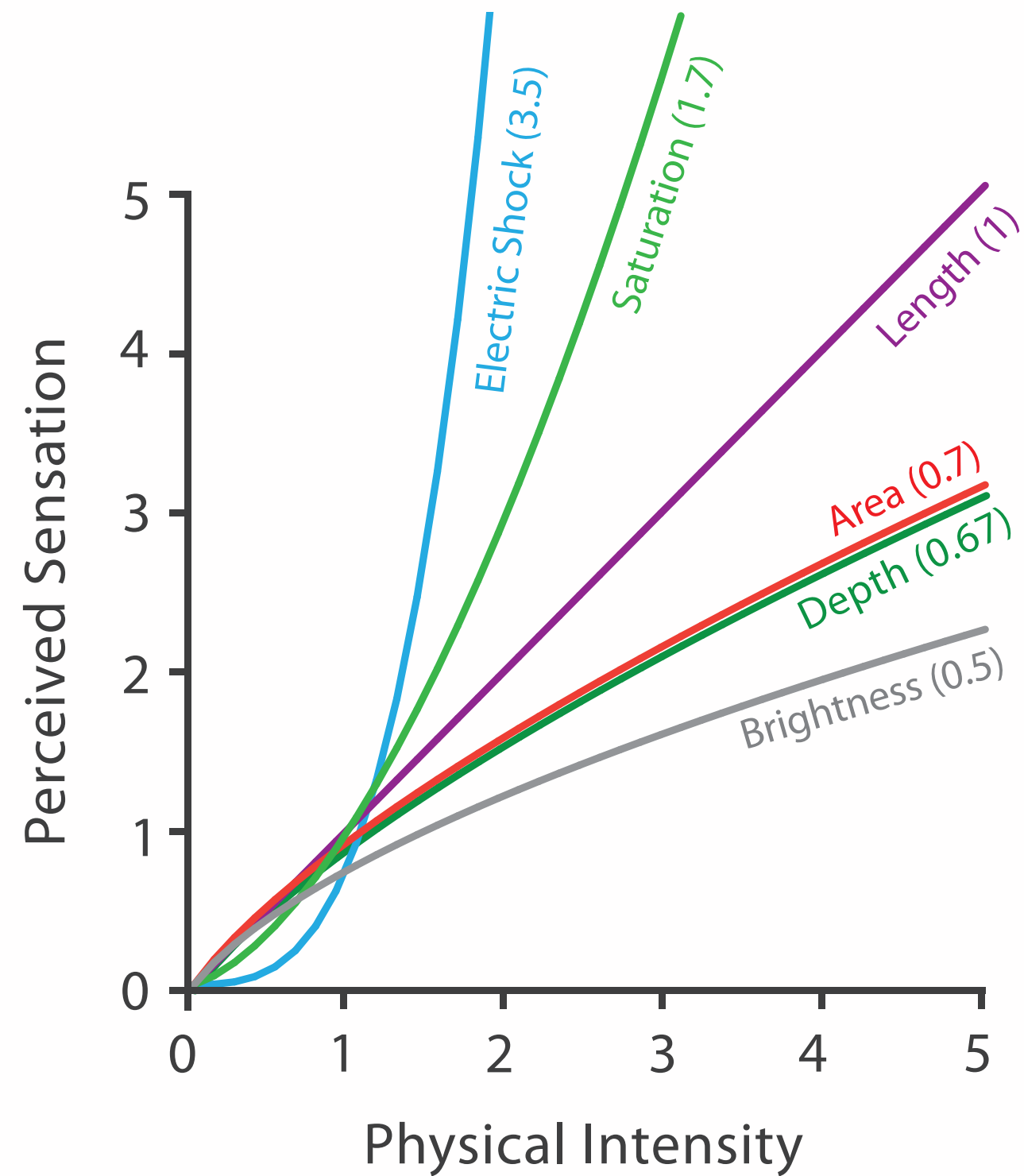
Same

- **expressiveness principle**
  - match channel and data characteristics
- **effectiveness principle**
  - encode most important attributes with highest ranked channels



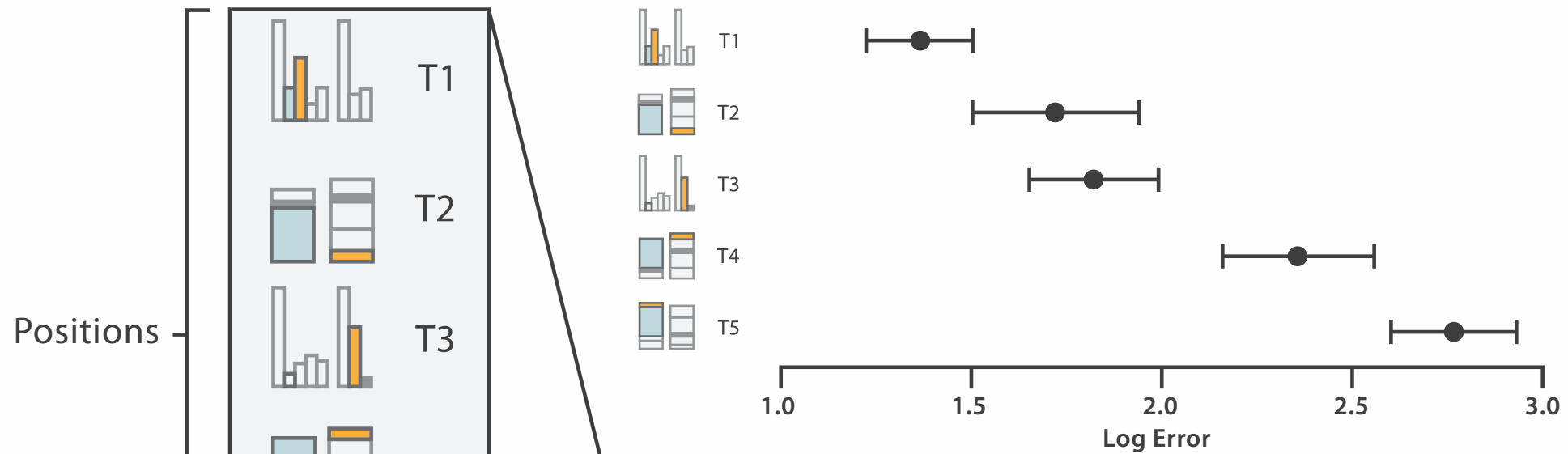
# Accuracy: Fundamental Theory

Steven's Psychophysical Power Law:  $S = I^N$

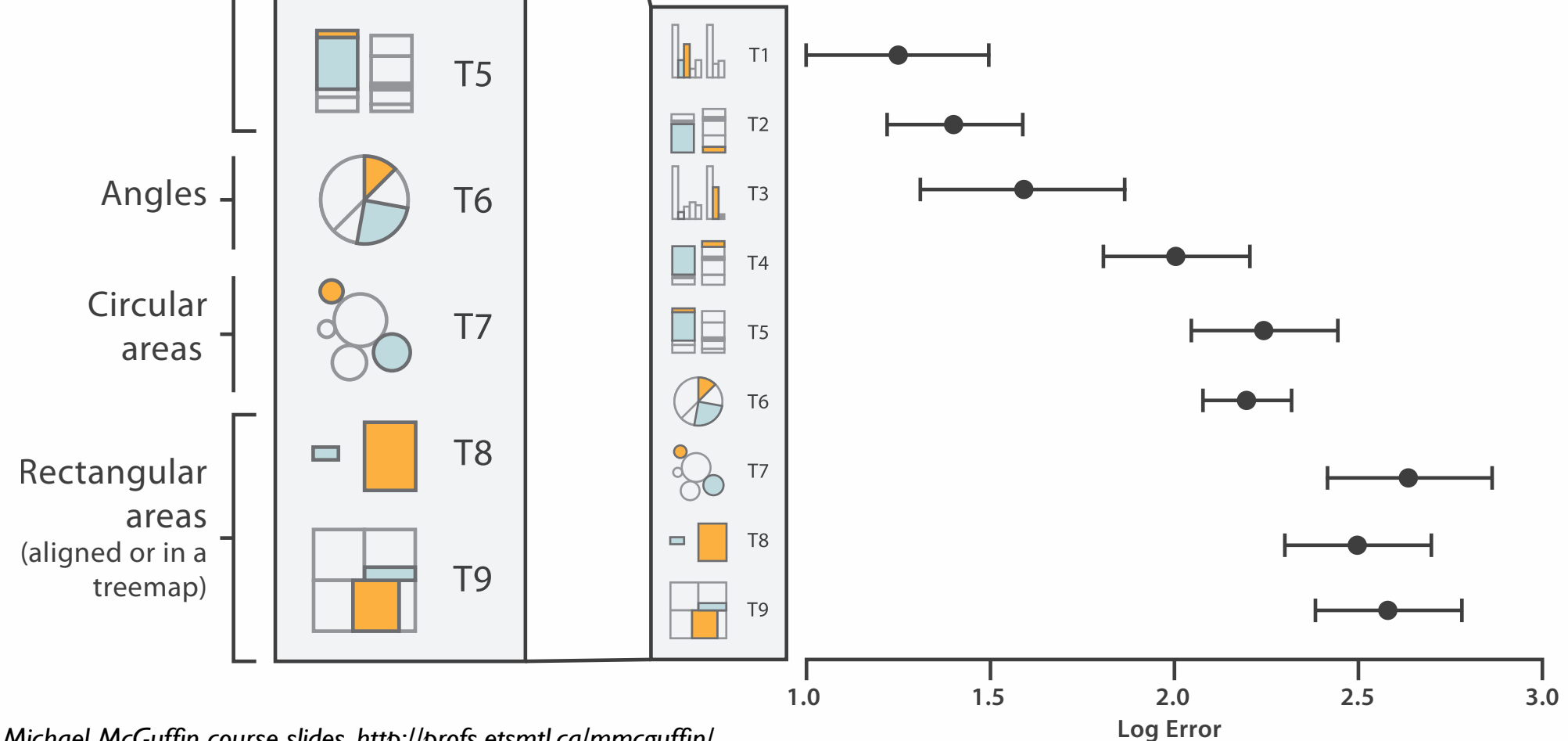


# Accuracy: Vis experiments

Cleveland & McGill's Results



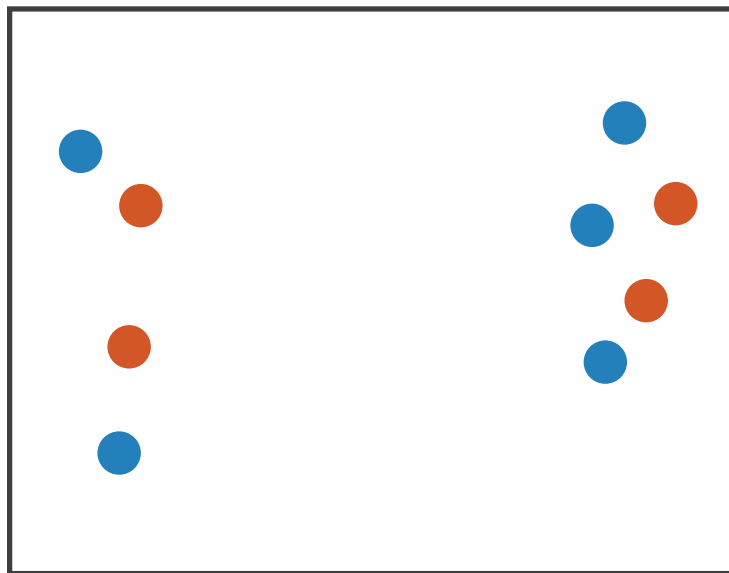
Crowdsourced Results



*[Crowdsourcing Graphical Perception: Using Mechanical Turk to Assess Visualization Design. Heer and Bostock. Proc ACM Conf. Human Factors in Computing Systems (CHI) 2010, p. 203–212.]*

# Separability vs. Integrality

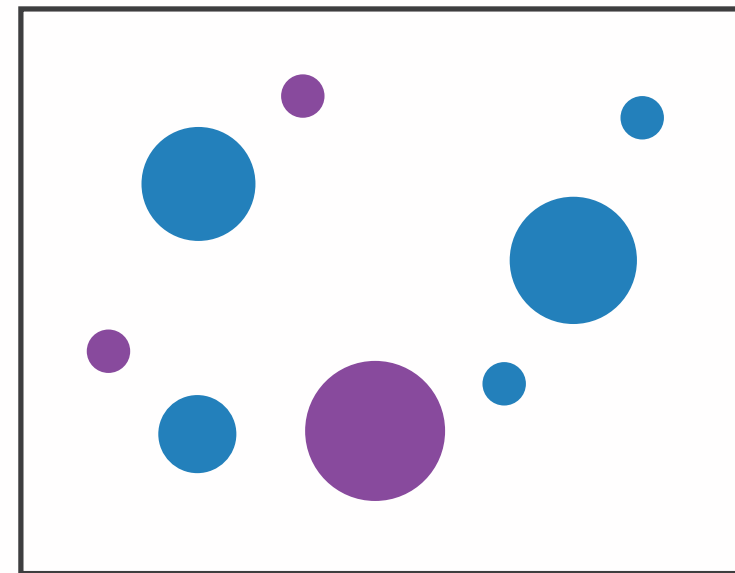
Position  
+ Hue (Color)



Fully separable

2 groups each

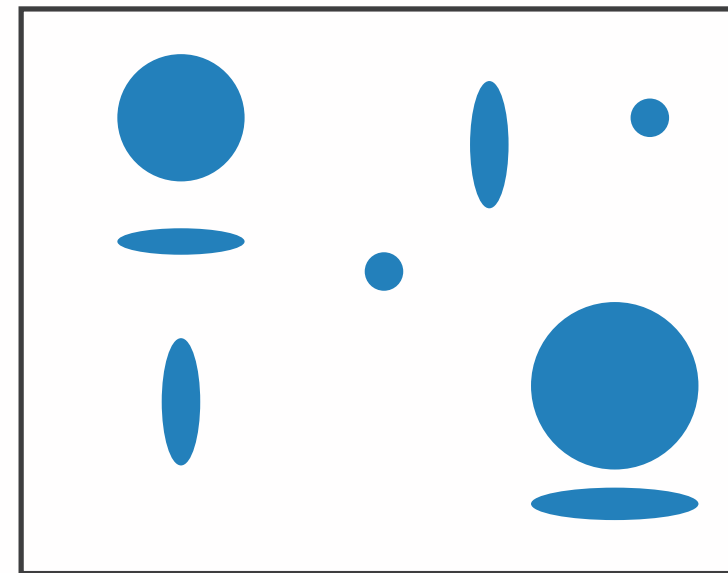
Size  
+ Hue (Color)



Some interference

2 groups each

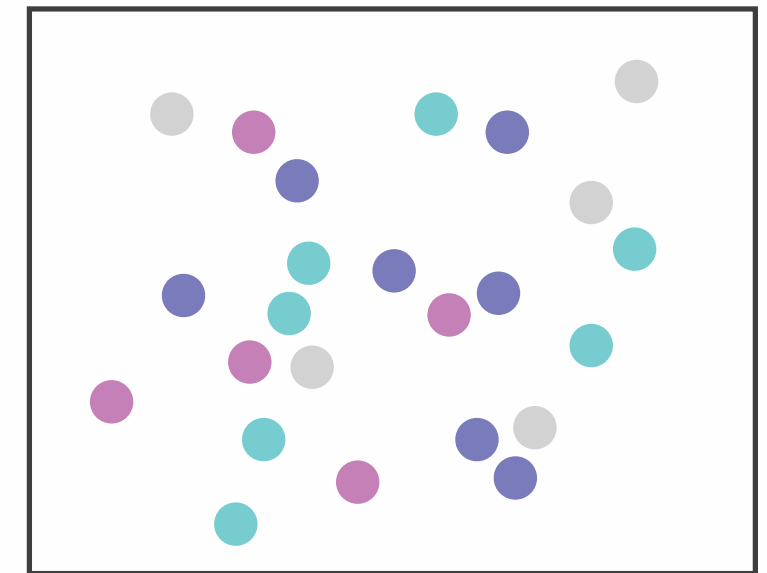
Width  
+ Height



Some/significant  
interference

3 groups total:  
integral area

Red  
+ Green



Major interference

4 groups total:  
integral hue

# Grouping

- containment
- connection

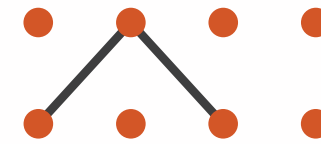
- proximity
  - same spatial region
- similarity
  - same values as other categorical channels

## Marks as Links

### ➔ Containment



### ➔ Connection



### ➔ Identity Channels: Categorical Attributes

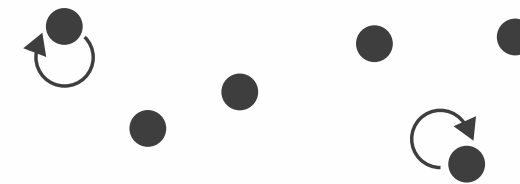
Spatial region



Color hue



Motion



Shape



# How to encode: Arrange position and region

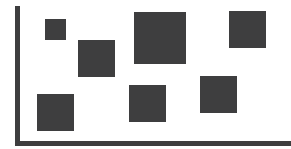
## Encode

### → Arrange

→ Express



→ Separate



→ Order



→ Align



→ Use



### → Map

from **categorical** and **ordered** attributes

→ Color

→ Hue



→ Saturation



→ Luminance



→ Size, Angle, Curvature, ...

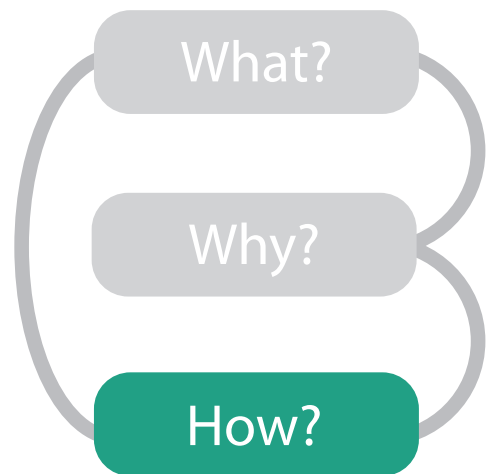
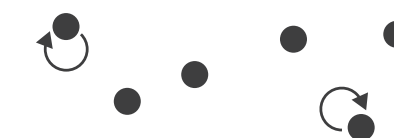


→ Shape



→ Motion

*Direction, Rate, Frequency, ...*



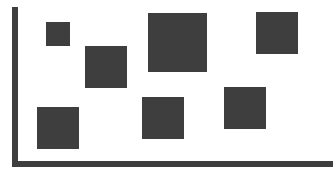
# Arrange tables

## ② Express Values

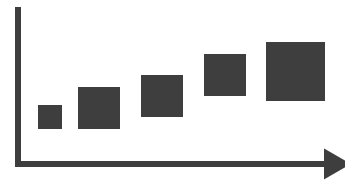


## ② Separate, Order, Align Regions

→ Separate



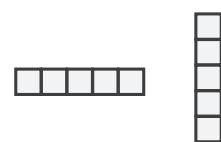
→ Order



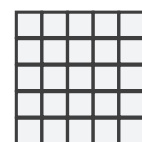
→ Align



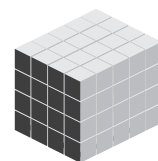
→ 1 Key  
*List*



→ 2 Keys  
*Matrix*



→ 3 Keys  
*Volume*

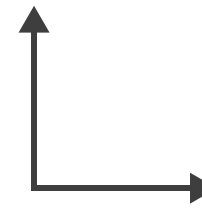


→ Many Keys  
*Recursive Subdivision*

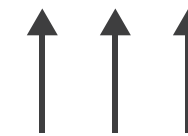


## ② Axis Orientation

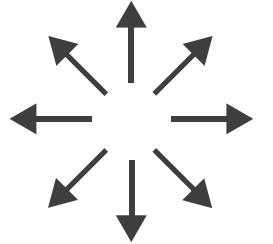
→ Rectilinear



→ Parallel

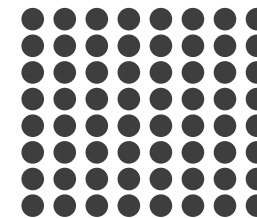


→ Radial



## ② Layout Density

→ Dense



→ Space-Filling



# Idioms: dot chart, line chart

- one key, one value

- data

- 2 quant attribs

- mark: points

- dot plot: + line connection marks between them

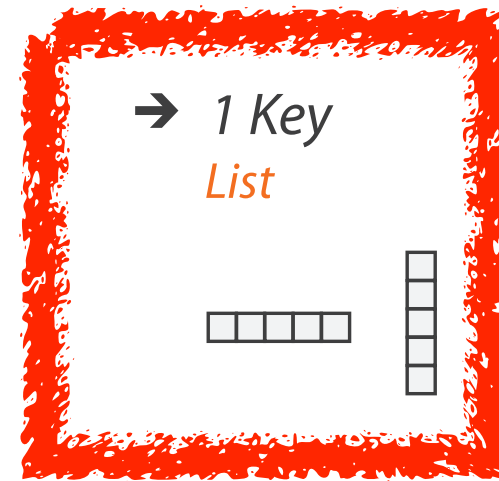
- channels

- aligned lengths to express quant value
- separated and ordered by key attrib into horizontal regions

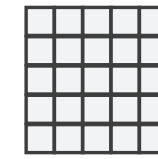
- task

- find trend

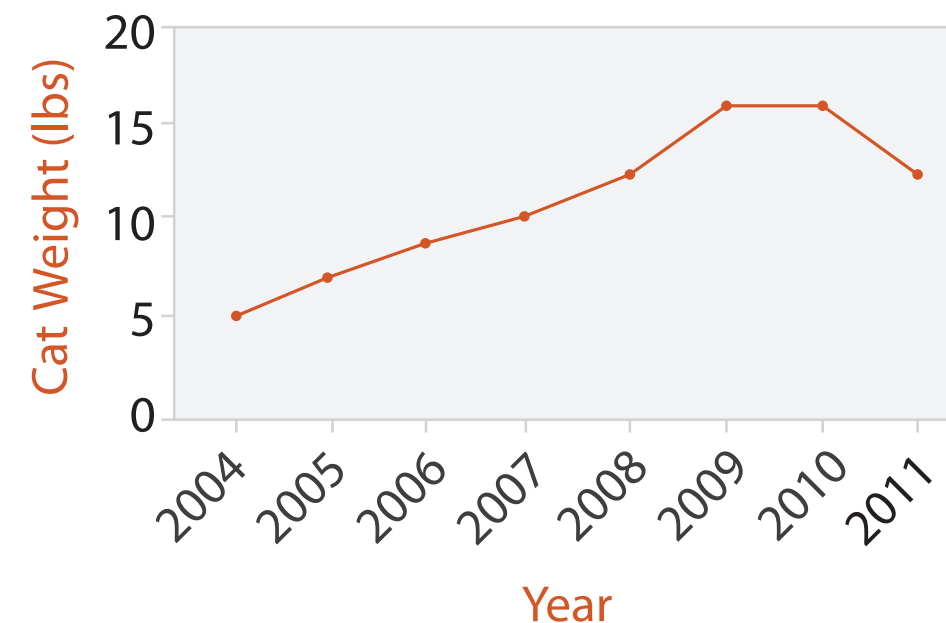
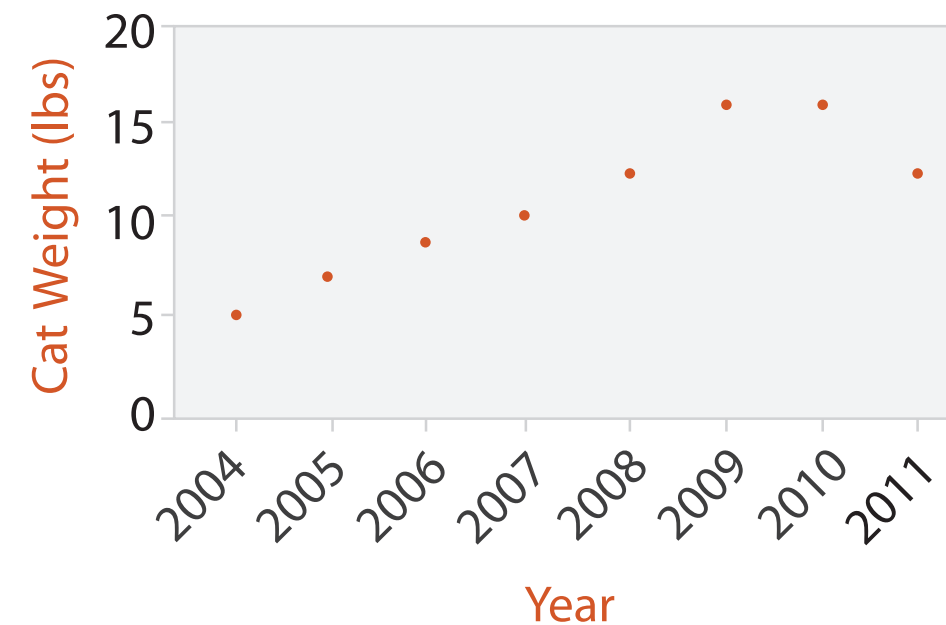
- connection marks emphasize ordering of items along key axis by explicitly showing relationship between one item and the next



→ 2 Keys  
*Matrix*

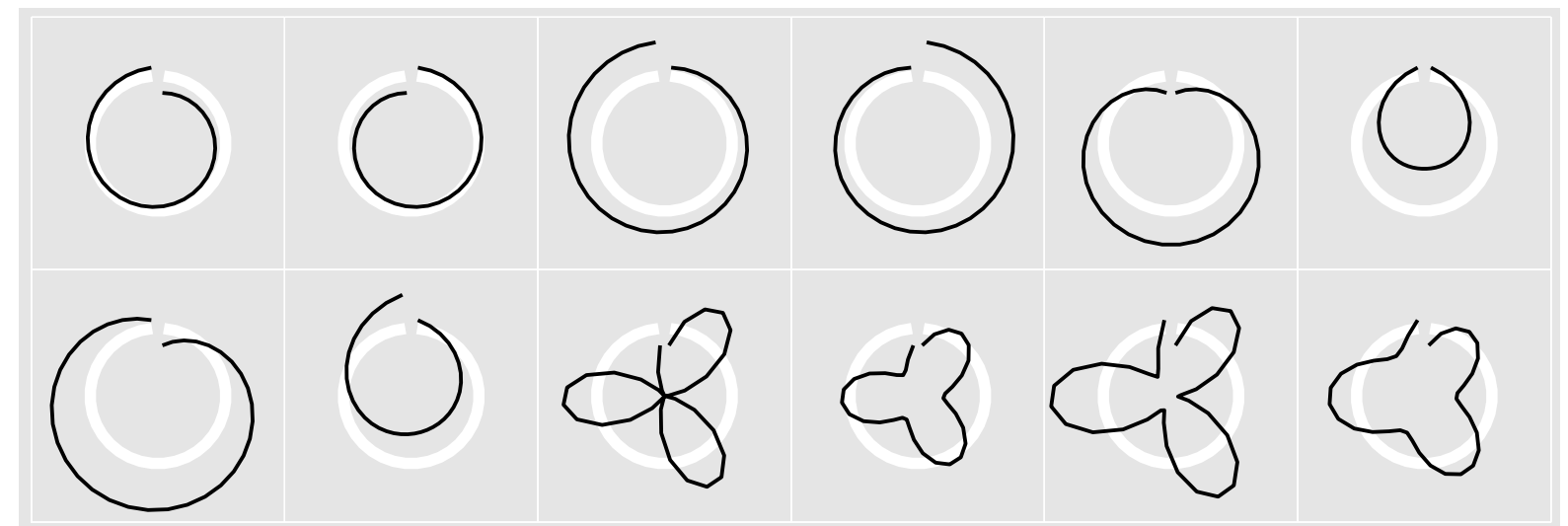
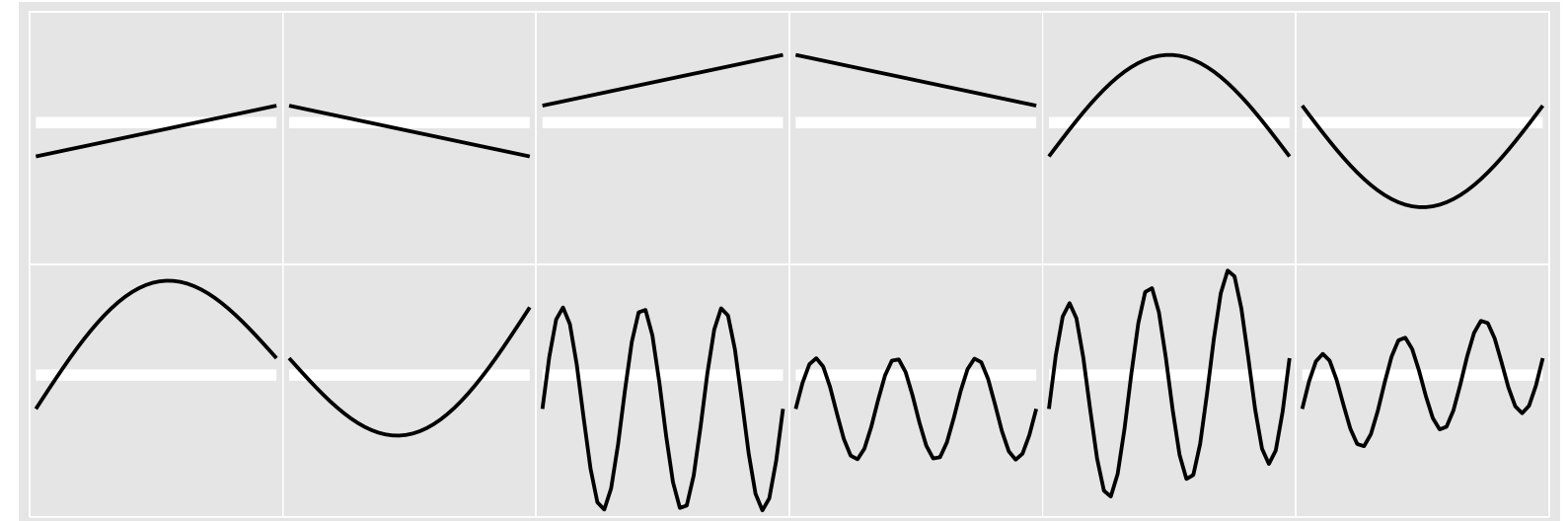


→ Many Keys  
*Recursive Subdivision*

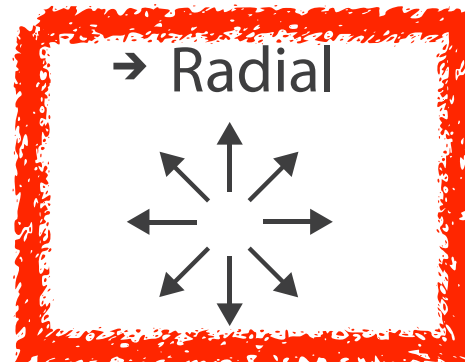
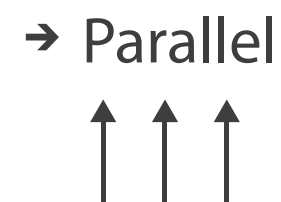
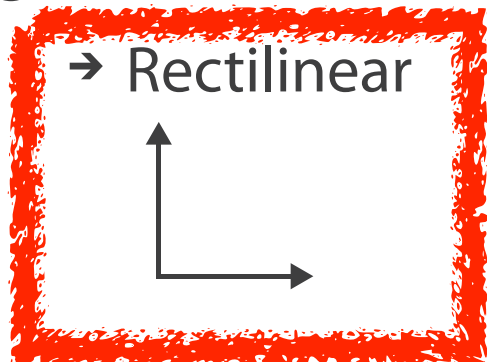


# Idiom: glyphmaps

- rectilinear good for linear vs nonlinear trends
- radial good for cyclic patterns



## ➔ Axis Orientation



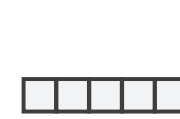
[Glyph-maps for Visually Exploring Temporal Patterns in Climate Data and Models. Wickham, Hofmann, Wickham, and Cook. *Environmetrics* 23:5 (2012), 382–393.]



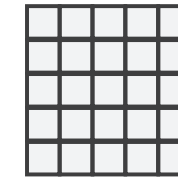
# Idiom: heatmap

- two keys, one value
  - data
    - 2 categ attribs (gene, experimental condition)
    - 1 quant attrib (expression levels)
  - marks: area
    - separate and align in 2D matrix
      - indexed by 2 categorical attributes
  - channels
    - color by quant attrib
      - (ordered diverging colormap)
  - task
    - find clusters, outliers
  - scalability
    - 1M items, 100s of categ levels, ~10 quant attrib levels

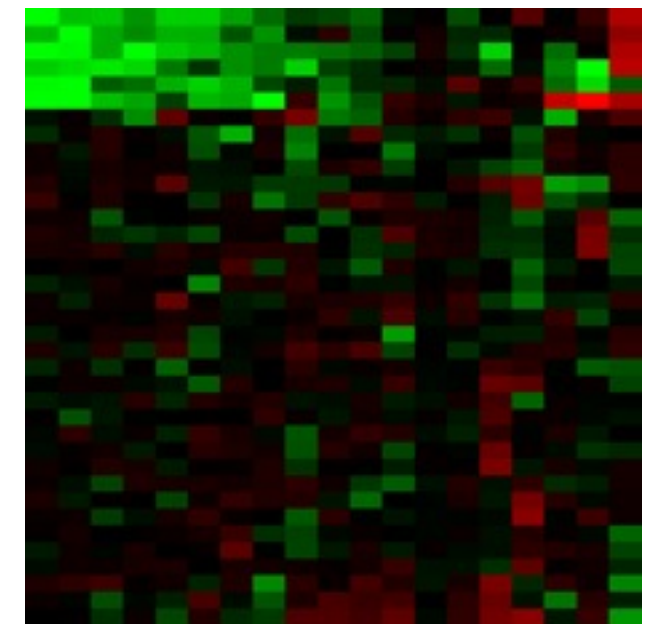
→ 1 Key  
*List*



→ 2 Keys  
*Matrix*

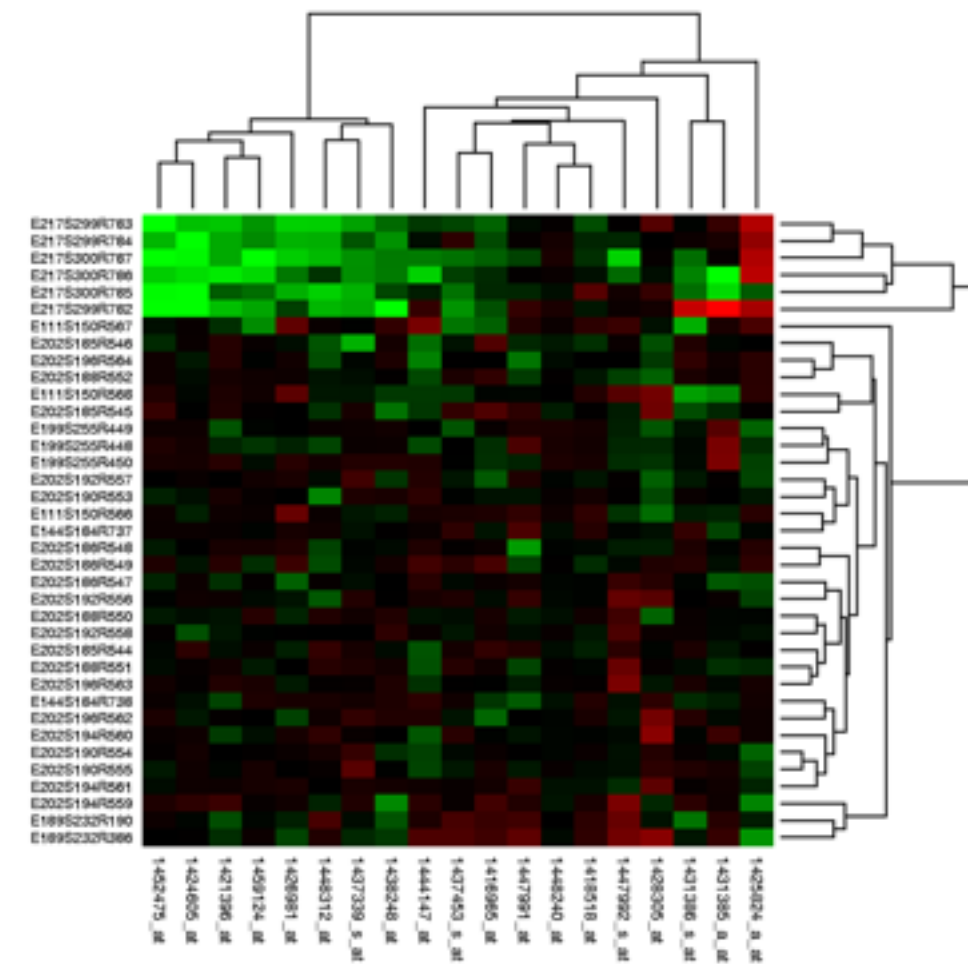


→ Many Keys  
*Recursive Subdivision*



# Idiom: cluster heatmap

- in addition
  - derived data
    - 2 cluster hierarchies
  - dendrogram
    - parent-child relationships in tree with connection line marks
    - leaves aligned so interior branch heights easy to compare
  - heatmap
    - marks (re-)ordered by cluster hierarchy traversal



# Arrange spatial data

## → Use Given

### → Geometry

→ *Geographic*

→ *Other Derived*

### → Spatial Fields

→ *Scalar Fields (one value per cell)*

→ *Isocontours*

→ *Direct Volume Rendering*

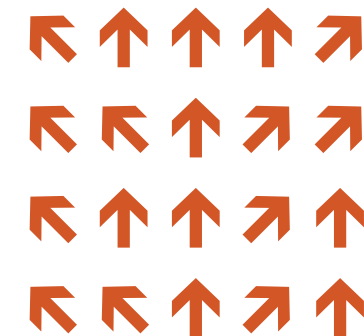
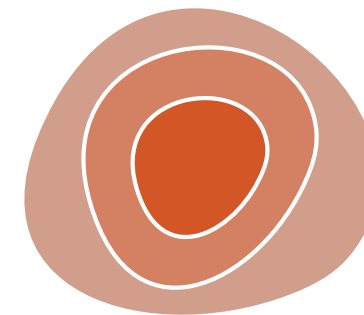
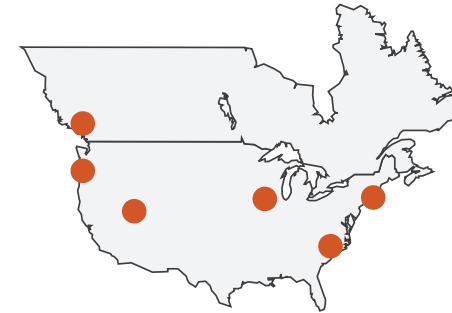
→ *Vector and Tensor Fields (many values per cell)*

→ *Flow Glyphs (local)*

→ *Geometric (sparse seeds)*

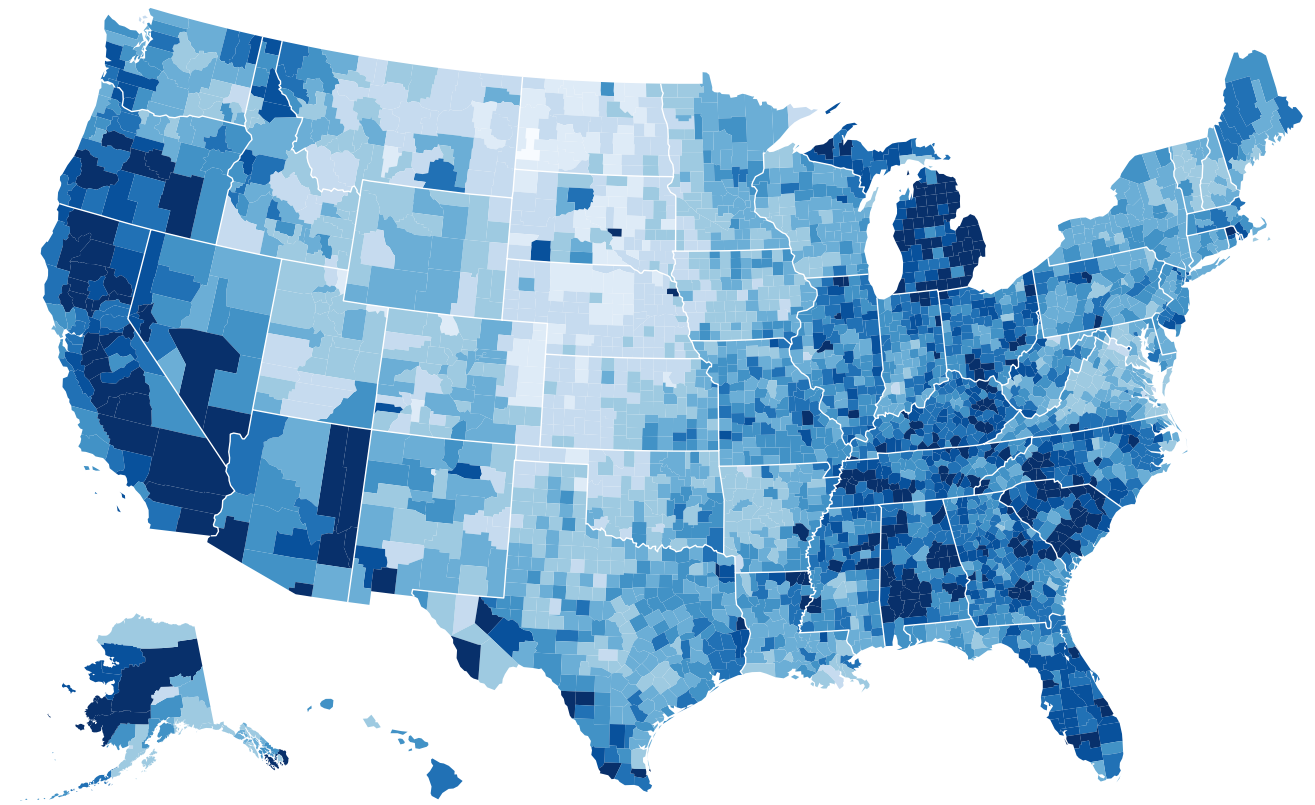
→ *Textures (dense seeds)*

→ *Features (globally derived)*



# Idiom: **choropleth map**

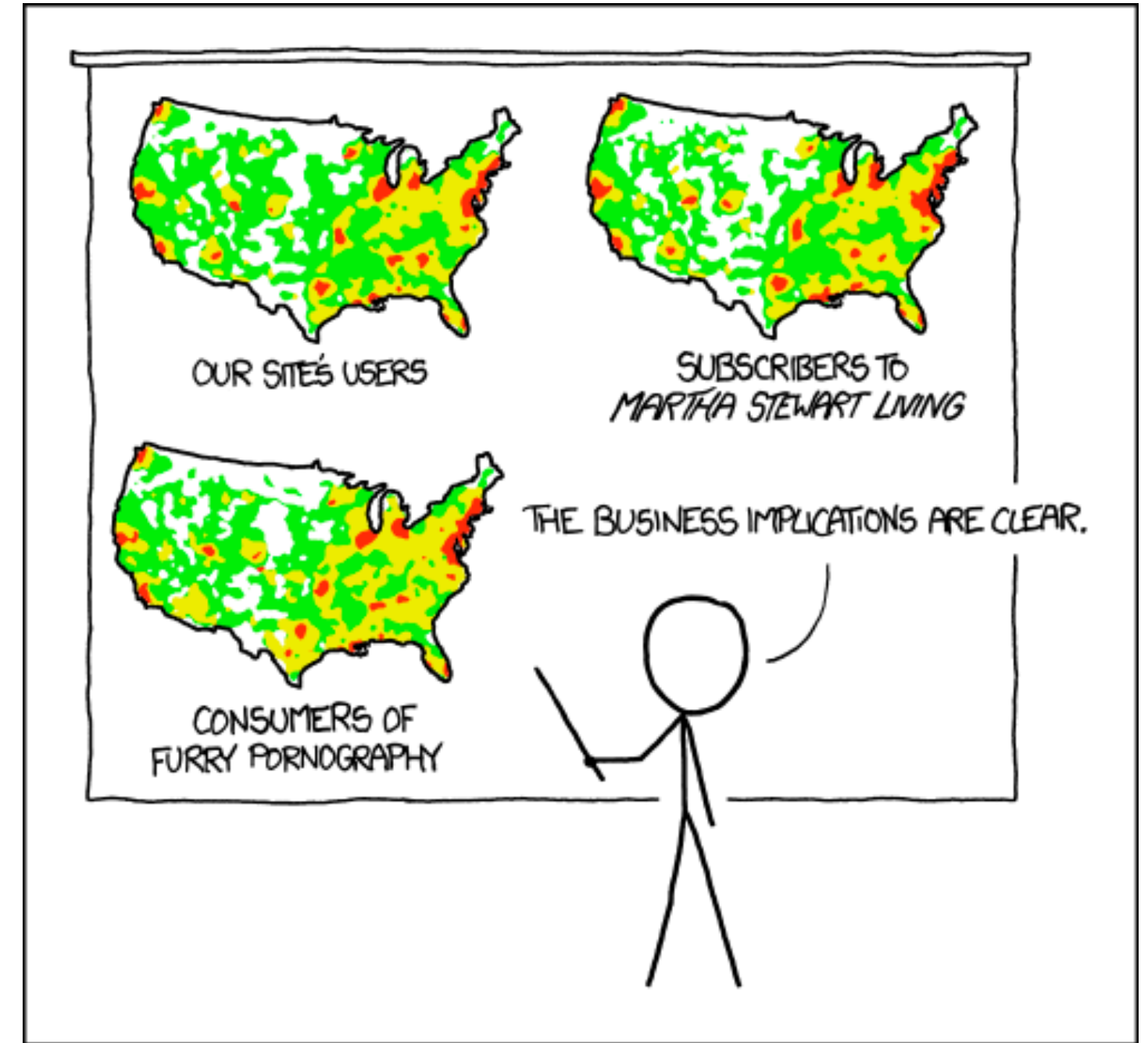
- **use** given spatial data
  - when central task is understanding spatial relationships
- data
  - geographic geometry
  - table with 1 quant attribute per region
- encoding
  - use given geometry for area mark boundaries
  - sequential segmented colormap



<http://bl.ocks.org/mbostock/4060606>

# Population maps trickiness

- beware!

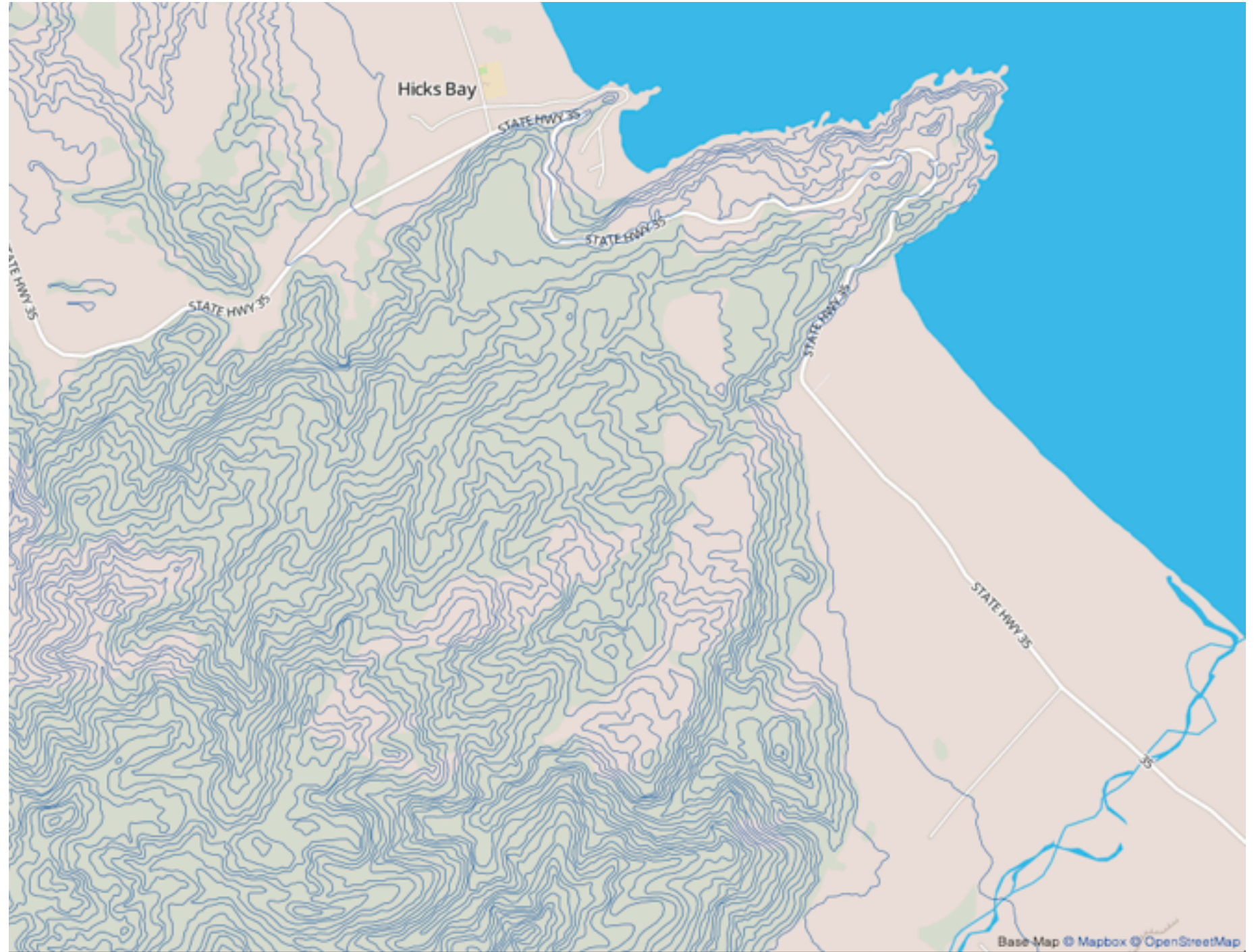


PET PEEVE #208:  
GEOGRAPHIC PROFILE MAPS WHICH ARE  
BASICALLY JUST POPULATION MAPS

[ <https://xkcd.com/1138> ]

# Idiom: topographic map

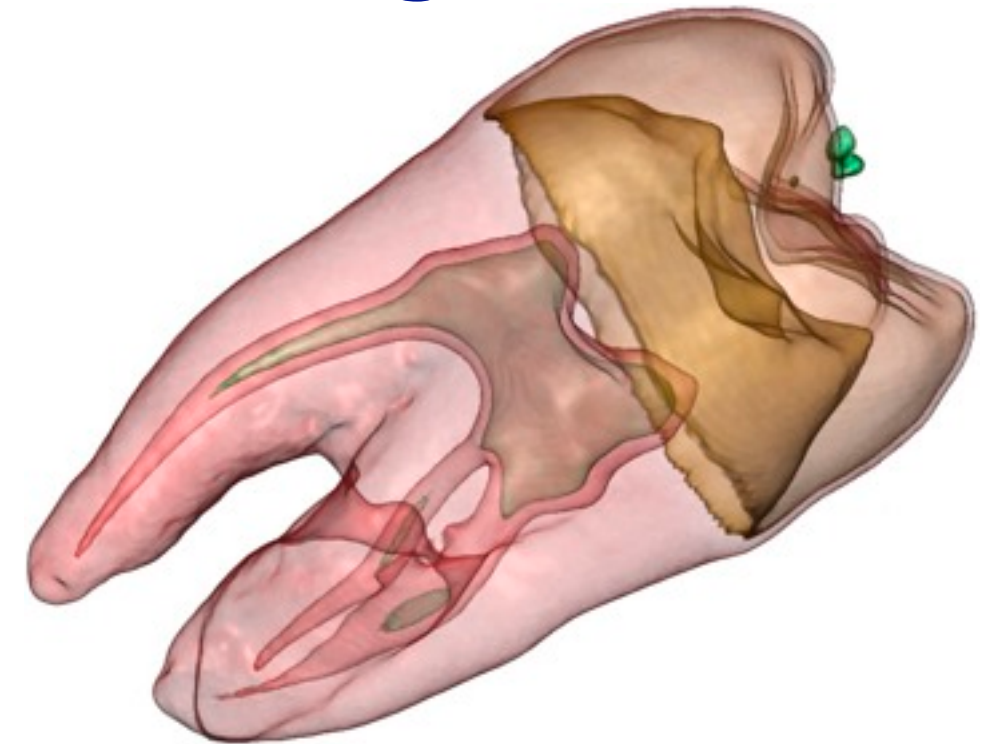
- data
  - geographic geometry
  - scalar spatial field
    - 1 quant attribute per grid cell
- derived data
  - isoline geometry
    - isocontours computed for specific levels of scalar values



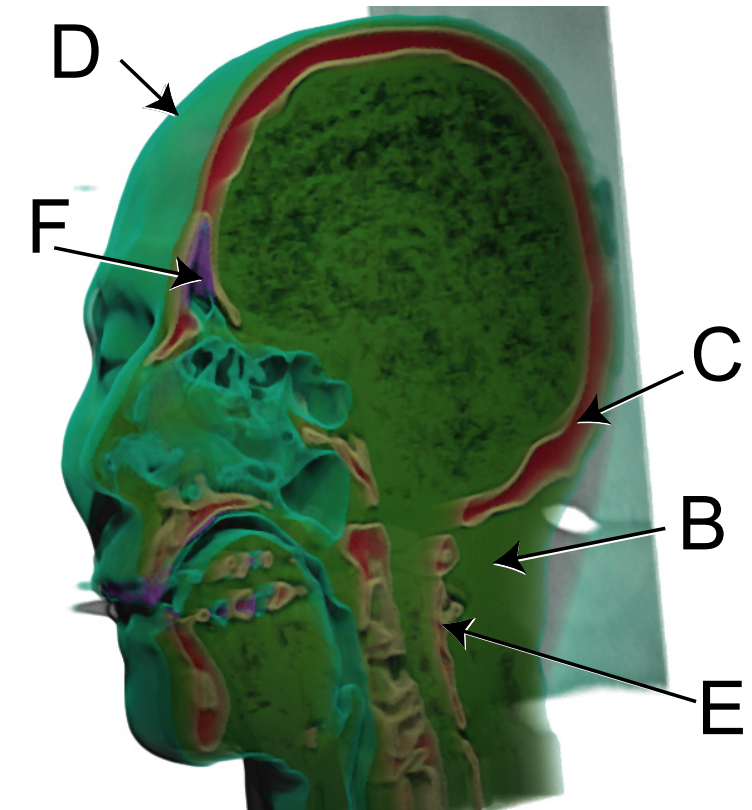
*Land Information New Zealand Data Service*

# Idioms: **isosurfaces**, **direct volume rendering**

- **data**
  - scalar spatial field
    - 1 quant attribute per grid cell
- **task**
  - shape understanding, spatial relationships
- **isosurface**
  - derived data: isocontours computed for specific levels of scalar values
- **direct volume rendering**
  - transfer function maps scalar values to color, opacity
    - no derived geometry



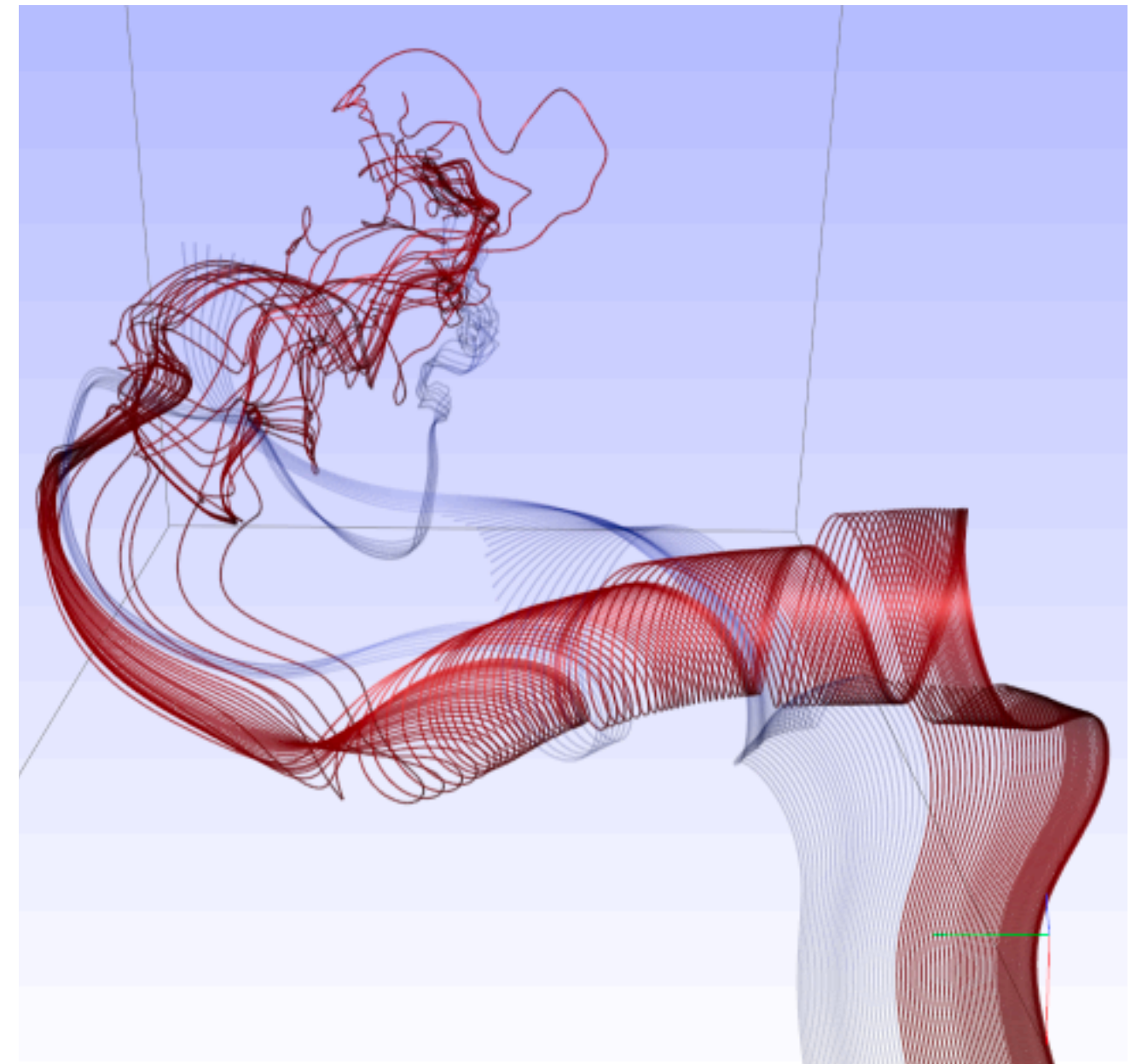
*[Interactive Volume Rendering Techniques. Kniss. Master's thesis, University of Utah Computer Science, 2002.]*



*[Multidimensional Transfer Functions for Volume Rendering. Kniss, Kindlmann, and Hansen. In The Visualization Handbook, edited by Charles Hansen and Christopher Johnson, pp. 189–210. Elsevier, 2005.]*

# Idiom: **similarity-clustered streamlines**

- data
  - 3D vector field
- derived data (from field)
  - streamlines: trajectory particle will follow
- derived data (per streamline)
  - curvature, torsion, tortuosity
  - signature: complex weighted combination
  - compute cluster hierarchy across all signatures
  - encode: color and opacity by cluster
- tasks
  - find features, query shape
- scalability
  - millions of samples, hundreds of streamlines



*[Similarity Measures for Enhancing Interactive Streamline Seeding. McLoughlin, Jones, Laramee, Malki, Masters, and Hansen. IEEE Trans. Visualization and Computer Graphics 19:8 (2013), 1342–1353.]*

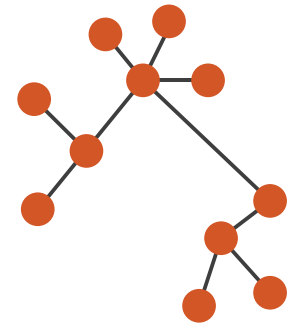


# Arrange networks and trees

## → Node–Link Diagrams Connection Marks

✓ NETWORKS

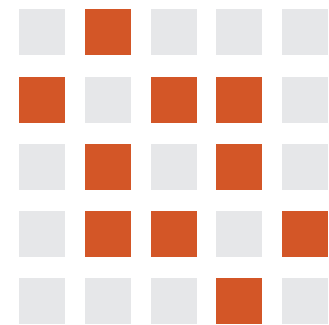
✓ TREES



## → Adjacency Matrix Derived Table

✓ NETWORKS

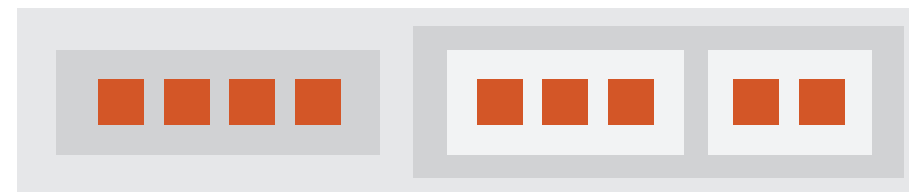
✓ TREES



## → Enclosure Containment Marks

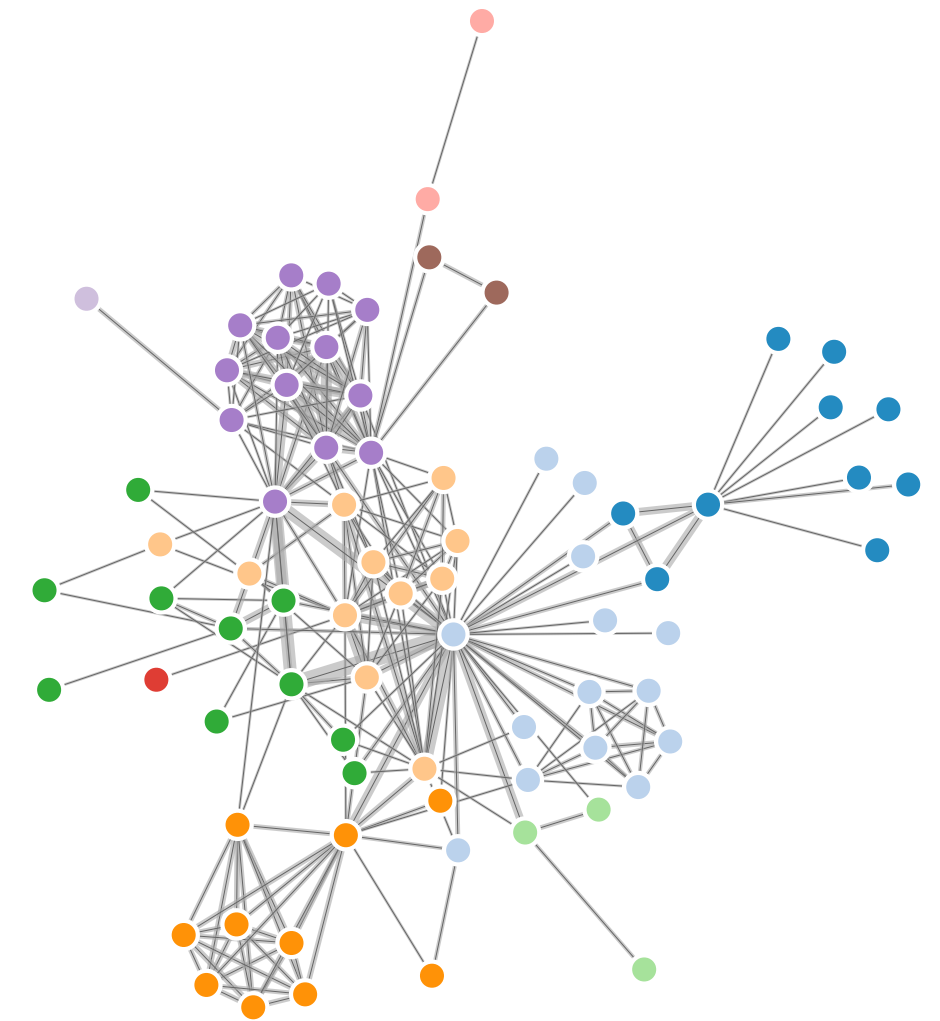
✗ NETWORKS

✓ TREES



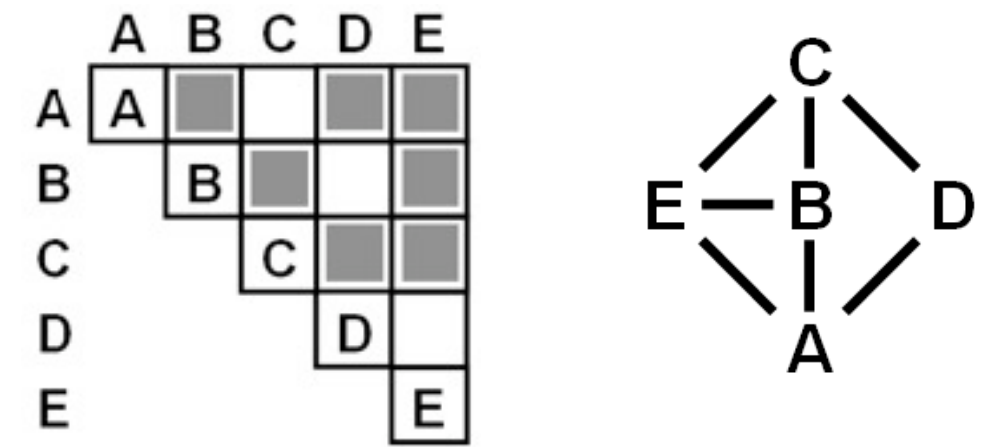
# Idiom: **force-directed placement**

- visual encoding
  - link connection marks, node point marks
- considerations
  - spatial position: no meaning directly encoded
    - left free to minimize crossings
  - proximity semantics?
    - sometimes meaningful
    - sometimes arbitrary, artifact of layout algorithm
    - tension with length
      - long edges more visually salient than short
- tasks
  - explore topology; locate paths, clusters
- scalability
  - node/edge density  $E < 4N$



# Idiom: adjacency matrix view

- data: network
  - transform into same data/encoding as heatmap
- derived data: table from network
  - 1 quant attrib
    - weighted edge between nodes
  - 2 categ attribs: node list x 2
- visual encoding
  - cell shows presence/absence of edge
- scalability
  - 1K nodes, 1M edges



[NodeTrix: a Hybrid Visualization of Social Networks. Henry, Fekete, and McGuffin. IEEE TVCG (Proc. InfoVis) 13(6):1302-1309, 2007.]

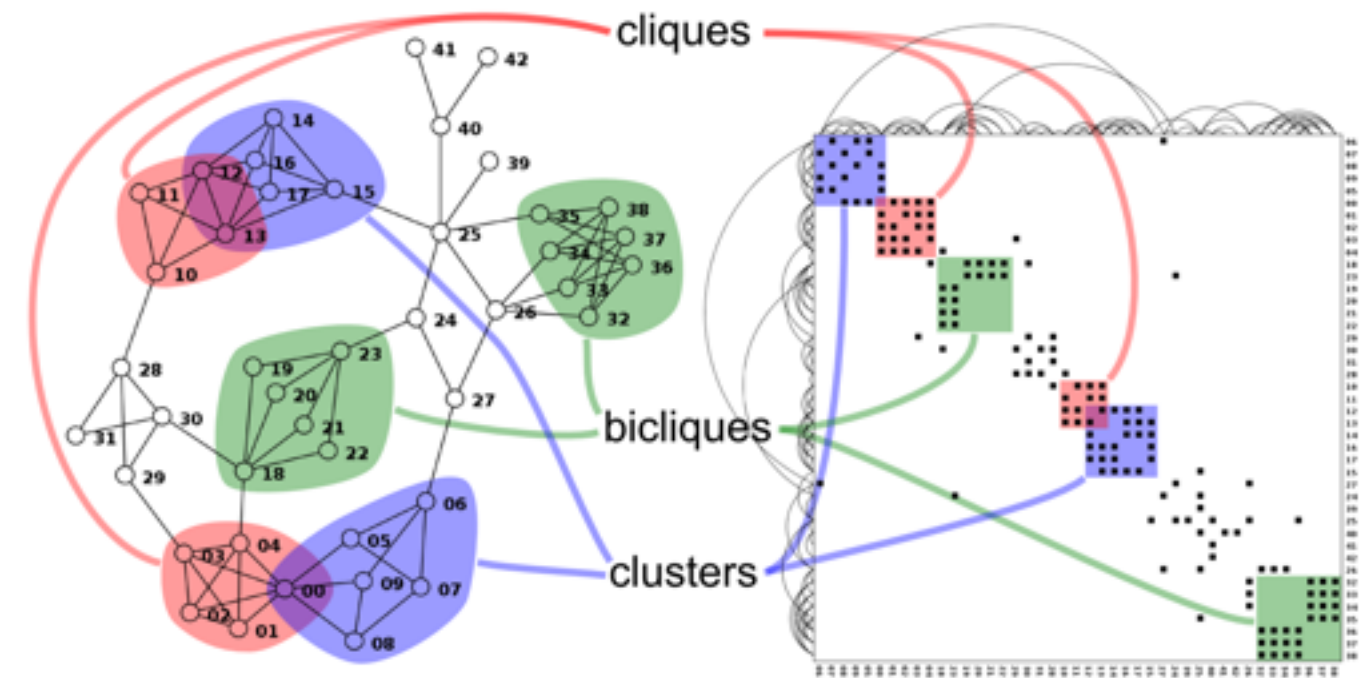


[Points of view: Networks. Gehlenborg and Wong. Nature Methods 9:115.]

# Connection vs. adjacency comparison

- adjacency matrix strengths
  - predictability, scalability, supports reordering
  - some topology tasks trainable
- node-link diagram strengths
  - topology understanding, path tracing
  - intuitive, no training needed
- empirical study
  - node-link best for small networks
  - matrix best for large networks
    - if tasks don't involve topological structure!

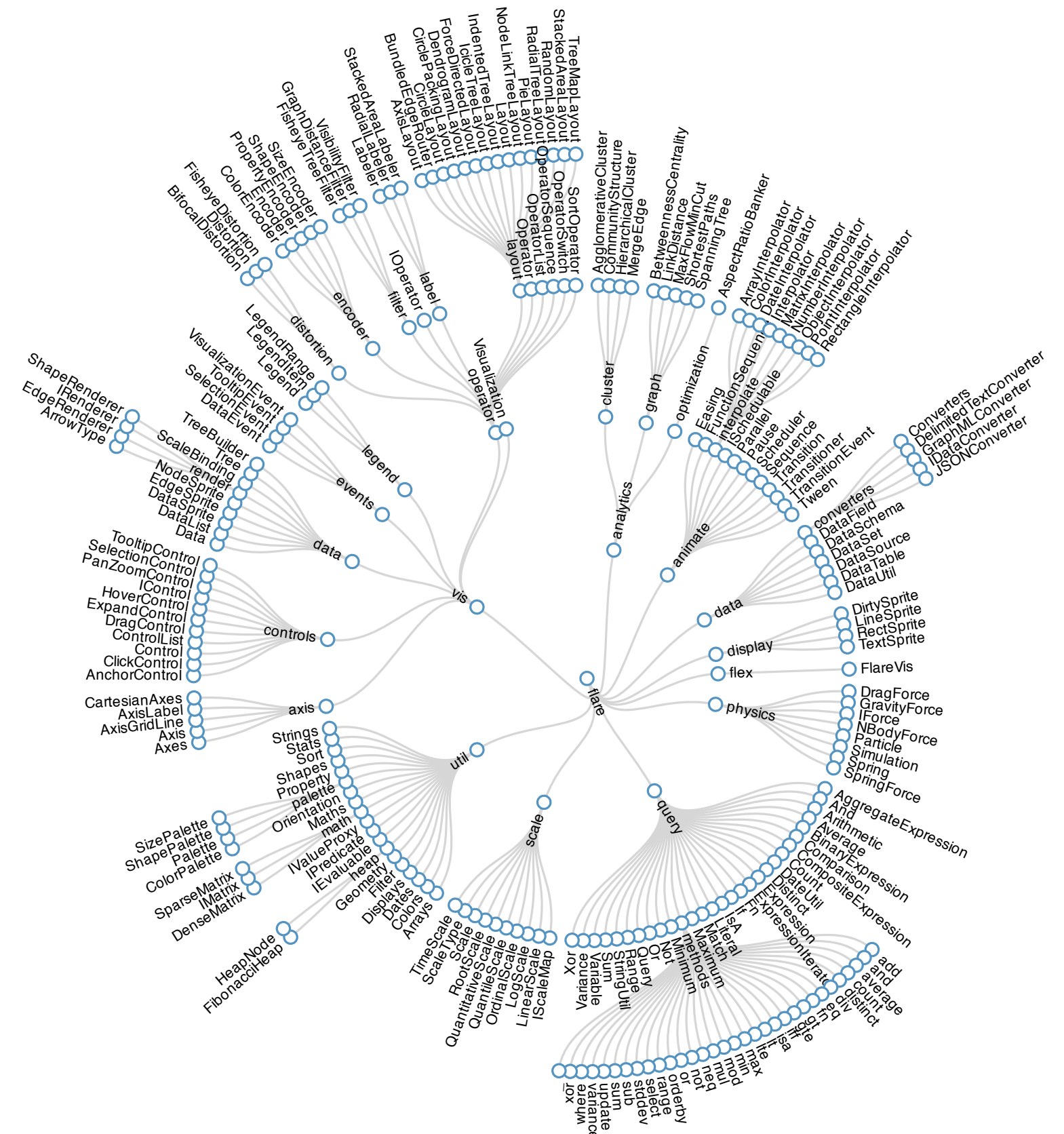
*[On the readability of graphs using node-link and matrix-based representations: a controlled experiment and statistical analysis. Ghoniem, Fekete, and Castagliola. Information Visualization 4:2 (2005), 114–135.]*



<http://www.michaelmcguffin.com/courses/vis/patternsInAdjacencyMatrix.png>

# Idiom: radial node-link tree

- data
  - tree
- encoding
  - link connection marks
  - point node marks
  - radial axis orientation
    - angular proximity: siblings
    - distance from center: depth in tree
- tasks
  - understanding topology, following paths
- scalability
  - 1K - 10K nodes



# Idiom: **treemap**

- **data**
  - tree
  - 1 quant attrib at leaf nodes
- **encoding**
  - area containment marks for hierarchical structure
  - rectilinear orientation
  - size encodes quant attrib
- **tasks**
  - query attribute at leaf nodes
- **scalability**
  - 1M leaf nodes

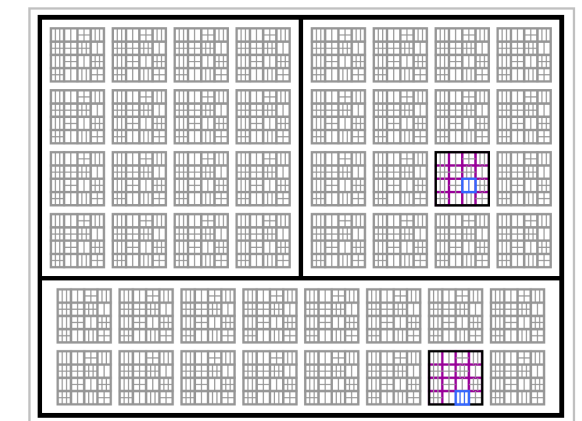
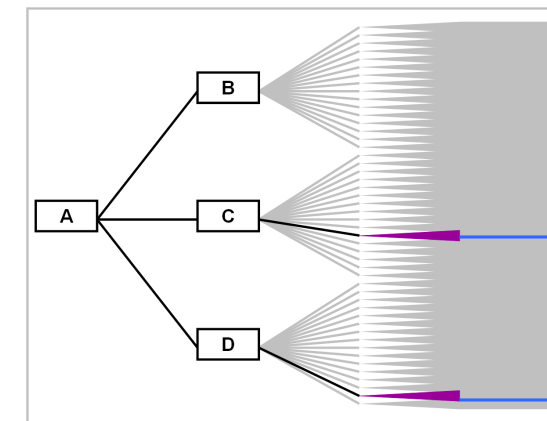
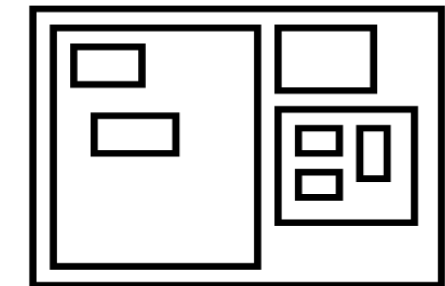
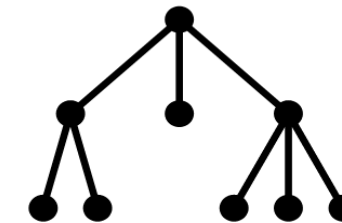
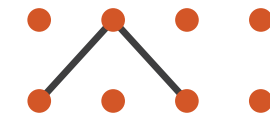
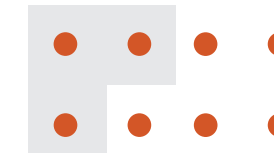


[http://tulip.labri.fr/Documentation/3\\_7/userHandbook/html/ch06.html](http://tulip.labri.fr/Documentation/3_7/userHandbook/html/ch06.html)

# Connection vs. containment comparison

- marks as links (vs. nodes)
  - common case in network drawing
  - 1D case: connection
    - ex: all node-link diagrams
    - emphasizes topology, path tracing
    - networks and trees
  - 2D case: containment
    - ex: all treemap variants
    - emphasizes attribute values at leaves (size coding)
    - only trees

➔ Containment    ➔ Connection



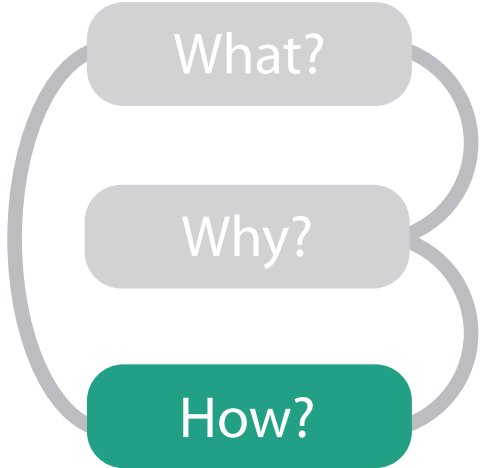
**Node-Link Diagram**

**Treemap**

[Elastic Hierarchies: Combining Treemaps and Node-Link Diagrams. Dong, McGuffin, and Chignell. Proc. InfoVis 2005, p. 57-64.]

# How to encode: Mapping color

## Encode



### → Arrange

→ Express



→ Separate



→ Order



→ Align



→ Use



### → Map

from **categorical** and **ordered** attributes

→ Color

→ Hue



→ Saturation



→ Luminance



→ Size, Angle, Curvature, ...



→ Shape



→ Motion

*Direction, Rate, Frequency, ...*



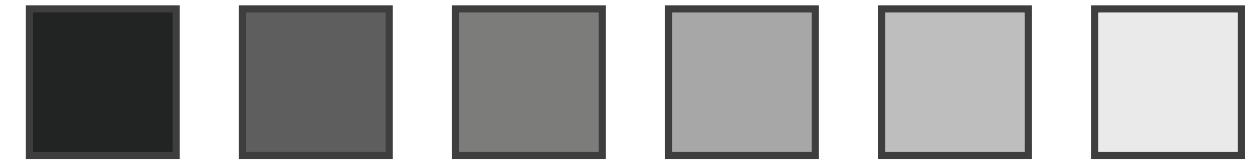


# Color: Luminance, saturation, hue

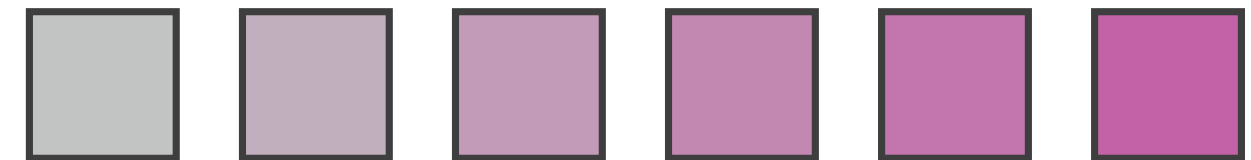
- 3 channels
  - identity for categorical
    - hue
  - magnitude for ordered
    - luminance
    - saturation
- RGB: poor for encoding
- HSL: better, but beware
  - lightness  $\neq$  luminance



Luminance



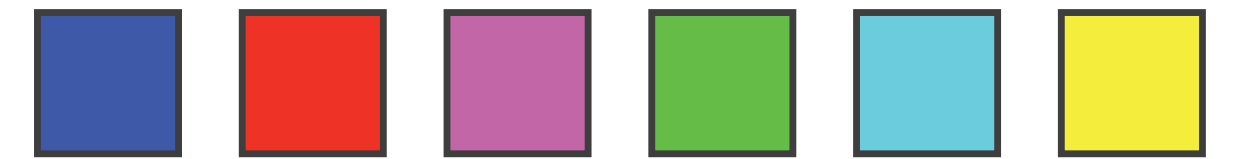
Saturation



Hue

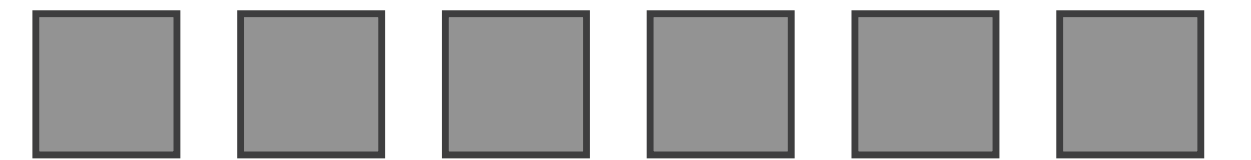


Corners of the RGB color cube

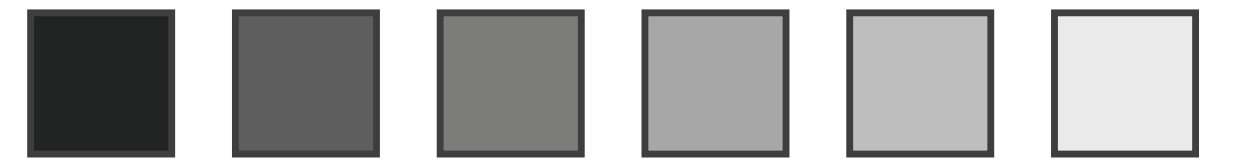


L from HLS

All the same

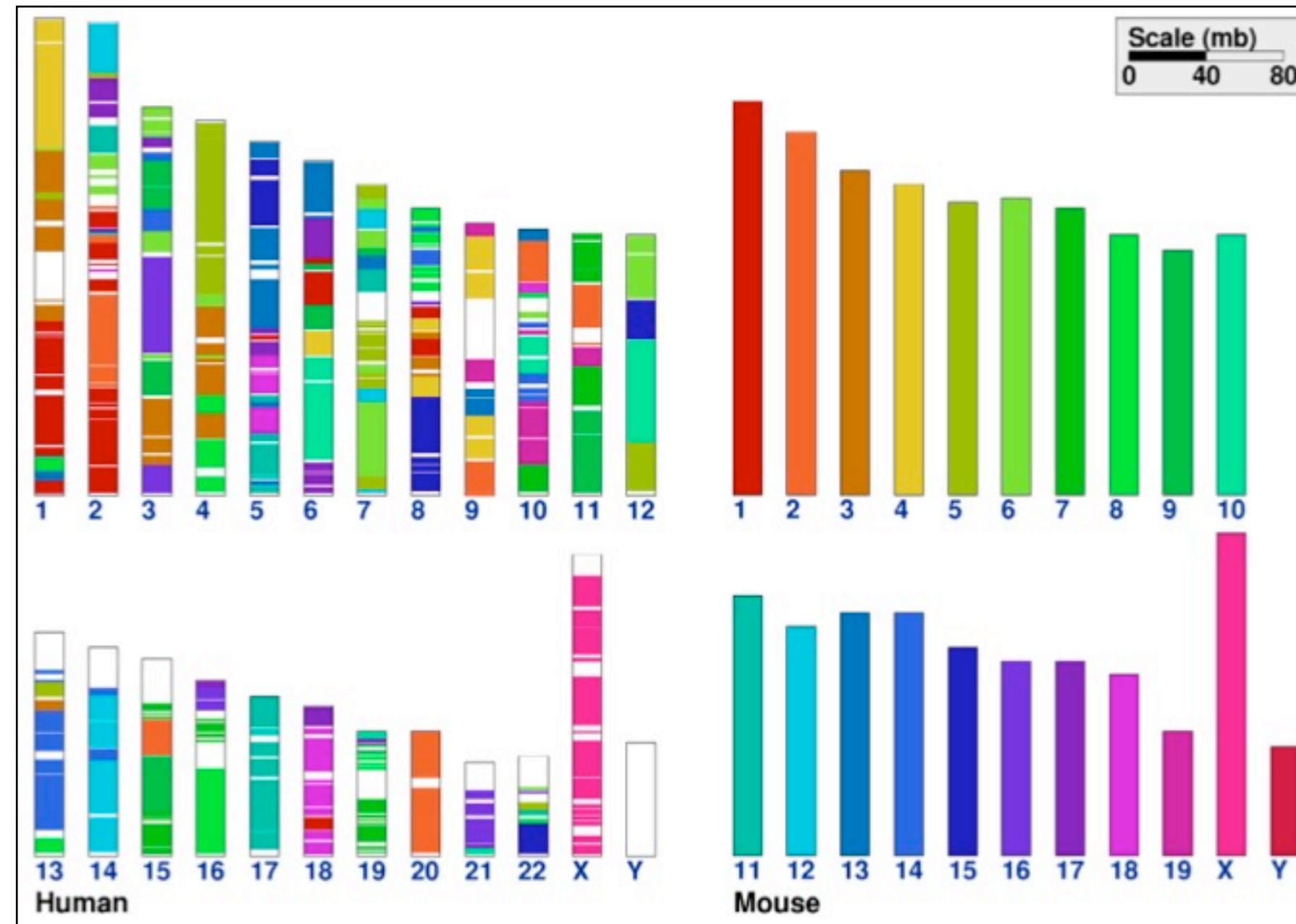


Luminance values



# Categorical color: Discriminability constraints

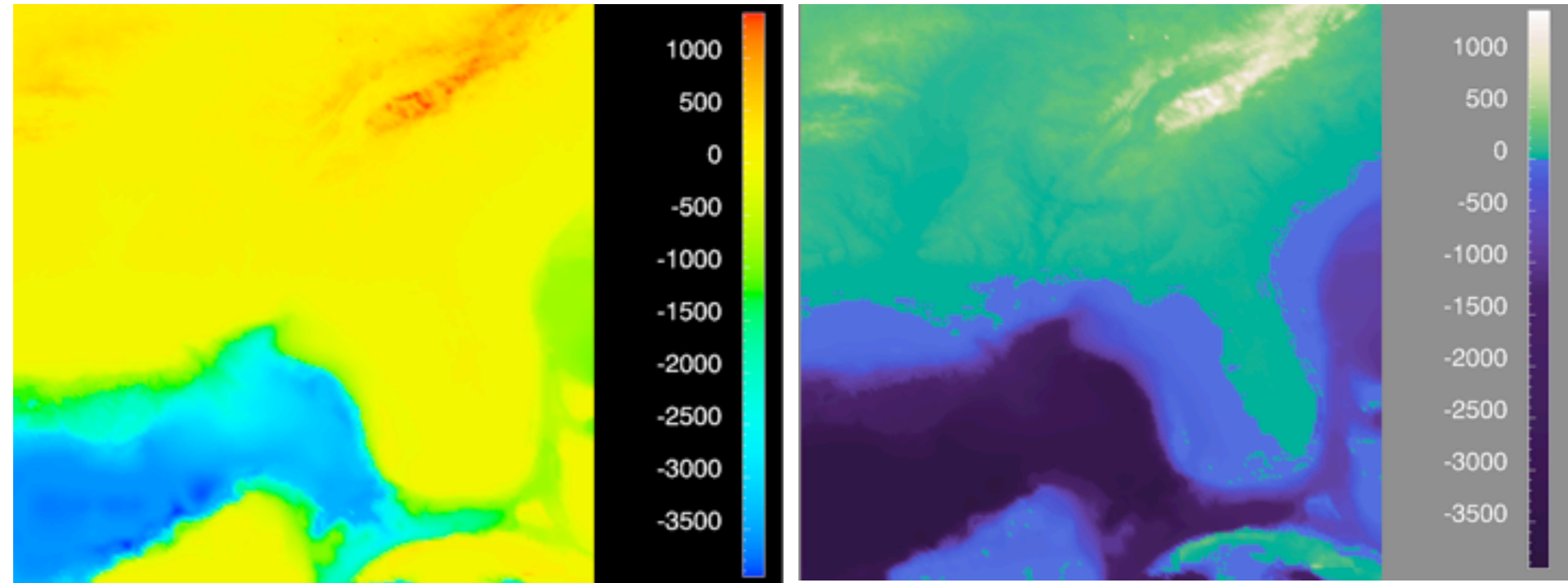
- noncontiguous small regions of color: only 6-12 bins



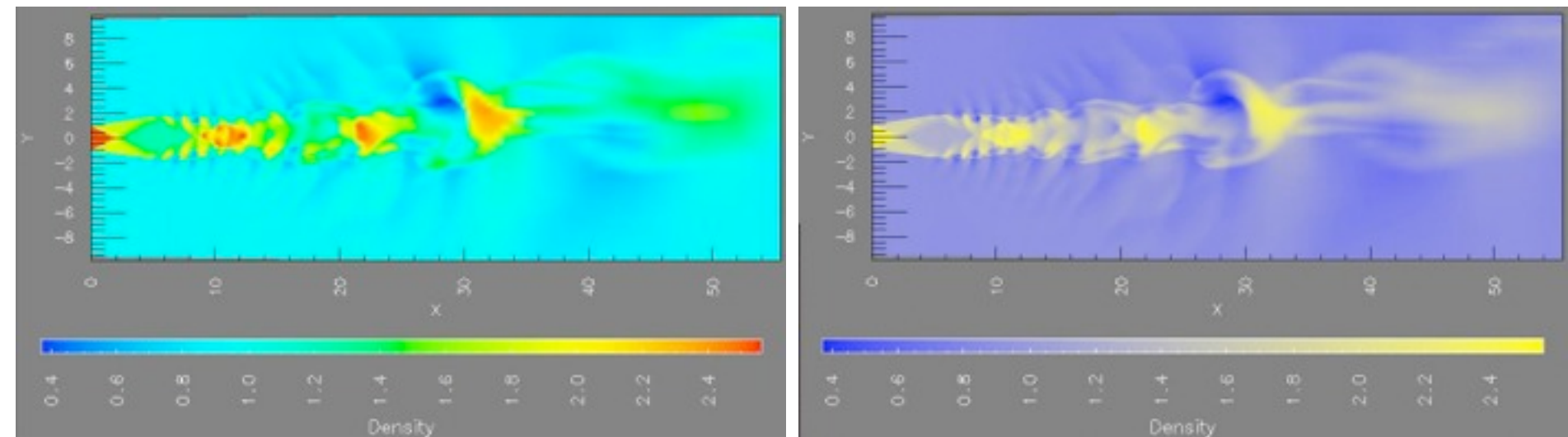
[Cinteny: flexible analysis and visualization of synteny and genome rearrangements in multiple organisms. Sinha and Meller. *BMC Bioinformatics*, 8:82, 2007.]

# Ordered color: Rainbow is poor default

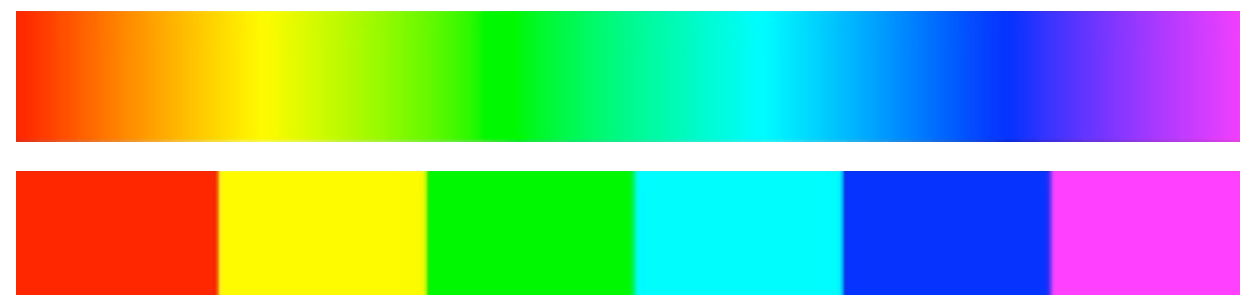
- problems
  - perceptually unordered
  - perceptually nonlinear
- benefits
  - fine-grained structure visible and nameable
- alternatives
  - fewer hues for large-scale structure
  - multiple hues with monotonically increasing luminance for fine-grained
  - segmented rainbows good for categorical, ok for binned



[Why Should Engineers Be Worried About Color? Treinish and Rogowitz 1998. <http://www.research.ibm.com/people/lloyd/color/color.HTM>]



[A Rule-based Tool for Assisting Colormap Selection. Bergman, Rogowitz, and Treinish. Proc. IEEE Visualization (Vis), pp. 118–125, 1995.]



[Transfer Functions in Direct Volume Rendering: Design, Interface, Interaction. Kindlmann. SIGGRAPH 2002 Course Notes]

# How?

## Encode

### → Arrange

→ Express



→ Order



→ Use



→ Separate



→ Align



### → Map

from **categorical** and **ordered** attributes

→ Color

→ Hue



→ Saturation



→ Luminance



→ Size, Angle, Curvature, ...



→ Shape



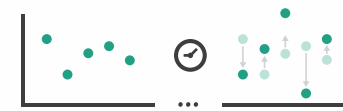
→ Motion

*Direction, Rate, Frequency, ...*

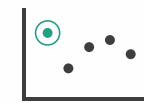


## Manipulate

### → Change



### → Select

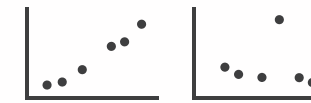


### → Navigate

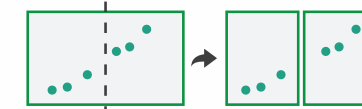


## Facet

### → Juxtapose



### → Partition



### → Superimpose



## Reduce

### → Filter



### → Aggregate



### → Embed



What?

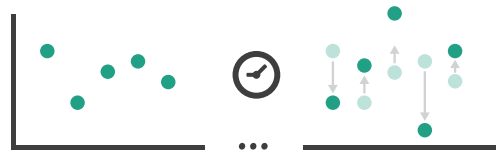
Why?

How?

# How to handle complexity: 3 more strategies + 1 previous

## Manipulate

### ➔ Change



### ➔ Select

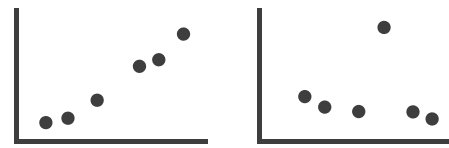


### ➔ Navigate

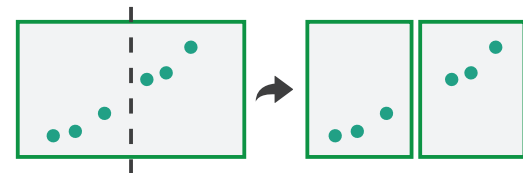


## Facet

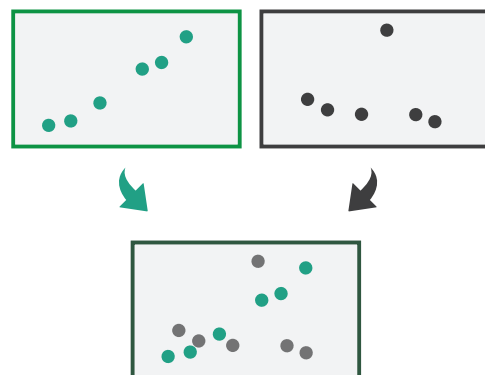
### ➔ Juxtapose



### ➔ Partition



### ➔ Superimpose



## Reduce

### ➔ Filter



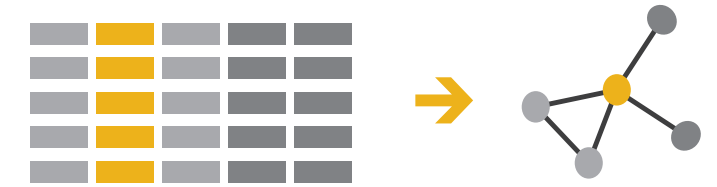
### ➔ Aggregate



### ➔ Embed



➔ *Derive*

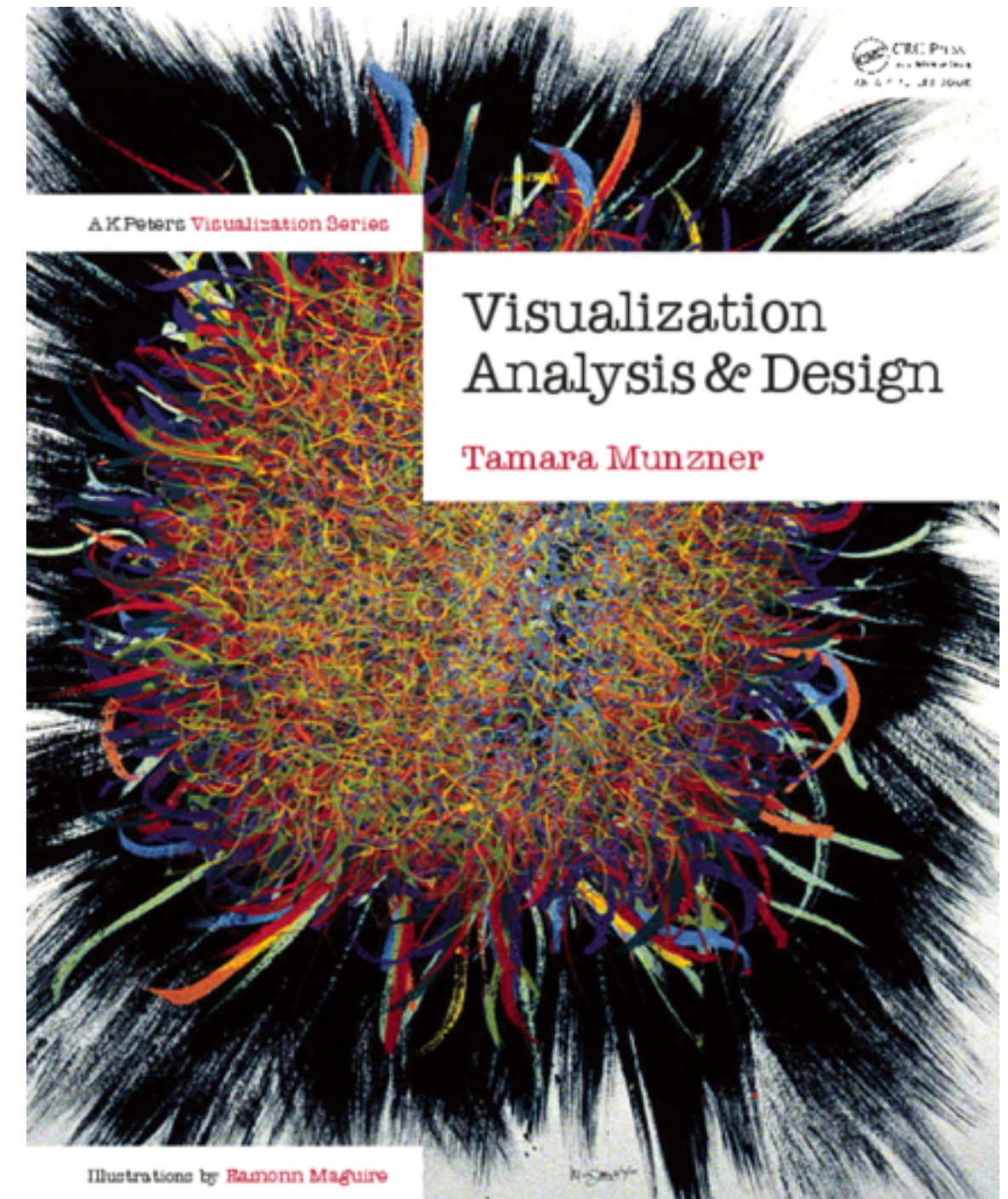


- change view over time
- facet across multiple views
- reduce items/attributes within single view
- derive new data to show within view

# More Information

[@tamaramunzner](https://twitter.com/tamaramunzner)

- book page (including tutorial lecture slides)  
<http://www.cs.ubc.ca/~tmm/vadbook>
  - illustrations: Eamonn Maguire
- grad class CPSC 547
  - usually taught fall term



Visualization Analysis and Design.  
Munzner. A K Peters Visualization Series, CRC Press, Visualization Series, 2014.